

Deadlocks

COMP 3361: Operating Systems I

Winter 2015

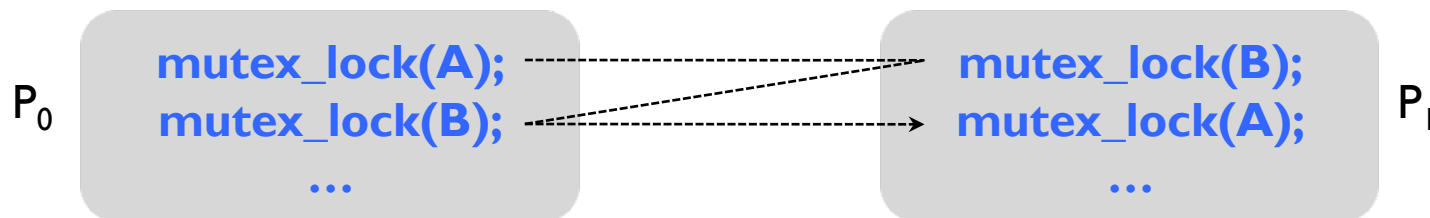
<http://www.cs.du.edu/3361>

- ▶ Resource types $R_1, R_2, \dots, R_m$
 - ▶ CPU cycles, I/O devices, mutex locks, semaphores, ...
 - ▶ resources cannot be preempted
- ▶ Each resource type R_i has E_i instances
- ▶ Each process utilizes a resource as follows
 - ▶ request
 - ▶ process waits if the request to acquire the resource is not granted immediately
 - ▶ use
 - ▶ process can operate on the resource
 - ▶ release
 - ▶ process no longer operates on the resource

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What is a Deadlock?

- ▶ A set of blocked processes
 - ▶ each holding a resource and
 - ▶ waiting to acquire a resource held by another process in the set
- ▶ Example
 - ▶ P₁ has CD drive, needs disk drive; P₂ has disk drive, needs CD drive
 - ▶ mutex A and B



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Conditions for Deadlocks

- ▶ Deadlock can arise if all of the following four conditions hold simultaneously
 - ▶ **mutual exclusion**: only one process at a time can use a resource
 - ▶ **hold and wait**: a process holding at least one resource can request additional resources (which may be held by other processes)
 - ▶ **no preemption**: a resource can be released only voluntarily
 - ▶ **circular wait**: there exists a set $\{P_0, P_1, \dots, P_n\}$ of waiting processes such that P_i is waiting for a resource that is held by $P_{(i+1)\%n}$

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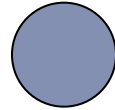
Resource-Allocation Graph

- ▶ A set of vertices V and edges E
- ▶ Vertices are partitioned into two types
 - ▶ $P = \{P_1, P_2, \dots, P_n\}$, the set consisting of all processes in the system
 - ▶ $R = \{R_1, R_2, \dots, R_m\}$, the set consisting of all resource types in the system
- ▶ An edge can be a
 - ▶ request edge: directed edge $P_i \rightarrow R_j$
 - ▶ P_i wants R_j
 - ▶ assignment edge: directed edge $R_j \rightarrow P_i$
 - ▶ R_j is with P_i

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Notations

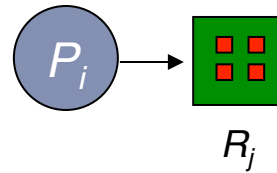
▶ Process



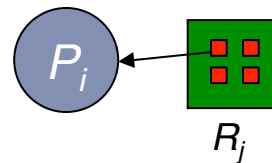
▶ Resource with 4 instances

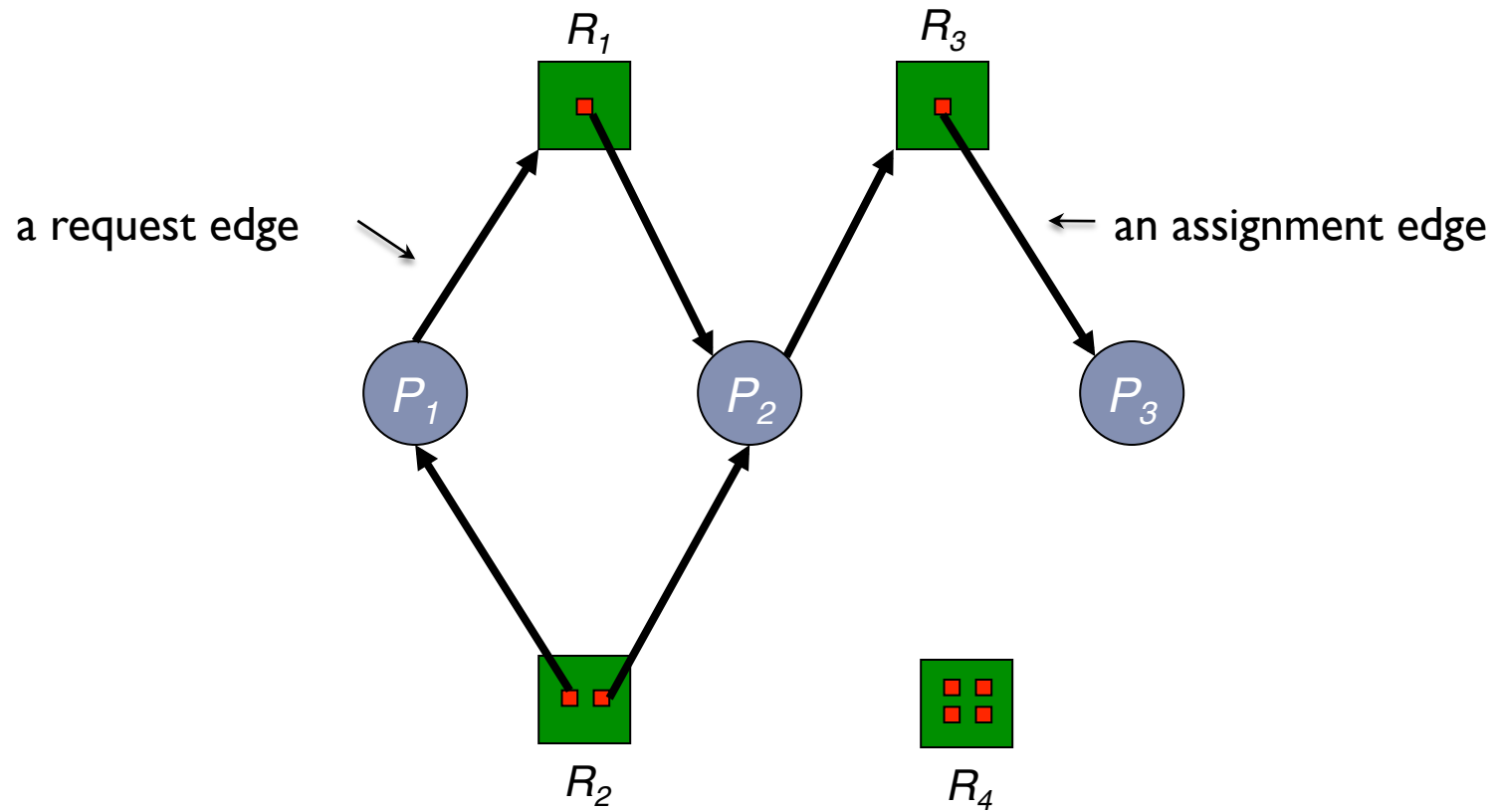


▶ P_i wants instance of R_j



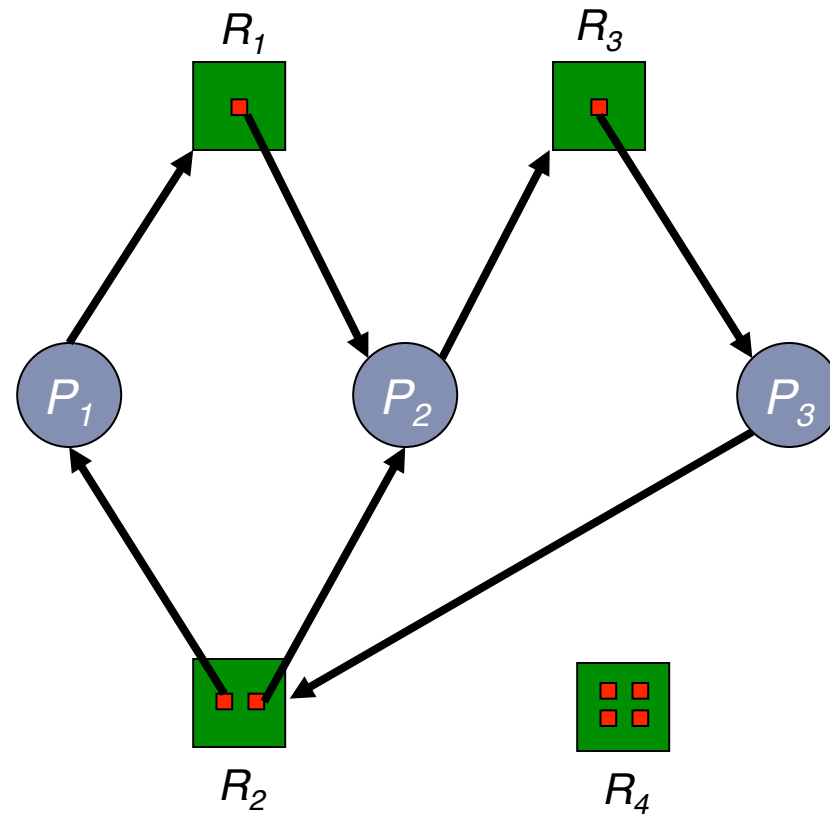
▶ P_i has an instance of R_j





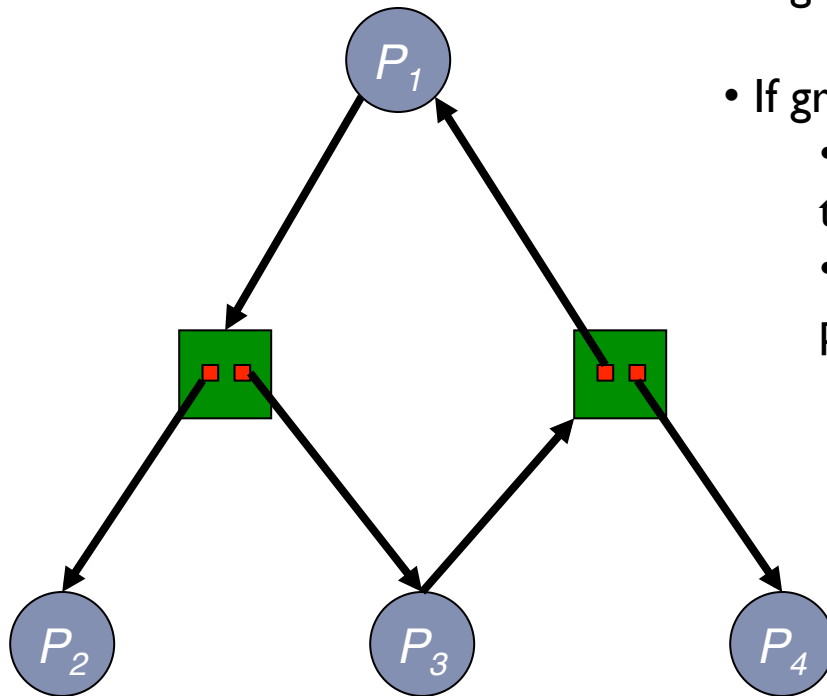
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Resource-Allocation Graph Deadlock



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A Cycle Is Not Necessarily a Deadlock



- If graph contains no cycles $\Rightarrow$ no deadlock
- If graph contains a cycle $\Rightarrow$
 - if only one instance per resource type, then deadlock
 - if several instances per resource type, possibility of deadlock

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Handling Deadlocks

- ▶ Ignore the problem and pretend that deadlocks never occur in the system
 - ▶ used by most operating systems, including UNIX
- ▶ Allow the system to enter a deadlock state and then recover
 - ▶ deadlock detection
- ▶ Ensure that the system will never enter a deadlock state
 - ▶ deadlock avoidance
 - ▶ deadlock prevention

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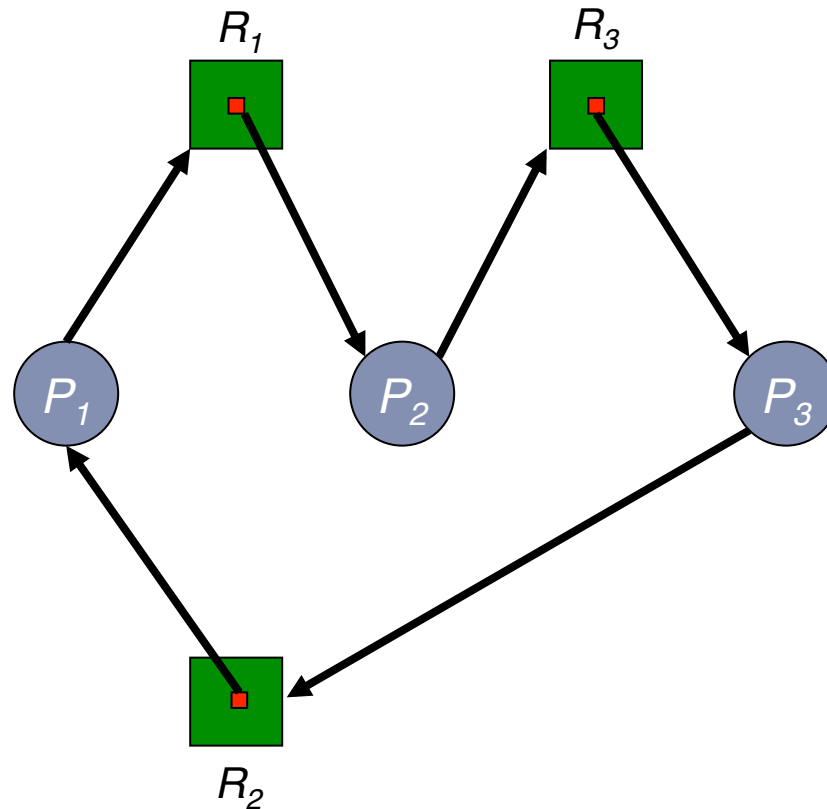
Deadlock Detection

- ▶ Allow system to enter deadlock state
- ▶ Examine the state of the system to determine if a deadlock has occurred
 - ▶ check whenever a new request has been granted
 - ▶ check periodically
 - ▶ check when CPU utilization drops below a threshold
- ▶ Have a policy on what to do if a deadlock has occurred
 - ▶ recovery scheme

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Single Instance Resources

- ▶ A deadlock exists in the system if and only if there is a cycle in the resource allocation graph



- ▶ Let n be number of processes and m be number of resource types
- ▶ **Existing:** vector of length m . If $\text{Existing}[j] = k$, there are k total instances of resource type R_j
- ▶ **Available:** vector of length m . If $\text{Available}[j] = k$, there are k instances of resource type R_j available
- ▶ **Allocation:** $n \times m$ matrix. If $\text{Allocation}[i,j] = k$, then P_i currently has k instances of R_j
- ▶ **Request:** $n \times m$ matrix. If $\text{Request}[i,j] = k$, then P_i wants k more instances of R_j

▶ **Request_i**

- ▶ refers to the vector of length m specifying the number of instances of each resource type that process P_i wants
- ▶ $\text{Request}_i = (\text{Request}[i,1], \dots, \text{Request}[i,m])$

▶ Similarly, **Allocation_i**

- ▶ Given two vectors $X = (x_1, \dots, x_m)$ and $Y = (y_1, \dots, y_m)$ we shall say
 - ▶ $X \leq Y$ if $x_i \leq y_i$ for all $i = 1, \dots, m$
 - ▶ $X \neq 0$ if $x_i \neq 0$ for all $i = 1, \dots, m$

Finish is a boolean vector of length n .

1. Let **Finish**[i] = **false** for all i with **Allocation** $_i \neq 0$; otherwise **Finish**[i] = **true**
2. Find an i such that
Finish[i] == **false** and **Request** $_i \leq$ **Available**
Goto 4 if no such i is found
3. **Available** = **Available** + **Allocation** $_i$
Finish[i] = **true**
Goto 2
4. If **Finish**[i] == **false** for some i , then process P_i is in a deadlocked state

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Detection Algorithm Example

5 processes; 3 resources types (A, B and C)
7 instances of A, 2 of B and 6 of C

	Allocation			Request			Available		
	A	B	C	A	B	C	A	B	C
P ₀	0	1	0	0	0	0	0	0	0
P ₁	2	0	0	2	0	2			
P ₂	3	0	3	0	0	0			
P ₃	2	1	1	1	0	0			
P ₄	0	0	2	0	0	2			

state at a certain point in time

Not Deadlocked:: sequence **<P₀, P₂, P₃, P₁, P₄>** will result in
Finish[i] = true for all **i**

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Detection Algorithm Example

	Allocation			Request			Available		
	A	B	C	A	B	C	A	B	C
P ₀	0	1	0	0	0	0	0	0	0
P ₁	2	0	0	2	0	2			
P ₂	3	0	3	0	0	1			
P ₃	2	1	1	1	0	0			
P ₄	0	0	2	0	0	2			

After P₀ executes, **Available = (0, 1, 0)**;
but after that no other process can progress

P₁, P₂, P₃ and P₄ are in a deadlocked state

- ▶ Abort all deadlocked processes
- ▶ Abort one process at a time until the deadlock cycle is eliminated
- ▶ Abort a process that is not deadlocked
- ▶ Preemption: take resource away from another process
- ▶ Rollback: return to some safe state (when resource was not needed) and resume process from that state
 - ▶ much easier to terminate and restart

- ▶ Requires that each process declare the maximum number of resources of each type that it may need
- ▶ Deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
 - ▶ resource-allocation state is the number of available and allocated resources, and the maximum demands of the processes

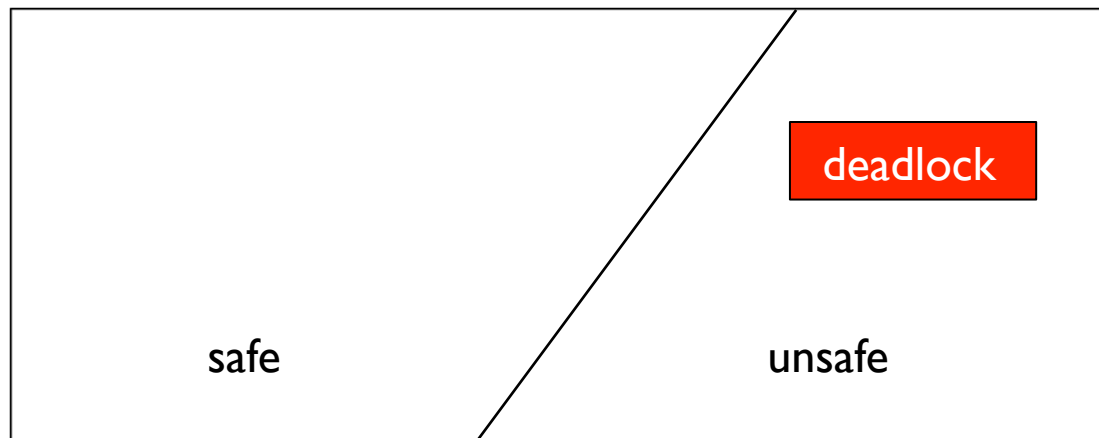
- ▶ When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- ▶ **Safe state**: there exists a safe sequence $\langle P_1, P_2, \dots, P_n \rangle$ of all processes in the system such that
 - ▶ for each P_i , the resources that P_i may still request can be satisfied by
 - ▶ currently available resources, and
 - ▶ resources held by all the P_j with $j < i$
- ▶ If no such sequence exists, then system is **unsafe**

- ▶ If P_i 's resource needs are not immediately met, then P_i can wait until all P_j have finished ($j < i$)
- ▶ When P_j is (are) finished, P_i can obtain needed resources, execute, return allocated resources, and terminate
- ▶ When P_i terminates, P_{i+1} may obtain its needed resources
- ▶ ...and so on

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Deadlocks and Safe State

- ▶ If a system is in safe state $\Rightarrow$ no deadlocks
- ▶ If a system is in unsafe state $\Rightarrow$ possibility of deadlock
- ▶ Avoidance $\Rightarrow$ ensure that a system will never enter an unsafe state



3 more available

	Maximum Need	Currently Has
P ₀	10	5
P ₁	4	2
P ₂	9	2

assume there are 12 instances of a resource

safe sequence: $\langle P_1, P_0, P_2 \rangle$

P₂ requests one more and is given

safe sequence: ??

unsafe state !!

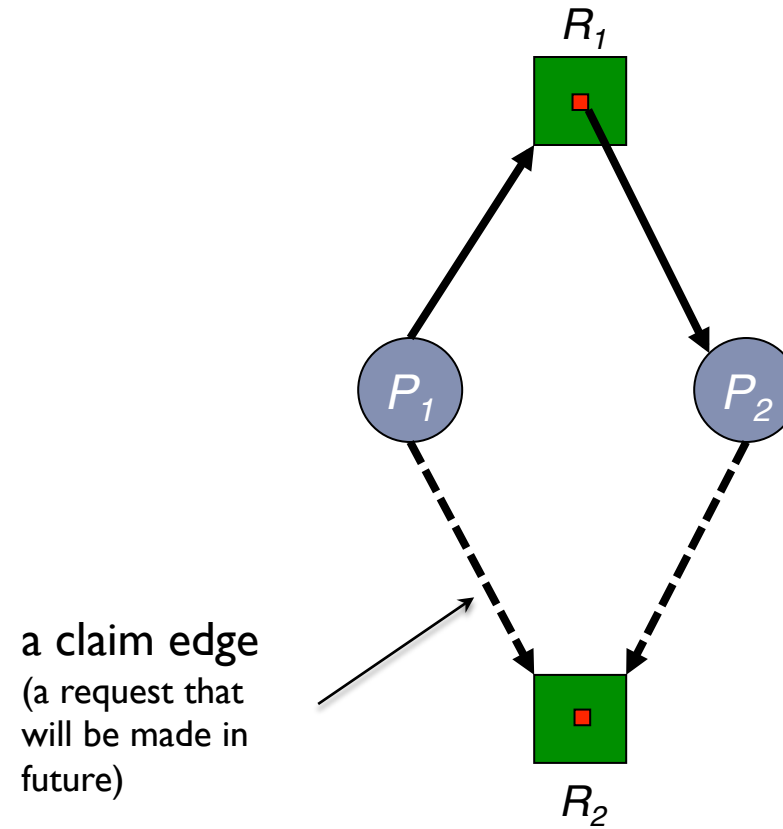
	Maximum Need	Currently Has
P ₀	10	5
P ₁	4	2
P ₂	9	3

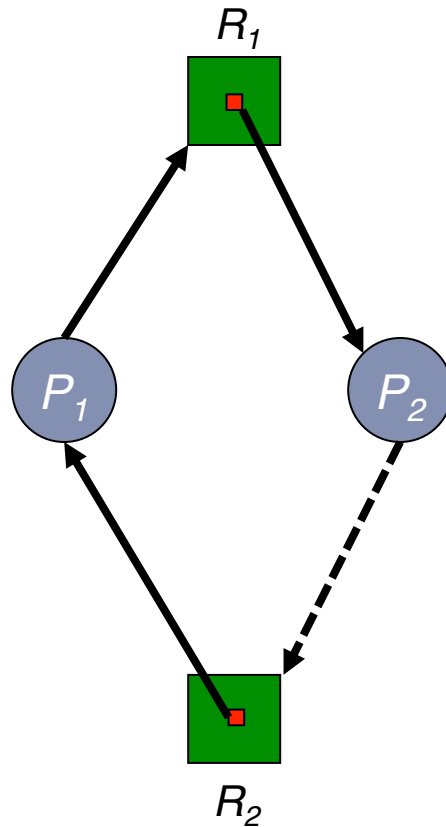
2 more available

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Avoidance Algorithms

- ▶ Single instance of a resource type
 - ▶ use a resource-allocation graph
- ▶ Multiple instances of a resource type
 - ▶ use the Banker's algorithm





P_1 requests R_2
Should it be given?

If R_2 is assigned to P_1 , neither $\langle P_1, P_2 \rangle$
nor $\langle P_2, P_1 \rangle$ is a safe sequence; there
is a cycle in the graph

So, NO!

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Banker's Algorithm

- ▶ Used when resources can have multiple instances
- ▶ Each process must declare the maximum number of instances of each resource type that it may need
- ▶ When a process requests a resource it may have to wait
- ▶ When a process gets all its resources, it must return them in a finite amount of time
- ▶ **Need:** $n \times m$ matrix. If $\text{Need}[i,j] = k$, then P_i needs k more instances of R_j to complete its task

- ▶ Determine if a system is in a safe state or not

Finish is a boolean vector of length n .

1. Let **Finish**[i] = **false** for all i
2. Find an i such that
Finish[i] == **false** and **Need** $_i \leq$ **Available**
Goto 4 if no such i is found
3. **Available** = **Available** + **Allocation** $_i$
Finish[i] = **true**
Goto 2
4. If **Finish**[i] == **true** for all i , then system is in a safe state

A request can be granted only if it ensures that the system will still be in a safe state

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Banker's Algorithm Example

5 processes; 3 resources types (A, B and C)
10 instances of A, 5 of B and 7 of C

Each process must
declare how much it will
ever need

	Allocation			Max			Available		
	A	B	C	A	B	C	A	B	C
P ₀	0	1	0	7	5	3	3	3	2
P ₁	2	0	0	3	2	2			
P ₂	3	0	2	9	0	2			
P ₃	2	1	1	2	2	2			
P ₄	0	0	2	4	3	3			

state at a certain point in time

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Banker's Algorithm Example

state is safe; $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ is a safe-sequence

	Allocation			Max			Available			Need		
	A	B	C	A	B	C	A	B	C	A	B	C
P ₀	0	1	0	7	5	3	3	3	2	7	4	3
P ₁	2	0	0	3	2	2				1	2	2
P ₂	3	0	2	9	0	2				6	0	0
P ₃	2	1	1	2	2	2				0	1	1
P ₄	0	0	2	4	3	3				4	3	1

- ▶ Assume allocation is done:

	Allocation			Max			Available			Need		
	A	B	C	A	B	C	A	B	C	A	B	C
P ₀	0	1	0	7	5	3	2	3	0	7	4	3
P ₁	3	0	2	3	2	2				0	2	0
P ₂	3	0	2	9	0	2				6	0	0
P ₃	2	1	1	2	2	2				0	1	1
P ₄	0	0	2	4	3	3				4	3	1

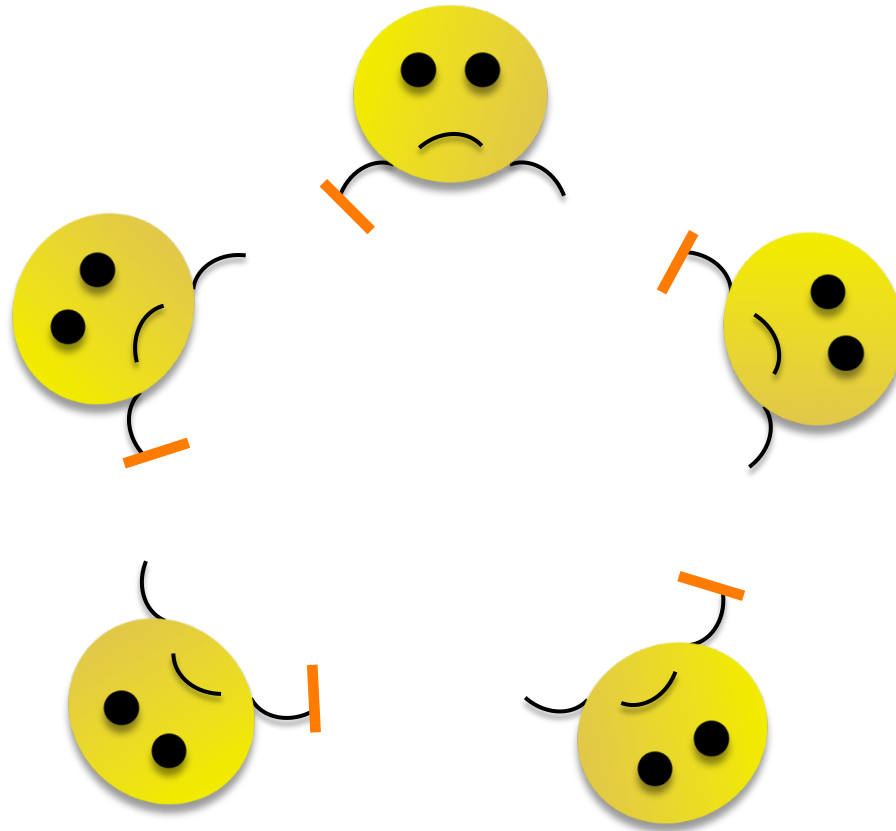
- ▶ Still a safe state: <P₁, P₃, P₄, P₀, P₂> is the safe-sequence
 - ▶ P₁ is given the resources it wants

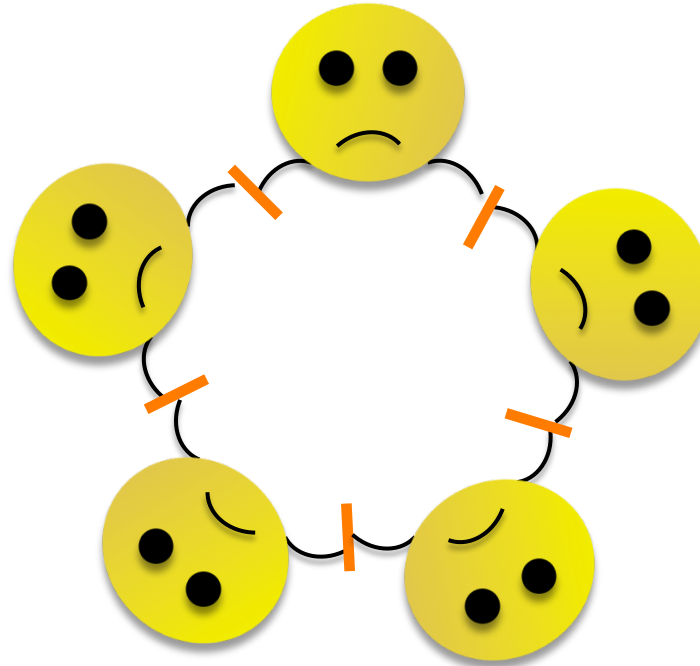
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Example: Can We Do These?

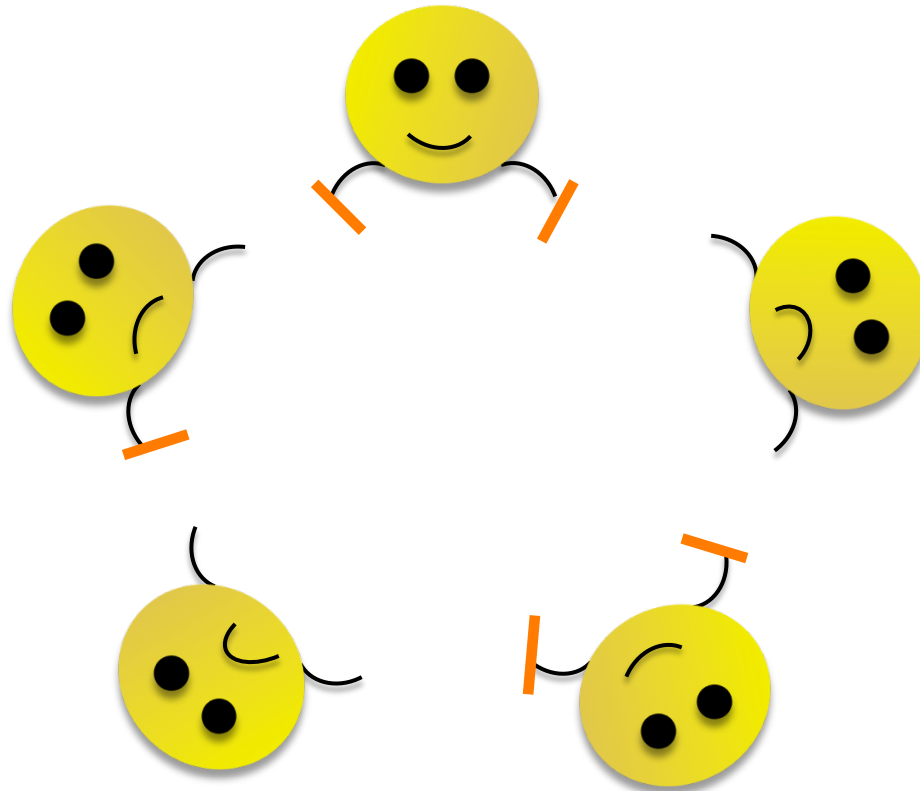
- ▶ Request₄ = (3, 3, 0)?
- ▶ Request₀ = (0, 2, 0)?

	Allocation			Max			Available			Need		
	A	B	C	A	B	C	A	B	C	A	B	C
P ₀	0	1	0	7	5	3	2	3	0	7	4	3
P ₁	3	0	2	3	2	2				0	2	0
P ₂	3	0	2	9	0	2				6	0	0
P ₃	2	1	1	2	2	2				0	1	1
P ₄	0	0	2	4	3	3				4	3	1



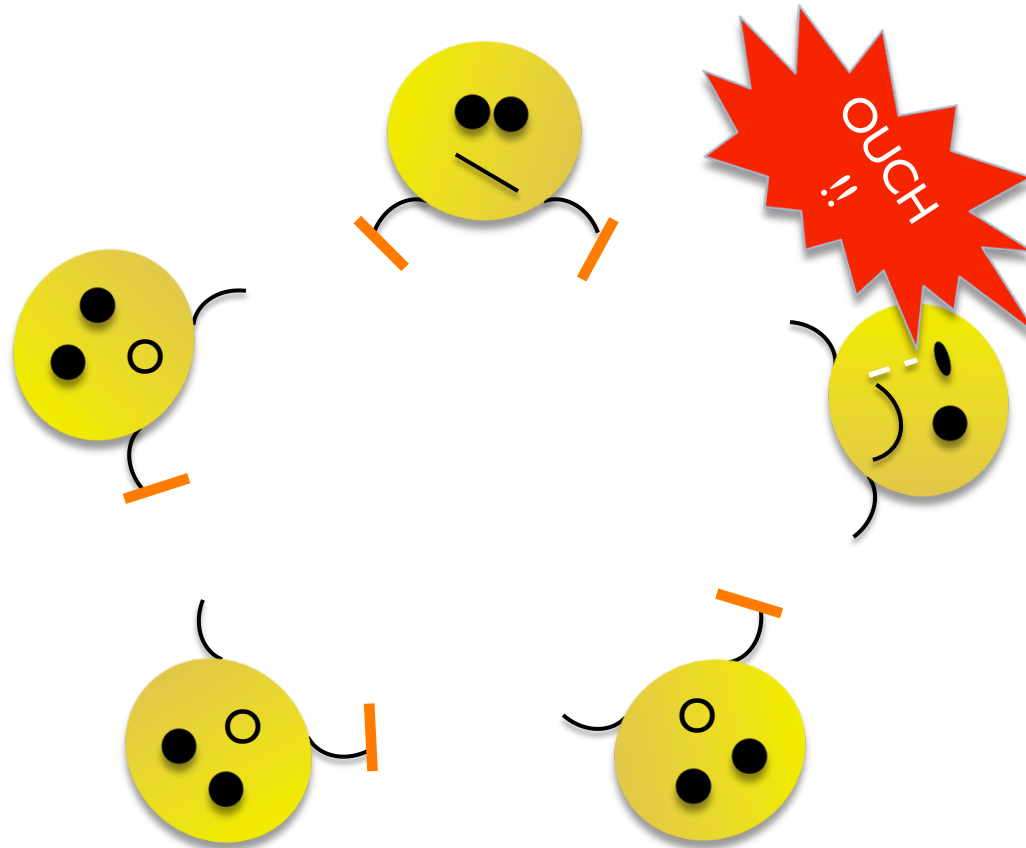


resources that are read-only can be concurrently accessed



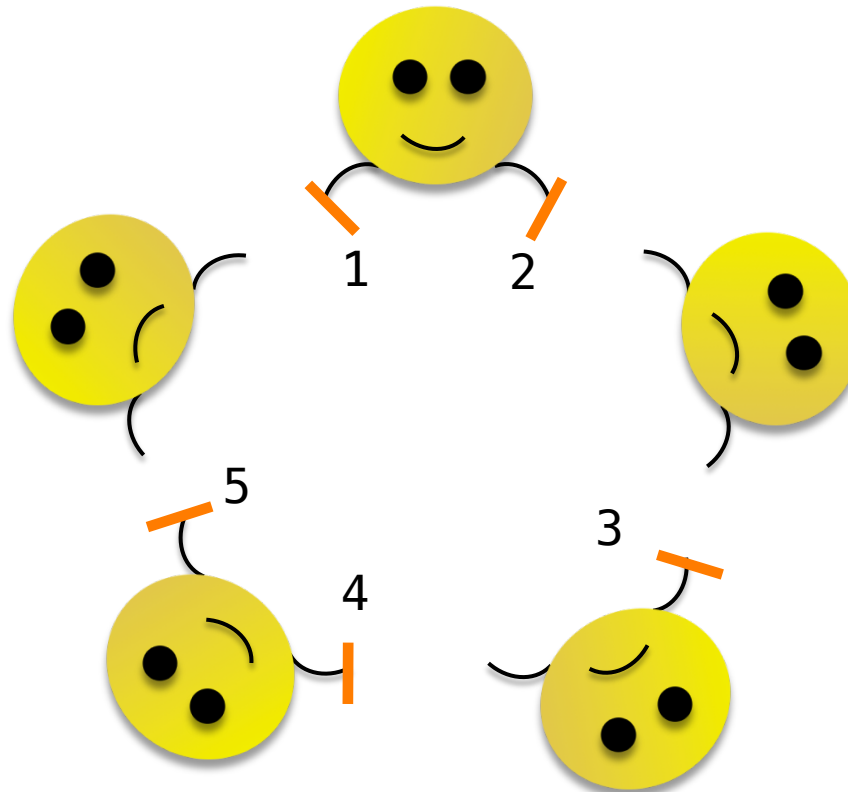
grab both chopsticks at the same time; philosopher wins if fast enough to get both

- must request all resources before using them
- release all resources on hold first, then request again



a philosopher forcefully takes a chopstick from another

- preempt resources from some processes



number chopsticks and allow philosophers to pick them in ascending order

- obtain resources according to some global numbering; must release all higher numbered resources if need a lower numbered one later

- ▶ Chapter 6, Modern Operating Systems, A. Tanenbaum and H. Bos, 4th Edition.