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1 PAGE 118,121
2 TITLE DSKETTE -- 04/21/86 DISKETTE BIOS
3 .286C
4 .LIST
5 SUBTTL (DSK(,ASM)
6 .LIST
7
8 INT 13H
9 DISKETTE I/O
10 THIS INTERFACE PROVIDES DISK ACCESS TO THE 5.25 INCH 360 KB,
11 1.2 MB, 720 KB, AND 1.44 MB DISKETTE DRIVES.
12 INPUT
13 (AH)=00H RESET DISKETTE SYSTEM
14 HARD RESET TO NEC, PREPARE COMMAND, RECALIBRATE REQUIRED
15 ON ALL DRIVES
16
17 (AH)=01H READ THE STATUS OF THE SYSTEM INTO (AH)
18 *DISKETTE STATUS FROM LAST OPERATION IS USED
19
20 REGISTERS FOR READ/WRITE/VERIFY/FORMAT
21 (DL) - DRIVE NUMBER (0-1 ALLOWED, VALUE CHECKED)
22 (DH) - HEAD NUMBER (0-1 ALLOWED, NOT VALUE CHECKED)
23 (CH) - TRACK NUMBER (NOT VALUE CHECKED)
24 MEDIA DRIVE TRACK NUMBER
25 320/360 320/360 0-39
26 320/360 1.2M 0-39
27 1.2M 1.2M 0-79
28 720K 720K 0-79
29 1.44M 1.44M 0-79
30 (CL) - SECTOR NUMBER (NOT VALUE CHECKED, NOT USED FOR FORMAT)
31 MEDIA DRIVE SECTOR NUMBER
32 320/360 320/360 1-8/9
33 320/360 1.2M 1-8/9
34 1.2M 1.2M 1-15
35 720K 720K 1-9
36 1.44M 1.44M 1-18
37 (AL) - NUMBER OF SECTORS (NOT VALUE CHECKED, NOT USED FOR FORMAT)
38 MAX NUMBER OF SECTORS
39 320/360 320/360 8/9
40 320/360 1.2M 8/9
41 1.2M 1.2M 15
42 720K 720K 9
43 1.44M 1.44M 18
44
45 (ES:BX) - ADDRESS OF BUFFER (NOT REQUIRED FOR VERIFY)
46
47 (AH)=02H READ THE DESIRED SECTORS INTO MEMORY
48
49 (AH)=03H WRITE THE DESIRED SECTORS FROM MEMORY
50
51 (AH)=04H VERIFY THE DESIRED SECTORS
52
53 (AH)=05H FORMAT THE DESIRED TRACK
54 (ES:BX) MUST POINT TO THE COLLECTION OF DESIRED ADDRESS FIELDS
55 FOR THE TRACK. EACH FIELD IS COMPOSED OF 4 BYTES, (C,H,R,N),
56 WHERE C = TRACK NUMBER, H = SECTOR NUMBER,
57 N = NUMBER OF BYTES PER SECTOR (00=128,01=256,02=512,03=1024).
58 THERE MUST BE ONE ENTRY FOR EVERY SECTOR ON THE TRACK.
59 THIS INFORMATION IS USED TO FIND THE REQUESTED SECTOR DURING
60 READ/WRITE ACCESS.
61
62 PRIOR TO FORMATTING A DISKETTE, IF THERE EXISTS MORE THAN
63 ONE SUPPORTED MEDIA FORMAT TYPE WITHIN THE DRIVE IN QUESTION,
64 THEN "SET DASD TYPE" (INT 13H, AH = 17H) OR "SET MEDIA TYPE"
65 (INT 13H, AH = 18H) MUST BE CALLED TO SET THE DISKETTE TYPE
66 THAT IS TO BE FORMATTED. IF "SET DASD TYPE" OR "SET MEDIA TYPE"
67 IS NOT CALLED, THE FORMAT ROUTINE WILL ASSUME THE MEDIA FORMAT
68 TO BE THE MAXIMUM CAPACITY OF THE DRIVE.
69
70 THESE PARAMETERS OF DISK BASE MUST BE CHANGED IN ORDER TO
71 FORMAT THE FOLLOWING MEDIA:
72
73 MEDIA DRIVE PARM 1 PARM 2
74
75 320K 320K/360K/1.2M 50H 8
76 360K 320K/360K/1.2M 50H 9
77 1.2M 1.2M 54H 15
78 720K 720K/1.44M 50H 9
79 1.44M 1.44M 6CH 18
80
81 NOTES: - PARM 1 = GAP LENGTH FOR FORMAT
82 - PARM 2 = EOT (LAST SECTOR ON TRACK)
83 - DISK BASE IS POINTED TO BY DISK POINTER LOCATED
84 AT ABSOLUTE ADDRESS 0178.
85 - WHEN FORMAT OPERATIONS ARE COMPLETE, THE PARAMETERS
86 SHOULD BE RESTORED TO THEIR RESPECTIVE INITIAL VALUES
87
88 READ DRIVE PARAMETERS
89
90 REGISTERS
91 INPUT
92 (DL) - DRIVE NUMBER (0-1 ALLOWED, VALUE CHECKED)
93 OUTPUT
94 (ES:DI) POINTS TO DRIVE PARAMETERS TABLE
95 (CH) - LOW ORDER 8 OF 10 BITS MAXIMUM NUMBER OF TRACKS
96 (CL) - BITS 7 & 6 - HIGH ORDER TWO BITS OF MAXIMUM TRACKS
97 - BITS 5 THRU 0 - MAXIMUM SECTORS PER TRACK
98 (DH) - MAXIMUM HEAD NUMBER
99 (DL) - NUMBER OF DISKETTE DRIVES INSTALLED
100 (BH) 0
101 (BL) - BITS 7 THRU 4 - 0
102 - BITS 3 THRU 0 - VALID DRIVE TYPE VALUE IN CMOS
103 (AX) = 0
104 UNDER THE FOLLOWING CIRCUMSTANCES:
105 (1) THE DRIVE NUMBER IS INVALID.
106 (2) THE DRIVE TYPE IS UNKNOWN AND CMOS IS NOT PRESENT.
107 (3) THE DRIVE TYPE IS UNKNOWN AND CMOS IS BAD.
108 (4) OR THE DRIVE TYPE IS UNKNOWN AND THE CMOS DRIVE TYPE IS INVALID
109 THEN ES,AX,BX,CX,DH,DI=0; DL=NUMBER OF DRIVES.
110 IF NO DRIVES ARE PRESENT THEN ES,AX,BX,CX,DX,DI=0.
111 *DSKETTE_STATUS = 0 AND CY IS RESET.
112
113 (AH)=15H READ DASD TYPE
114 OUTPUT REGISTERS
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115      (AH) - ON RETURN IF CARRY FLAG NOT SET, OTHERWISE ERROR
116      :
117      : 00 - DRIVE NOT PRESENT
118      : 01 - DISKETTE, NO CHANGE LINE AVAILABLE
119      : 02 - DISKETTE, CHANGE LINE AVAILABLE
120      : 03 - RESERVED
121      :
122      (DL) - DRIVE NUMBER (0-1 ALLOWED, VALUE CHECKED)
123      :
124      -----
125      (AH)=16H DISK CHANGE LINE STATUS
126      OUTPUT REGISTERS
127      (AH) - 00 - DISK CHANGE LINE NOT ACTIVE
128      : 06 - DISK CHANGE LINE ACTIVE & CARRY BIT ON
129      :
130      (DL) - DRIVE NUMBER (0-1 ALLOWED, VALUE CHECKED)
131      :
132      -----
133      (AH)=17H SET DASH TYPE FOR FORMAT
134      INPUT REGISTERS
135      (AL) - 00 - NOT USED
136      : 01 - DISKETTE 320/360K IN 360K DRIVE
137      : 02 - DISKETTE 360K IN 1.2M DRIVE
138      : 03 - DISKETTE 1.2M IN 1.2M DRIVE
139      : 04 - DISKETTE 720K IN 120K DRIVE
140      :
141      (DL) - DRIVE NUMBER (0-1 ALLOWED, VALUE CHECKED;
142      : DO NOT USE WHEN DISKETTE ATTACH CARD USED)
143      :
144      -----
145      (AH)=18H SET MEDIA TYPE FOR FORMAT
146      INPUT REGISTERS
147      (CH) - LOW ORDER 8 OF 10 BITS MAXIMUM NUMBER OF TRACKS
148      :
149      (CL) - BITS 7 & 6 - HIGH ORDER TWO BITS OF MAXIMUM TRACKS
150      :
151      : BITS 5 THRU 0 - MAXIMUM SECTORS PER TRACK
152      :
153      (DL) - DRIVE NUMBER (0-1 ALLOWED, VALUE CHECKED)
154      :
155      OUTPUT REGISTERS
156      (ESI:DI) - POINTER TO DRIVE PARAMETERS TABLE FOR THIS MEDIA TYPE,
157      : UNCHANGED IF (AH) IS NON-ZERO
158      :
159      (AH) - 00H, CY = 0, TRACK AND SECTORS/TRACK COMBINATION IS SUPPORTED
160      :
161      : 01H, CY = 1, FUNCTION IS NOT AVAILABLE
162      :
163      : 02H, CY = 1, TRACK AND SECTORS/TRACK COMBINATION IS NOT SUPPORTED
164      :
165      : 80H, CY = 1, TIME OUT (DISKETTE NOT PRESENT)
166      :
167      DISK CHANGE STATUS IS ONLY CHECKED WHEN A MEDIA SPECIFIED IS OTHER
168      : THAN 360 KB DRIVE. IF THE DISK CHANGE LINE IS FOUND TO BE
169      : ACTIVE THE FOLLOWING ACTIONS TAKE PLACE:
170      :
171      : ATTEMPT TO RESET DISK CHANGE LINE TO INACTIVE STATE.
172      : IF ATTEMPT SUCCEEDS SET DASH TYPE FOR FORMAT AND RETURN DISK
173      : CHANGE ERROR CODE
174      : IF ATTEMPT FAILS RETURN TIMEOUT ERROR CODE AND SET DASH TYPE
175      : TO A PREDETERMINED STATE INDICATING MEDIA TYPE UNKNOWN.
176      : IF THE DISK CHANGE LINE IN INACTIVE PERFORM SET DASH TYPE FOR FORMAT.
177      :
178      DATA VARIABLE -- #DISK POINTER
179      : DOUBLE WORD POINTER TO THE CURRENT SET OF DISKETTE PARAMETERS
180      :
181      OUTPUT FOR ALL FUNCTIONS
182      :
183      : AH = STATUS OF OPERATION
184      :
185      : STATUS BITS ARE
186      :
187      : VARIABLE IN THE DATA SEGMENT OF THIS MODULE
188      :
189      : CY = 0 SUCCESSFUL OPERATION (AH=0 ON RETURN, EXCEPT FOR READ DASH
190      : : TYPE AH=(15)).
191      :
192      : CY = 1 FAILED OPERATION (AH HAS ERROR REASON)
193      :
194      : FOR READ/WRITE/VERIFY
195      :
196      : AL = COUNT OF SECTORS TRANSFERRED
197      :
198      : DS,BX,DX,CX RESERVED
199      :
200      : NOTE: IF AN ERROR IS REPORTED BY THE DISKETTE CODE, THE APPROPRIATE
201      : : ACTION IS TO RESET THE DISKETTE, THEN RETRY THE OPERATION.
202      : : ON READ ACCESSSES, NO MOTOR START DELAY IS TAKEN, SO THAT
203      : : THREE RETRIES ARE REQUIRED ON READS TO ENSURE THAT THE
204      : : PROBLEM IS NOT DUE TO MOTOR START-UP.
205      :
206      -----
207      .LIST
208      : DISKETTE STATE MACHINE - ABSOLUTE ADDRESS 40190 (DRIVE A) & 91 (DRIVE B)
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PAGE
225
226 MD_STRUC STRUC
227 MD_SPEC1 DB ? ; SRT=D, HD UNLOAD=0F - 1ST SPECIFY BYTE
228 MD_SPEC2 DB ? ; HD LOAD=1, MODE=DMA - 2ND SPECIFY BYTE
229 MD_OFF_TIM DB ? ; WAIT TIME AFTER OPERATION TILL MOTOR OFF
230 MD_BYT_SEC DB ? ; 512 BYTES/SECTOR
231 MD_SEC_TRK DB ? ; EOT (LAST SECTOR ON TRACK)
232 MD_GAP DB ? ; GAP LENGTH
233 MD_DTL DB ? ; DTL
234 MD_GAPS DB ? ; GAP LENGTH FOR FORMAT
235 MD_FIL_BYT DB ? ; FILL BYTE FOR FORMAT
236 MD_HD_TIM DB ? ; HEAD SETTLE TIME (MILLISECONDS)
237 MD_STR_TRK DB ? ; MOTOR START TIME (1/8 SECONDS)
238 MD_MAX_TRK DB ? ; MAX. TRACK NUMBER
239 MD_RATE DB ? ; DATA TRANSFER RATE
240 MD_STRUC ENDS
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242 = 007F EQU 7FH
243 = 0080 EQU 80H
244
245 PUBLIC DISK_INT_I
246 PUBLIC SEEK
247 PUBLIC DSSETUP
248 PUBLIC DISKETTE_IO_I
249
250 EXTRN CMOS_READ:NEAR
251 EXTRN DDS:NEAR
252 EXTRN DISK_BASE:NEAR
253 EXTRN WAITF:NEAR
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344 0039          MD_TBL4          LABEL BYTE
345 003A 02          DB              1101111B          ; SRT=D, HD UNLOAD=0F - 1ST SPECIFY BYTE
346 003B 25          DB              2              ; HD LOAD=1, MODE=DMA - 2ND SPECIFY BYTE
347 003C 02          DB              MOTOR_WAIT      ; WAIT TIME AFTER OPERATION TILL MOTOR OFF
348 003D 09          DB              2              ; 512 BYTES/SECTOR
349 003E 2A          DB              09              ; EOT ( LAST SECTOR ON TRACK)
350 003F FF          DB              02AH            ; GAP LENGTH
351 0040 50          DB              0FFH            ; DTL
352 0041 F6          DB              050H            ; GAP LENGTH FOR FORMAT
353 0042 0F          DB              0F6H            ; FILL BYTE FOR FORMAT
354 0043 08          DB              15              ; HEAD SETTLE TIME (WILLI SECONDS)
355 0044 4F          DB              8              ; MOTOR START TIME (1/8 SECONDS)
356 0045 80          DB              79              ; MAX. TRACK NUMBER
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362 0046          MD_TBL5          LABEL BYTE
363 0046 DF          DB              1101111B          ; SRT=D, HD UNLOAD=0F - 1ST SPECIFY BYTE
364 0047 02          DB              2              ; HD LOAD=1, MODE=DMA - 2ND SPECIFY BYTE
365 0048 25          DB              MOTOR_WAIT      ; WAIT TIME AFTER OPERATION TILL MOTOR OFF
366 0049 02          DB              2              ; 512 BYTES/SECTOR
367 004A 09          DB              09              ; EOT ( LAST SECTOR ON TRACK)
368 004B 2A          DB              02AH            ; GAP LENGTH
369 004C FF          DB              0FFH            ; DTL
370 004D 50          DB              050H            ; GAP LENGTH FOR FORMAT
371 004E F6          DB              0F6H            ; FILL BYTE FOR FORMAT
372 004F 0F          DB              15              ; HEAD SETTLE TIME (WILLI SECONDS)
373 0050 08          DB              8              ; MOTOR START TIME (1/8 SECONDS)
374 0051 4F          DB              79              ; MAX. TRACK NUMBER
375 0052 80          DB              RATE_250         ; DATA TRANSFER RATE
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381 0053          MD_TBL6          LABEL BYTE
382 0053 AF          DB              1010111B          ; SRT=A, HD UNLOAD=0F - 1ST SPECIFY BYTE
383 0054 02          DB              2              ; HD LOAD=1, MODE=DMA - 2ND SPECIFY BYTE
384 0055 25          DB              MOTOR_WAIT      ; WAIT TIME AFTER OPERATION TILL MOTOR OFF
385 0056 02          DB              2              ; 512 BYTES/SECTOR
386 0057 12          DB              18              ; EOT ( LAST SECTOR ON TRACK)
387 0058 1B          DB              01BH            ; GAP LENGTH
388 0059 FF          DB              0FFH            ; DTL
389 005A 6C          DB              06CH            ; GAP LENGTH FOR FORMAT
390 005B F6          DB              0F6H            ; FILL BYTE FOR FORMAT
391 005C 0F          DB              15              ; HEAD SETTLE TIME (WILLI SECONDS)
392 005D 08          DB              8              ; MOTOR START TIME (1/8 SECONDS)
393 005E 4F          DB              79              ; MAX. TRACK NUMBER
394 005F 00          DB              RATE_500         ; DATA TRANSFER RATE
395
396
397 0060          DISKETTE_IO_1     PROC      FAR          ;>>> ENTRY POINT FOR ORG 0EC59H
398
399 0060 FB          STI              ; INTERRUPTS BACK ON
400 0061 55          PUSH     BP      ; USER REGISTER
401 0062 57          PUSH     DI      ; USER REGISTER
402 0063 52          PUSH     DX      ; HEAD #, DRIVE # OR USER REGISTER
403 0064 53          PUSH     BX      ; BUFFER OFFSET PARAMETER OR REGISTER
404 0065 51          PUSH     CX      ; TRACK #-SECTOR # OR USER REGISTER
405 0066 8B EC      MOV      BP,SP    ; BP => PARAMETER LIST DEP. ON AH
406
407              ; [BP] = SECTOR #
408              ; [BP+1] = TRACK #
409              ; [BP+2] = BUFFER OFFSET
410              ; FOR RETURN OF DRIVE PARAMETERS:
411              ; CL/[BP] = BITS 7&6 HI BITS OF MAX CYL
412              ; CH/[BP+1] = BITS 0-5 MAX SECTORS/TRACK
413              ; BL/[BP+2] = LOW 8 BITS OF MAX CYL.
414              ; BH/[BP+3] = BITS 3-0 = VALID CMOS TYPE
415              ; DL/[BP+4] = # DRIVES INSTALLED
416              ; DH/[BP+5] = MAX HEAD #
417              ; DI/[BP+6] = OFFSET TO DISK BASE
418              ; BUFFER SEGMENT PARM OR USER REGISTER
419 0068 1E          PUSH     DS      ; USER REGISTERS
420 0069 56          PUSH     SI      ; SEGMENT OF BIOS DATA AREA TO DS
421 006A E8 0000 E   CALL     DOS      ; CHECK FOR > LARGEST FUNCTION
422 006D 80 FC 19   CMP      AH,(FNC_TAE-FNC_TAB)/2 ; FUNCTION OK
423 0070 72 02      JB       OK_FUNC  ; REPLACE WITH KNOWN INVALID FUNCTION
424 0072 B4 14      MOV      AH,14H
425
426 0074          OK_FUNC:
427 0074 80 FC 01   CMP      AH,1          ; RESET OR STATUS ?
428 0077 76 0C      JBE      OK_DRV   ; IF RESET OR STATUS DRIVE ALWAYS OK
429 0079 80 FC 08   CMP      AH,8          ; READ DRIVE PARAMS ?
430 007C 74 07      JZ       OK_DRV   ; IF 0 DRIVE CHECKED LATER
431 007E 80 FA 01   CMP      DI,1          ; DRIVES 0 AND 1 OK
432 0081 76 02      JBE      OK_DRV   ; IF 0 OR 1 THEN JUMP
433 0083 B4 14      MOV      AH,14H   ; REPLACE WITH KNOWN INVALID FUNCTION
434
435 0085          OK_DRV:
436 0085 8A CC      MOV      CL,AH      ; CL = FUNCTION
437 0087 32 ED      XOR      CH,CH      ; CX = FUNCTION
438 0089 D0 E1      SHL      CL,1      ; FUNCTION TIMES 2
439 008B 8B 05 B R   MOV      BX,OFFSET FNC_TAB ; LOAD START OF FUNCTION TABLE
440 008E 03 D9      ADD      BX,CX      ; ADD OFFSET INTO TABLE => ROUTINE
441 0090 8A E6      MOV      AH,DH      ; AX = HEAD #, # OF SECTORS OR DASD TYPE
442 0092 32 F6      XOR      DH,DH      ; DX = DRIVE #
443 0094 8B F0      MOV      SI,AX      ; SI = HEAD #, # OF SECTORS OR DASD TYPE
444 0096 8B FA      MOV      DI,DX      ; DI = DRIVE #
445 0098 8A 26 0041 R MOV      AH,DISKETTE_STATUS ; LOAD STATUS TO AH FOR STATUS FUNCTION
446 009C C6 06 0041 R MOV      DS,DISKETTE_STATUS,0 ; INITIALIZE FOR ALL OTHERS
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452      I          DI      : DRIVE #
453      I          SI-HI   : HEAD #
454      I          SI-LOW  : # OF SECTORS OR DASD TYPE FOR FORMAT
455      I          ES      : BUFFER SEGMENT
456      I          [BP]    : SECTOR #
457      I          [BP+1]  : TRACK #
458      I          [BP+2]  : BUFFER OFFSET
459      I
460      I          ACROSS CALLS TO SUBROUTINES THE CARRY FLAG (CY=1), WHERE INDICATED IN
461      I          SUBROUTINE PROLOGUES, REPRESENTS AN EXCEPTION RETURN (NORMALLY AN ERROR
462      I          CONDITION). IN MOST CASES, WHEN CY = 1, *DSKETTE_STATUS CONTAINS THE
463      I          SPECIFIC ERROR CODE.
464      I
465      00A1 2E: FF 17      CALL    WORD PTR CS:[BX]      I (AH) = *DSKETTE_STATUS
466      I                  I CALL THE REQUESTED FUNCTION
467      00A4 5E            POP     SI                  I RESTORE ALL REGISTERS
468      00A5 1F            POP     DS
469      00A6 59            POP     CX
470      00A7 5B            POP     BX
471      00A8 5A            POP     DX
472      00A9 5F            POP     DI
473      00AA 8B EC         MOV     BP,SP
474      00AC 50            PUSH    AX
475      00AD 9C            PUSHF
476      00AE 58            POP     AX
477      00AF 89 46 06      MOV     [BP+6],AX
478      00B0 5D            POP     BP
479      00B3 5D            POP     BP
480      00B4 CF            IRET
481
482      -----
483      00B5 00E7 R        FNC_TAB DW    DISK_RESET      I AH = 00H: RESET
484      00B7 013C R        DW    DISK_STATUS           I AH = 01H: STATUS
485      00B9 0148 R        DW    DISK_READ             I AH = 02H: READ
486      00BB 0154 R        DW    DISK_WRITE            I AH = 03H: WRITE
487      00BD 0160 R        DW    DISK_VERIFY           I AH = 04H: VERIFY
488      00BF 016C R        DW    DISK_FORMAT           I AH = 05H: FORMAT
489      00C1 01C6 R        DW    FNC_ERR               I AH = 06H: INVALID
490      00C3 01C6 R        DW    FNC_ERR               I AH = 07H: INVALID
491      00C5 01D0 R        DW    DISK_PARAMS            I AH = 08H: READ DRIVE PARAMETERS
492      00C7 01C6 R        DW    FNC_ERR               I AH = 09H: INVALID
493      00C9 01C6 R        DW    FNC_ERR               I AH = 0AH: INVALID
494      00CB 01C6 R        DW    FNC_ERR               I AH = 0BH: INVALID
495      00CD 01C6 R        DW    FNC_ERR               I AH = 0CH: INVALID
496      00CF 01C6 R        DW    FNC_ERR               I AH = 0DH: INVALID
497      00D1 01C6 R        DW    FNC_ERR               I AH = 0EH: INVALID
498      00D3 01C6 R        DW    FNC_ERR               I AH = 0FH: INVALID
499      00D5 01C6 R        DW    FNC_ERR               I AH = 10H: INVALID
500      00D7 01C6 R        DW    FNC_ERR               I AH = 11H: INVALID
501      00D9 01C6 R        DW    FNC_ERR               I AH = 12H: INVALID
502      00DB 01C6 R        DW    FNC_ERR               I AH = 13H: INVALID
503      00DD 01C6 R        DW    FNC_ERR               I AH = 14H: INVALID
504      00DF 0289 R        DW    DISK_TYPE             I AH = 15H: READ DASD TYPE
505      00E1 02AB R        DW    DISK_CHANGE           I AH = 16H: CHANGE STATUS
506      00E3 02D6 R        DW    FORMAT_SET           I AH = 17H: SET DASD TYPE
507      00E5 0337 R        DW    SET_MEDIA             I AH = 18H: SET MEDIA TYPE
508      = 00E7            FNC_TAE EQU    $
509      00E7            DISKETTE_IO_1 ENDP
510
511      I          I DISK_RESET (AH = 00H)
512      I          I RESET THE DISKETTE SYSTEM.
513      I
514      I          I ON EXIT: *DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION
515      I          I
516      I          I
517      00E7            PROC    NEAR
518      00E7 BA 03F2        MOV     DX,03F2H          I ADAPTER CONTROL PORT
519      00EB FA            CLD                     I NO INTERRUPTS
520      00EE 24 3F          AND     AL,00111111B      I GET DIGITAL OUTPUT REGISTER REFLECTION
521      00F0 C0 C0 04      ROL     AL,4              I KEEP SELECTED AND MOTOR ON BITS
522      I          I MOTOR VALUE TO HIGH NIBBLE
523      00F3 0C 08          OR      AL,00001000B      I DRIVE SELECT TO LOW NIBBLE
524      00F5 EE            OUT      DX,AL             I TURN ON INTERRUPT ENABLE
525      00F6 C6 06 003E R 00 MOV     *SEEK_STATUS,0      I RESET THE ADAPTER
526      00FB EB 00          JMP     $+2              I SET RECALIBRATE REQUIRED ON ALL DRIVES
527      00FD EB 00          JMP     $+2              I WAIT FOR I/O (TO INSURE MINIMUM
528      I          I PULSE WIDTH)
529      00FF 0C 04          OR      AL,00000100B      I TURN OFF RESET BIT
530      0101 EE            OUT      DX,AL             I RESET THE ADAPTER
531      0102 FE            STI                     I ENABLE THE INTERRUPTS
532      0103 E8 0AC1 R      CALL    WAIT_INT          I WAIT FOR THE INTERRUPT
533      0106 72 2D          JC      DR_ERR            I IF ERROR, RETURN IT
534      0108 B9 00C0        MOV     CX,11000000B      I CL = EXPECTED *NEC_STATUS
535
536      010B            NEXT_DRV:
537      010B 51            PUSH    CX                I SAVE FOR CALL
538      010C B8 0134 R      MOV     AX,OFFSET DR_POP_ERR I LOAD NEC_OUTPUT ERROR ADDRESS
539      010F 50            PUSH    AX
540      0110 B4 08          MOV     AH,08H           I SENSE INTERRUPT STATUS COMMAND
541      0112 E8 09F8 R      CALL    NEC_OUTPUT        I THROW AWAY ERROR RETURN
542      0115 58            POP     AX                I READ IN THE RESULTS
543      0116 E8 0AE9 R      CALL    RESULTS           I RESTORE AFTER CALL
544      0119 59            POP     CX
545      011A 72 19          JC      DR_ERR            I ERROR RETURN
546      011C 3A 0E 0042 R  CMP     CL,*NEC_STATUS      I TEST FOR DRIVE READY TRANSITION
547      0120 75 13          JNZ     DR_ERR            I EVERYTHING OK
548      0122 FE C1          INC     CL              I NEXT EXPECTED *NEC STATUS
549      0124 80 F9 C3      CMP     BP,*NEC_STATUS      I ALL POSSIBLE DRIVES CLEARED
550      0127 76 E2          JBE     NEXT_DRV          I FALL THRU IF 1100100B OR >
551
552      0129 E8 03D8 R      CALL    SEND_SPEC          I SEND SPECIFY COMMAND TO NEC
553
554      012C            RESBAC:
555      012C E8 0854 R      CALL    SETUP_END          I VARIOUS CLEANUPS
556      012F 8B DE          MOV     BX,SI             I GET SAVED AL TO BL
557      0131 8A C3          MOV     AL,BL             I PUT BACK FOR RETURN
558      0133 C3            RET
559
560      0134            DR_POP_ERR:
561      0134 59            POP     CX                I CLEAR STACK
562      0135
563      0135 80 041 R 20      OR      *DSKETTE_STATUS,BAD_NEC I SET ERROR CODE
564      013A EB F0          JMP     RESBAC          I RETURN FROM RESET
565      013C            DISK_RESET
566      013C            ENDP

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574 013C
575 013C B8 26 0041 R
576 0140 E8 0854 R
577 0143 B8 DE
578 0145 BA C3
579 0147 C3
580 0148
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594 0148
595 0148 B0 26 003F R 7F
596 014D B8 E646
597 0150 E8 04AE R
598 0153 C3
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613 0154
614 0154 B8 C54A
615 0157 B0 0E 003F R 80
616 015C E8 04AE R
617 015F C3
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633 0160 B0 26 003F R 7F
634 0165 B8 E642
635 0168 E8 04AE R
636 016B C3
637 016C
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653 016C
654 016C E8 040F R
655 016F E8 0598 R
656 0172 B0 0E 003F R 80
657 0177 E8 05E9 R
658 017A 72 3F
659 017C E8 0808 R
660 017F E8 063D R
661 0182 74 03
662 0184 E8 0624 R
663 0187
664 0187 E8 06AD R
665 018A 72 2F
666 018C B4 40
667 018E E8 0700 R
668 0191 72 28
669 0193 B8 01BB R
670 0196 50
671 0197 B2 03
672 0199 E8 0905 R
673 019C E8 09F8 R
674 019F B2 04
675 01A1 E8 0905 R
676 01A4 E8 09F8 R
677 01A7 B2 07
678 01A9 E8 0905 R
679 01AC E8 09F8 R

;-----;
; DISK_STATUS (AH = 01H) ;
; DISKETTE STATUS. ;
; ON ENTRY: AH = STATUS OF PREVIOUS OPERATION ;
; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION ;
;-----;
DISK_STATUS PROC NEAR
; MOV 0DSKETTE_STATUS,AH ; PUT BACK FOR SETUP END
; CALL SETUP_END ; VARIOUS CLEANUPS
; MOV BX,SI ; GET SAVED AL TO BL
; MOV AL,BL ; PUT BACK FOR RETURN
; RET
DISK_STATUS ENDP
;-----;
; DISK_READ (AH = 02H) ;
; DISKETTE READ. ;
; ON ENTRY: DI = DRIVE # ;
; SI-HI = HEAD # ;
; SI-LOW = # OF SECTORS ;
; ES = BUFFER SEGMENT ;
; [BP] = SECTOR # ;
; [BP+1] = TRACK # ;
; [BP+2] = BUFFER OFFSET ;
; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION ;
;-----;
DISK_READ PROC NEAR
; AND 0MOTOR_STATUS,01111111B ; INDICATE A READ OPERATION
; MOV AX,DE646H ; AX = NEC COMMAND, DMA COMMAND
; CALL RD_WR_VF ; COMMON READ/WRITE/VERIFY
; RET
DISK_READ ENDP
;-----;
; DISK_WRITE (AH = 03H) ;
; DISKETTE WRITE. ;
; ON ENTRY: DI = DRIVE # ;
; SI-HI = HEAD # ;
; SI-LOW = # OF SECTORS ;
; ES = BUFFER SEGMENT ;
; [BP] = SECTOR # ;
; [BP+1] = TRACK # ;
; [BP+2] = BUFFER OFFSET ;
; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION ;
;-----;
DISK_WRITE PROC NEAR
; MOV AX,0C54AH ; AX = NEC COMMAND, DMA COMMAND
; MOV 0MOTOR_STATUS,10000000B ; INDICATE WRITE OPERATION
; CALL RD_WR_VF ; COMMON READ/WRITE/VERIFY
; RET
DISK_WRITE ENDP
;-----;
; DISK_VERIFY (AH = 04H) ;
; DISKETTE VERIFY. ;
; ON ENTRY: DI = DRIVE # ;
; SI-HI = HEAD # ;
; SI-LOW = # OF SECTORS ;
; ES = BUFFER SEGMENT ;
; [BP] = SECTOR # ;
; [BP+1] = TRACK # ;
; [BP+2] = BUFFER OFFSET ;
; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION ;
;-----;
DISK_VERIFY PROC NEAR
; AND 0MOTOR_STATUS,01111111B ; INDICATE A READ OPERATION
; MOV AX,DE642H ; AX = NEC COMMAND, DMA COMMAND
; CALL RD_WR_VF ; COMMON READ/WRITE/VERIFY
; RET
DISK_VERIFY ENDP
;-----;
; DISK_FORMAT (AH = 05H) ;
; DISKETTE FORMAT. ;
; ON ENTRY: DI = DRIVE # ;
; SI-HI = HEAD # ;
; SI-LOW = # OF SECTORS ;
; ES = BUFFER SEGMENT ;
; [BP] = SECTOR # ;
; [BP+1] = TRACK # ;
; [BP+2] = BUFFER OFFSET ;
; 0DISK_POINTER POINTS TO THE PARAMETER TABLE OF THIS DRIVE ;
; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION ;
;-----;
DISK_FORMAT PROC NEAR
; CALL XLAT_NEW ; TRANSLATE STATE TO PRESENT ARCH.
; CALL FMT_INIT ; ESTABLISH STATE, IF UNESTABLISHED
; OR 0MOTOR_STATUS,10000000B ; INDICATE WRITE OPERATION
; OR MED_CHANGE ; CHECK MEDIA CHANGE AND RESET IF SO
; JC FM_DON ; MEDIA CHANGED, SKIP
; CALL SEND_SPEC ; SEND SPECIFY COMMAND TO NEC
; CALL CHK_LASTRATE ; 2F+1 ATTEMPT RATE IS SAME AS LAST RATE
; JZ FM_WR ; YES, SKIP SPECIFY COMMAND
; CALL SEND_RATE ; SEND DATA RATE TO CONTROLLER
; FM_WR: CALL FMTDMA_SET ; SET UP THE DMA FOR FORMAT
; JC FM_DON ; RETURN WITH ERROR
; MOV AH,040H ; ESTABLISH THE FORMAT COMMAND
; CALL NEC_INIT ; INITIALIZE THE NEC
; JC FM_DON ; ERROR - EXIT
; MOV AX,OFFSET FM_DON ; LOAD ERROR ADDRESS
; PUSH AX ; PUSH NEC OUT ERROR RETURN
; MOV DI,3 ; BYTES/SECTOR VALUE TO NEC
; CALL GET_PARM ; SECTORS/TRACK VALUE TO NEC
; CALL NEC_OUTPUT
; MOV DI,4
; CALL GET_PARM
; CALL NEC_OUTPUT
; MOV DI,5
; CALL GET_PARM ; GAP LENGTH VALUE TO NEC
; CALL NEC_OUTPUT

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680 01AF B2 08          MOV     DL,8          ; FILLER BYTE TO NEC
681 01B1 E8 0905 R      CALL    GET_PARM
682 01B4 E8 09F8 R      CALL    NEC_OUTPUT
683 01B7 58             POP     AX          ; THROW AWAY ERROR
684 01B8 E8 075B R      CALL    NEC_TERM    ; TERMINATE, RECEIVE STATUS, ETC.
685 01BB                FM_DON:
686 01BB E8 0435 R      CALL    XLAT_OLD    ; TRANSLATE STATE TO COMPATIBLE MODE
687 01BE E8 0854 R      CALL    SETUP_END  ; VARIOUS CLEANUPS
688 01C1 8B DE          MOV     BX,SI       ; GET SAVED AL TO BL
689 01C3 8A C3          MOV     AL,BL       ; PUT BACK FOR RETURN
690 01C5 C3             RET
691 01C6                DISK_FORMAT
692                        ENDP
693
694 FNC_ERR:
695     INVALID FUNCTION REQUESTED OR INVALID DRIVE;
696     SET BAD COMMAND IN STATUS.
697
698     ON EXIT:      *DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION
699
700 FNC_ERR PROC NEAR
701     MOV     AX,SI
702     MOV     AH,BAD_CMD
703     MOV     *DSKETTE_STATUS,AH
704     STC
705     RET
706 FNC_ERR ENDP
707
708     DISK_PARAMS (AH = 08H)
709     READ DRIVE PARAMETERS.
710
711     ON ENTRY:
712     DI = DRIVE #
713
714     ON EXIT:
715     CL/[BP] = BITS 7 & 6 HIGH 2 BITS OF MAX CYLINDER
716             BITS 0-5 MAX SECTORS/TRACK
717     CH/[BP+1] = LOW 8 BITS OF MAX CYLINDER
718     BL/[BP+2] = BITS 7-4 = 0
719             BITS 3-0 = VALID CMOS DRIVE TYPE
720     BH/[BP+3] = 0
721     DL/[BP+4] = # DRIVES INSTALLED
722     DH/[BP+5] = MAX HEAD #
723     DI/[BP+6] = OFFSET OF MEDIA/DRIVE PARAMETER TABLE
724     ES = SEGMENT OF MEDIA/DRIVE PARAMETER TABLE
725     AX = 0
726
727     NOTE: THE ABOVE INFORMATION IS STORED IN THE USERS STACK AT
728           THE LOCATIONS WHERE THE MAIN ROUTINE WILL POP THEM
729           INTO THE APPROPRIATE REGISTERS BEFORE RETURNING TO THE
730           CALLER.
731
732 DISK_PARAMS PROC NEAR
733     CALL    XLAT_NEW
734     MOV     WORD PTR [BP+2],0
735     MOV     AX,EQUIP_FLAG
736     AND     AL,10000001B
737     MOV     DL,2
738     CMP     AL,010000001B
739     JZ      STO_DL
740
741     DEC     DL
742     CMP     AL,000000001B
743     JNZ     NON_DRV
744
745     MOV     [BP+4],DL
746     CMP     DI,1
747     JNE     NON_DRV1
748     MOV     BYTE PTR [BP+5],1
749     CALL    CMOS_TYPE
750     JC      CHK_EST
751     OR      AL,AL
752     JC      CHK_EST
753     CALL    DR_TYPE_CHECK
754     JC      CHK_EST
755     MOV     [BP+2],AL
756     MOV     CL,CS:[BX].MD_SEC_TRK
757     MOV     CH,CS:[BX].MD_MAX_TRK
758     JMP     SHORT STO_CX
759
760     ; TRANSLATE STATE TO PRESENT ARCH.
761     ; DRIVE TYPE = 0
762     ; LOAD EQUIPMENT FLAG FOR # DISKETTES
763     ; KEEP DISKETTE DRIVE BITS
764     ; DISKETTE DRIVES = 2
765     ; 2 DRIVES INSTALLED ?
766     ; IF YES JUMP
767
768     ; DISKETTE DRIVES = 1
769     ; 1 DRIVE INSTALLED ?
770     ; IF NO JUMP
771
772 STO_DL: MOV     [BP+4],DL
773     CMP     DI,1
774     JNE     NON_DRV1
775     MOV     BYTE PTR [BP+5],1
776     CALL    CMOS_TYPE
777     JC      CHK_EST
778     OR      AL,AL
779     JC      CHK_EST
780     CALL    DR_TYPE_CHECK
781     JC      CHK_EST
782     MOV     [BP+2],AL
783     MOV     CL,CS:[BX].MD_SEC_TRK
784     MOV     CH,CS:[BX].MD_MAX_TRK
785     JMP     SHORT STO_CX
786
787     ; STORE NUMBER OF DRIVES
788     ; CHECK FOR VALID DRIVE
789     ; DRIVE INVALID
790     ; MAXIMUM HEAD NUMBER = 1
791     ; RETURN DRIVE TYPE IN AL
792     ; ON CMOS BAD CHECK ESTABLISHED
793     ; TEST FOR NO DRIVE TYPE
794     ; JUMP IF SO
795     ; RTN CS:BX = MEDIA/DRIVE PARAM TBL
796     ; TYPE NOT IN TABLE (POSSIBLE BAD CMOS)
797     ; STORE VALID CMOS DRIVE TYPE
798     ; GET SECTOR/TRACK
799     ; GET MAX. TRACK NUMBER
800     ; CMOS GOOD, USE CMOS
801
802 CHK_EST: MOV     AH,*DSK_STATE[DI]
803     TEST    AH,MED_DET
804     JZ      NON_DRV1
805
806     ; LOAD STATE FOR THIS DRIVE
807     ; CHECK FOR ESTABLISHED STATE
808     ; CMOS BAD/INVALID AND UNESTABLISHED
809
810 USE_EST: MOV     AH,RATE_MSK
811     AND     AH,RATE_280
812     CMP     AH,RATE_280
813     JNE     USE_EST2
814
815     ; ISOLATE STATE
816     ; RATE 250 ?
817     ; NO, GO CHECK OTHER RATE
818
819 ---- DATA RATE IS 250 KBS, TRY 360 KB TABLE FIRST
820
821     MOV     AL,01
822     CALL    DR_TYPE_CHECK
823     MOV     CL,CS:[BX].MD_SEC_TRK
824     MOV     CH,CS:[BX].MD_MAX_TRK
825     TEST    *DSK_STATE[DI],TRK_CAPA
826     JZ      STO_CX
827
828     ; DRIVE TYPE 1 (360KB)
829     ; RTN CS:BX = MEDIA/DRIVE PARAM TBL
830     ; GET SECTOR/TRACK
831     ; GET MAX. TRACK NUMBER
832     ; 80 TRACK ?
833     ; MUST BE 360KB DRIVE
834
835 ---- IT IS 1.44 MB DRIVE
836
837 PARM144: MOV     AL,04
838     CALL    DR_TYPE_CHECK
839     MOV     CL,CS:[BX].MD_SEC_TRK
840     MOV     CH,CS:[BX].MD_MAX_TRK
841
842     ; DRIVE TYPE 4 (1.44MB)
843     ; RTN CS:BX = MEDIA/DRIVE PARAM TBL
844     ; GET SECTOR/TRACK
845     ; GET MAX. TRACK NUMBER
846
847 STO_CX: MOV     [BP],CX
848     MOV     [BP+4],BX
849     MOV     AX,CS
850     MOV     ES,AX
851
852     ; SAVE IN STACK FOR RETURN
853     ; ADDRESS OF MEDIA/DRIVE PARAM TABLE
854     ; SEGMENT MEDIA/DRIVE PARAMETER TABLE
855     ; ES IS SEGMENT OF TABLE
856
857 DP_OUT: CALL    XLAT_OLD
858     XOR     AX,AX
859     CLC
860     RET

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794
795
796 ;----- NO DRIVE PRESENT HANDLER
797
798 0253 NO_DRIVE: MOV     BYTE PTR [BP+4],0      ; CLEAR NUMBER OF DRIVES
799
800 0257 NON_DRIVE1:
801 0257 81 FF 0080 CMP     DI,80H                      ; CHECK FOR FIXED MEDIA TYPE REQUEST
802 0258 72 09 JB      NON_DRIVE2              ; CONTINUE IF NOT REQUEST FALL THROUGH
803
804 ;----- FIXED DISK REQUEST FALL THROUGH ERROR
805
806 025D E8 0435 R CALL     XLAT_OLD                      ; ELSE TRANSLATE TO COMPATIBLE MODE
807 0260 8B C6 MOV     AX,SI                      ; RESTORE AL
808 0262 B4 01 MOV     AH,BAD_CMD                 ; SET BAD COMMAND ERROR
809 0264 F9 STC                                     ; SET ERROR RETURN CODE
810 0265 C3 RET
811
812 0266 33 C0 XOR     AX,AX                      ; CLEAR PARMS IF NO DRIVES OR CMOS BAD
813 0268 89 46 00 MOV     [BP],AX                    ; TRACKS, SECTORS/TRACK = 0
814 026B 86 66 05 MOV     [BP+5],AH                  ; HEAD = 0
815 026E 89 46 06 MOV     [BP+6],AX                    ; OFFSET TO DISK BASE = 0
816 0271 8E C0 MOV     ES,AX                      ; ES IS SEGMENT OF TABLE
817 0273 EB D7 JMP     SHORT DP_OUT
818
819 ;---- DATA RATE IS EITHER 300 KBS OR 500 KBS, TRY 1.2 MB TABLE FIRST
820
821
822 0275 USE_EST2:
823 0275 B0 02 MOV     AL,02                      ; DRIVE TYPE 2 (1.2MB)
824 0277 E8 03B8 R CALL     AL,DT_TYPE_CHECK          ; RTN CSI:BX = MEDIA/DRIVE PARAM TBL
825 027A 2E1 5A 4F 04 MOV     CL,CSI[BX],MD_SEC_TRK      ; GET SECTOR/TRACK
826 027E 2E1 5A 6F 0B MOV     CH,CSI[BX],MD_MAX_TRK     ; GET MAX. TRACK NUMBER
827 0282 80 FC 40 CMP     AH,RA_300              ; RASTOR 300 ?
828 0285 74 BB JE      STO_CX                      ; MUST BE 1.2MB DRIVE
829 0287 EB AC JMP     SHORT PARM144             ; ELSE, IT IS 1.44MB DRIVE
830
831 0289 DISK_PARMS ENDP
832
833 ;-----
834 ; DISK_TYPE (AH = 15H)
835 ; THIS ROUTINE RETURNS THE TYPE OF MEDIA INSTALLED.
836 ; ON ENTRY: DI = DRIVE #
837 ; ON EXIT: AH = DRIVE TYPE, CY=0
838 ;-----
839
840 0289 DISK_TYPE: PROC NEAR
841 0289 E8 040F R CALL     XLAT_NEW                      ; TRANSLATE STATE TO PRESENT ARCH.
842 028C 8A 85 0090 R MOV     AL,*DSK_STATE[DI]          ; GET PRESENT STATE INFORMATION
843 0290 0A C0 OR      AL,AL                      ; CHECK FOR NO DRIVE
844 0292 74 13 JZ      NO_DRV                     ; NO CHANGE LINE FOR 40 TRACK DRIVE
845 0294 B4 01 MOV     AH,NOCHGLN              ; IS THIS DRIVE AN 80 TRACK DRIVE?
846 0296 A8 01 TEST    AL,TRK_CAPA              ; IF NO JUMP
847 0298 74 02 JZ      DT_BACK                    ; CHANGE LINE FOR 80 TRACK DRIVE
848 029A B4 02 MOV     AH,CHGLN
849
850 029C DT_BACK:
851 029C 50 PUSH     AX                      ; SAVE RETURN VALUE
852 029D E8 0435 R CALL     XLAT_OLD                      ; TRANSLATE STATE TO COMPATIBLE MODE
853 02A0 58 POP      AX                      ; RESTORE RETURN VALUE
854 02A1 F8 CLC                                     ; NO ERROR
855 02A2 8B DE MOV     BX,SI                      ; GET SAVED AL TO BL
856 02A4 8A C3 MOV     AL,BL                      ; PUT BACK FOR RETURN
857 02A6 C3 RET
858 02A7
859 02A7 32 E4 XOR     AH,AH                      ; NO DRIVE PRESENT OR UNKNOWN
860 02A9 EB F1 JMP     SHORT DT_BACK
861 02AB DISK_TYPE ENDP
862
863 ;-----
864 ; DISK_CHANGE (AH = 16H)
865 ; THIS ROUTINE RETURNS THE STATE OF THE DISK CHANGE LINE.
866 ; ON ENTRY: DI = DRIVE #
867 ; ON EXIT: AH = *DSKETTE_STATUS
868 ; 00 - DISK CHANGE LINE INACTIVE, CY = 0
869 ; 06 - DISK CHANGE LINE ACTIVE, CY = 1
870 ;-----
871
872 02AB DISK_CHANGE: PROC NEAR
873 02AB E8 040F R CALL     XLAT_NEW                      ; TRANSLATE STATE TO PRESENT ARCH.
874 02AE 8A 85 0090 R MOV     AL,*DSK_STATE[DI]          ; GET MEDIA STATE INFORMATION
875 02B2 0A C0 OR      AL,AL                      ; DRIVE PRESENT ?
876 02B4 74 19 JZ      DC_NON                     ; JUMP IF NO DRIVE
877 02B6 A8 01 TEST    AL,TRK_CAPA              ; 80 TRACK DRIVE ?
878 02B8 74 05 JZ      SETIT                      ; IF SO, CHECK CHANGE LINE
879
880 02BA E8 0B28 R DC0: CALL     READ_DSKCHNG          ; GO CHECK STATE OF DISK CHANGE LINE
881 02BD 74 05 JZ      FINIS                      ; CHANGE LINE NOT ACTIVE
882
883 02BF C6 06 0041 R 06 SETIT: MOV     *DSKETTE_STATUS,MEDIA_CHANGE ; INDICATE MEDIA REMOVED
884
885 02C4 E8 0435 R FINIS: CALL     XLAT_OLD                      ; TRANSLATE STATE TO COMPATIBLE MODE
886 02C7 E8 0B54 R CALL     SETUP_END                    ; VARIOUS CLEANUPS
887 02CA 8B DE MOV     BX,SI                      ; GET SAVED AL TO BL
888 02CC 8A C3 MOV     AL,BL                      ; PUT BACK FOR RETURN
889 02CE C3 RET
890
891 02CF DC_NON:
892 02CF 80 0E 0041 R 80 OR      *DSKETTE_STATUS,TIME_OUT          ; SET TIMEOUT, NO DRIVE
893 02D4 EB EE JMP     SHORT FINIS
894 02D6 DISK_CHANGE ENDP
895
896 ;-----
897 ; FORMAT SET (AH = 17H)
898 ; THIS ROUTINE IS USED TO ESTABLISH THE TYPE OF
899 ; MEDIA TO BE USED FOR THE FOLLOWING FORMAT OPERATION.
900 ; ON ENTRY: SI LOW = DASD TYPE FOR FORMAT
901 ; DI = DRIVE #
902 ; ON EXIT: *DSKETTE_STATUS REFLECTS STATUS
903 ; AH = *DSKETTE_STATUS
904 ; CY = 1 IF ERROR
905 ;-----
906
907

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908 0206      PROC    NEAR
909 0206 E8 040F R    CALL    XLAT_NEW      ; TRANSLATE STATE TO PRESENT ARCH.
910 0209 56          PUSH    SI             ; SAVE DASD TYPE
911 020A 8B C6       MOV     AX,SI         ; AH = ? , AL = DASD TYPE
912 020C 32 E4       XOR     AH,AH        ; AH = 0 , AL = DASD TYPE
913 020E 8B F0       MOV     SI,AX        ; SI = DASD TYPE
914 0210 80 A5 0090 R OF  AND     @DSK_STATE[DI],NOT MED_DET+DBL_STEP+RATE_MSK ; CLEAR STATE
915 0215 4E          DEC     SI             ; CHECK FOR 320/360K MEDIA & DRIVE
916 0216 75 07       JNZ     NOT_320      ; BYPASS IF NOT
917 0218 80 8D 0090 R 90 OR      @DSK_STATE[DI],MED_DET+RATE_250 ; SET TO 320/360
918 021D EB 37       JMP     SHORT S0
919
920 021F          NOT_320:
921 021F E8 05E9 R    CALL    MED_CHANGE     ; CHECK FOR TIME_OUT
922 0222 F0 3E 0041 R 80 CMP     @DSKETTE_STATUS,TIME_OUT
923 0227 74 2D       JZ      S0             ; IF TIME OUT TELL CALLER
924
925 022F 9 4E        S3:   DEC     SI             ; CHECK FOR 320/360K IN 1.2M DRIVE
926 023A 75 07       JNZ     NOT_320_12   ; BYPASS IF NOT
927 023C 80 8D 0090 R 70 OR      @DSK_STATE[DI],MED_DET+DBL_STEP+RATE_300 ; SET STATE
928 0301 EB 23       JMP     SHORT S0
929
930 0303          NOT_320_12:
931 0303 4E          DEC     SI             ; CHECK FOR 1.2M MEDIA IN 1.2M DRIVE
932 0304 75 07       JNZ     NOT_12       ; BYPASS IF NOT
933 0306 80 8D 0090 R 10 OR      @DSK_STATE[DI],MED_DET+RATE_500 ; SET STATE VARIABLE
934 030B EB 19       JMP     SHORT S0      ; RETURN TO CALLER
935
936 030D          NOT_12:
937 030D 4E          DEC     SI             ; CHECK FOR SET DASD TYPE 04
938 030E 75 20       JNZ     FS_ERR       ; BAD COMMAND EXIT IF NOT VALID TYPE
939
940 0310 F6 85 0090 R 04 TEST    @DSK_STATE[DI],DRV_DET      ; DRIVE DETERMINED ?
941 0315 74 09       JZ      ASSUME        ; IF STILL NOT DETERMINED ASSUME
942 0317 80 50       MOV     AL,MED_DET+RATE_300
943 0319 F6 85 0090 R 02 TEST    @DSK_STATE[DI],FMT_CAPA    ; MULTIPLE FORMAT CAPABILITY ?
944 031E 75 02       JNZ     OR_IT_IN     ; IF 1.2 M THEN DATA RATE 300
945
946 0320          ASSUME:
947 0320 80 90       MOV     AL,MED_DET+RATE_250 ; SET UP
948
949 0322          OR_IT_IN:
950 0322 08 85 0090 R OR      @DSK_STATE[DI],AL ; OR IN THE CORRECT STATE
951
952 0326 E8 0435 R    S0:   CALL    XLAT_OLD      ; TRANSLATE STATE TO COMPATIBLE MODE
953 0329 E8 0854 R    CALL    SETUP_END    ; VARIOUS CLEANUPS
954 033C 58          POP     AL,BL         ; GET SAVED AL TO BL
955 032D 8A C3       MOV     AL,BL         ; PUT BACK FOR RETURN
956 032F C3         RET
957
958 0330          FS_ERR:
959 0330 C6 06 0041 R 01 MOV     @DSKETTE_STATUS,BAD_CMD ; UNKNOWN STATE,BAD COMMAND
960 0335 EB EF       JMP     SHORT S0
961
962 0337          FORMAT_SET    ENDP
963
964 -----
965 ; SET_MEDIA (AH = 18H)
966 ; THIS ROUTINE SETS THE TYPE OF MEDIA AND DATA RATE
967 ; TO BE USED FOR THE FOLLOWING FORMAT OPERATION.
968 ;
969 ; ON ENTRY:
970 ; [BP] = SECTOR PER TRACK
971 ; [BP+1] = TRACK #
972 ; DI = DRIVE #
973 ; ON EXIT:
974 ; @DSKETTE_STATUS REFLECTS STATUS
975 ; IF NO ERROR:
976 ; AH = 0
977 ; CY = 0
978 ; ES = SEGMENT OF MEDIA/DRIVE PARAMETER TABLE
979 ; DI/[BP+6] = OFFSET OF MEDIA/DRIVE PARAMETER TABLE
980 ; IF ERROR:
981 ; AH = @DSKETTE_STATUS
982 ; CY = 1
983 -----
984 0337          SET_MEDIA    PROC    NEAR
985 0337 E8 040F R    CALL    XLAT_NEW      ; TRANSLATE STATE TO PRESENT ARCH.
986 033A F6 85 0090 R 01 TEST    @DSK_STATE[DI],TRK_CAPA    ; CHECK FOR CHANGE LINE AVAILABLE
987 033F 74 0F       JZ      SM_CMOS      ; JUMP IF 40 TRACK DRIVE
988 0341 E8 05E9 R    CALL    MED_CHANGE     ; RESET CHANGE LINE
989 0344 80 3E 0041 R 80 CMP     @DSKETTE_STATUS,TIME_OUT ; IF TIME OUT TELL CALLER
990 0349 74 66       JE      SM_RTN       ; SET STATE
991 0350          SM_CMOS:
992 0350 80 8E 008C R MOV     CMOS_TYPE ; RETURN DRIVE TYPE IN (AL)
993 0353 72 38       JC      MD_NOT_FND   ; ERROR IN CMOS
994 0355 0A C0       OR      AL,AL        ; TEST FOR NO DRIVE
995 0357 74 58       JZ      SM_RTN       ; RETURN IF SO
996 0359 E8 03B8 R    CALL    DR_TYPE_CHECK    ; RTN CS:BX = MEDIA/DRIVE PARAM TBL
997 035C 72 2F       JC      MD_NOT_FND   ; TYPE NOT IN TABLE (BAD CMOS)
998 035E 57          PUSH    DI           ; SAVE REG.
999 035F 33 DB       XOR     BX,BX        ; BX = INDEX TO DR_TYPE TABLE
1000 0361 B9 0006     MOV     CX,DR_CNT    ; CX = LOOP COUNT
1001 0364
1002 0364 2E: 8A A7 0000 R DR_SEARCH: MOV     AH,CS:DR_TYPE[BX] ; GET DRIVE TYPE
1003 0369 80 E4 7F    AND     AH,BIT7OFF    ; MASK OUT MSB
1004 036C 3A C4       CMP     AL,AH        ; DRIVE TYPE MATCH ?
1005 036E 75 17       JNE     NXT_MD       ; NO, CHECK NEXT DRIVE TYPE
1006
1007 0370 2E: 8B BF 0001 R MOV     DI,CS:WORD PTR DR_TYPE[BX+1] ; DI = MEDIA/DRIVE PARAMETER TABLE
1008
1009 0375 2E: 8A 65 04  MOV     AH,CS:[DI].MD_SEC_TRK ; GET SECTOR/TRACK
1010 0379 38 66 00     CMP     [BP],AH        ; MATCH ?
1011 037C 75 09       JNE     NXT_MD       ; NO, CHECK NEXT MEDIA
1012 037E 2E: 8A 65 0B MOV     AH,CS:[DI].MD_MAX_TRK ; GET MAX. TRACK #
1013 0382 38 66 01     CMP     [BP+1],AH      ; MATCH ?
1014 0385 74 0D       JE      MD_FND       ; YES, GO GET RATE
1015 0387
1016 0387 82 C3 03     NXT_MD:  ADD     BX,3           ; CHECK NEXT DRIVE TYPE
1017 038A E2 DB       LOOP    DR_SEARCH    ; DR_SEARCH
1018 038C 5F          POP     DI           ; RESTORE REG.
1019 038D
1020 038D C6 06 0041 R 0C MD_NOT_FND: MOV     @DSKETTE_STATUS,MED_NOT_FND ; ERROR, MEDIA TYPE NOT FOUND
1021 0392 EB 1D       JMP     SHORT SM_RTN    ; RETURN

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1022
1023 0394 MD_FND: MOV AL,CS:[DI],MD_RATE ; GET RATE
1024 0394 2E: 8A 45 0C OR AL,RATE_300 ; DOUBLE STEP REQUIRED FOR RATE 300
1025 0398 3C 40 CMP AL,RATE_300
1026 039A 75 02 JNE MD_SET ; RESTORE REG.
1027 039C 0C 20 OR AL,DBL_STEP
1028 039E MD_SET: MOV [BP+6],DI ; SAVE TABLE POINTER IN STACK
1029 039E 89 7E 06 OR AL,MD_DET ; SET MEDIA ESTABLISHED
1030 03A1 0C 10 POP DI ; RESTORE REG.
1031 03A3 5F POP DI
1032 03A4 80 A5 0090 R OF AND *DSK_STATE[DI],NOT MD_DET+DBL_STEP+RATE_MSK ; CLEAR STATE
1033 03A9 08 85 0090 R OR *DSK_STATE[DI],AL ; SET STATE
1034 03AD 8C C8 MOV AX,C3 ; SEGMENT MEDIA/DRIVE PARAMETER TABLE
1035 03AF 8E C0 MOV ES,AX ; ES IS SEGMENT OF TABLE
1036 03B1 SM_RTN: CALL XLAT_OLD ; TRANSLATE STATE TO COMPATIBLE MODE
1037 03B1 E8 0435 R CALL SETUP_END ; VARIOUS CLEANUPS
1038 03B4 E8 0854 R RET
1039 03B7 C3
1040 03B8 SET_MEDIA ENDP
1041
1042 -----
1043 ; DR_TYPE_CHECK
1044 ; CHECK IF THE GIVEN DRIVE TYPE IN REGISTER (AL)
1045 ; IS SUPPORTED IN BIOS DRIVE TYPE TABLE
1046 ; ON ENTRY:
1047 ; AL = DRIVE TYPE
1048 ; ON EXIT:
1049 ; CS = SEGMENT OF MEDIA/DRIVE PARAMETER TABLE (CODE)
1050 ; CY = 0 DRIVE TYPE SUPPORTED
1051 ; BX = OFFSET TO MEDIA/DRIVE PARAMETER TABLE
1052 ; CX = DRIVE TYPE NOT SUPPORTED
1053 ; REGISTERS ALTERED: BX
1054 -----
1055 03B8 DR_TYPE_CHECK PROC NEAR
1056 03B8 50 PUSH AX
1057 03B9 51 PUSH CX
1058 03BA 33 DB XOR BX,BX ; BX = INDEX TO DR_TYPE TABLE
1059 03BC B9 0006 MOV CX,DR_CNT ; CX = LOOP COUNT
1060 03BF TYPE_CHK: MOV AH,CS:DR_TYPE[BX] ; GET DRIVE TYPE
1061 03BF 2E: 8A AT 0000 R CMP AL,AH ; DRIVE TYPE MATCH ?
1062 03C4 3A C4 JE DR_TYPE_VALID ; YES, RETURN WITH CARRY RESET
1063 03C6 74 08 JZ ADD ; CHECK NEXT DRIVE TYPE
1064 03C8 83 C3 03 ADD BX,BX
1065 03CB E2 F2 LOOP TYPE_CHK
1066 03CD F9 STC ; DRIVE TYPE NOT FOUND IN TABLE
1067 03CE EB 05 JMP SHORT TYPE_RTN
1068 03D0 DR_TYPE_VALID: MOV BX,CS:WORD PTR DR_TYPE[BX+1] ; BX = MEDIA TABLE
1069 03D0 2E: 8B 9F 0001 R
1070 03D5 TYPE_RTN: MOV CX
1071 03D5 59 POP AX
1072 03D6 58 POP AX
1073 03D7 C3 RET
1074 03D8 DR_TYPE_CHECK ENDP
1075
1076 -----
1077 ; SEND_SPEC
1078 ; SEND THE SPECIFY COMMAND TO CONTROLLER USING DATA FROM
1079 ; THE DRIVE PARAMETER TABLE POINTED BY *DISK_POINTER
1080 ; ON ENTRY: *DISK_POINTER = DRIVE PARAMETER TABLE
1081 ; ON EXIT: NONE
1082 ; REGISTERS ALTERED: CX, DX
1083 -----
1084 03D8 SEND_SPEC PROC NEAR
1085 03D8 50 PUSH AX ; SAVE AX
1086 03D9 B8 03F3 R MOV AX,OFFSET SPECBAC ; LOAD ERROR ADDRESS
1087 03DC 50 PUSH AX ; PUSH NEC_OUT ERROR RETURN
1088 03DD B4 03 MOV AH,03H ; SPECIFY COMMAND
1089 03DF E8 09F8 R CALL NEC_OUTPUT ; OUTPUT THE COMMAND
1090 03E2 2A D2 SUB DL,DL ; FIRST SPECIFY BYTE
1091 03E4 E8 0905 R CALL GET_PARM ; GET PARAMETER TO AH
1092 03E7 E8 09F8 R CALL NEC_OUTPUT ; OUTPUT THE COMMAND
1093 03EA B2 01 MOV DL,1 ; SECOND SPECIFY BYTE
1094 03EC E8 0905 R CALL GET_PARM ; GET PARAMETER TO AH
1095 03EF E8 09F8 R CALL NEC_OUTPUT ; OUTPUT THE COMMAND
1096 03F2 58 POP AX ; POP ERROR RETURN
1097 03F3 SPECBAC: POP AX
1098 03F3 58 POP AX ; RESTORE ORIGINAL AX VALUE
1099 03F4 C3 RET
1100 03F5 SEND_SPEC ENDP
1101
1102 -----
1103 ; SEND_SPEC MD
1104 ; SEND THE SPECIFY COMMAND TO CONTROLLER USING DATA FROM
1105 ; THE MEDIA/DRIVE PARAMETER TABLE POINTED BY (CS:BX)
1106 ; ON ENTRY: CS:BX = MEDIA/DRIVE PARAMETER TABLE
1107 ; ON EXIT: NONE
1108 ; REGISTERS ALTERED: AX
1109 -----
1110 03F5 SEND_SPEC MD PROC NEAR
1111 03F5 50 PUSH AX ; SAVE RATE DATA
1112 03F6 B8 040D R MOV AX,OFFSET SPEC_ESBAC ; LOAD ERROR ADDRESS
1113 03F9 50 PUSH AX ; PUSH NEC_OUT ERROR RETURN
1114 03FA B4 03 MOV AH,03H ; SPECIFY COMMAND
1115 03FC E8 09F8 R CALL NEC_OUTPUT ; OUTPUT THE COMMAND
1116 03FF 2E: 8A 27 MOV AH,CS:[BX],MD_SPEC1 ; GET 1ST SPECIFY BYTE
1117 0402 E8 09F8 R CALL NEC_OUTPUT ; OUTPUT THE COMMAND
1118 0405 2E: 8A 67 01 MOV AH,CS:[BX],MD_SPEC2 ; GET SECOND SPECIFY BYTE
1119 0409 E8 09F8 R CALL NEC_OUTPUT ; OUTPUT THE COMMAND
1120 040C 58 POP AX ; POP ERROR RETURN
1121 040D SPEC_ESBAC: POP AX
1122 040D 58 POP AX ; RESTORE RATE
1123 040E C3 RET
1124 040F SEND_SPEC_MD ENDP

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1125 PAGE
1126 -----
1127 ; XLAT_NEW
1128 ; TRANSLATES DISKETTE STATE LOCATIONS FROM COMPATIBLE
1129 ; MODE TO NEW ARCHITECTURE.
1130 ;
1131 ; ON ENTRY: DI : DRIVE
1132 -----
1133 XLAT_NEW PROC NEAR
1134 040F 83 FF 01 ; VALID DRIVE ?
1135 0412 77 1C ; IF INVALID BACK
1136 0414 80 80 0090 R 00 ; NO DRIVE ?
1137 0419 74 16 ; IF NO DRIVE ATTEMPT DETERMINE
1138 041B 8B CF ; CX = DRIVE NUMBER
1139 041D C0 E1 02 ; CL = SHIFT COUNT, A=0, B=4
1140 0420 A0 008F R ; DRIVE INFORMATION
1141 0423 D2 C8 ; TO LOW Nibble
1142 0425 24 07 ; AL,DRV_DET+FMT_CAPA+TRK_CAPA ; KEEP DRIVE BITS
1143 0427 80 A5 0090 R F8 ; *DSK_STATE[DI],NOT DRV_DET+FMT_CAPA+TRK_CAPA
1144 042C 08 65 0090 R ; *DSK_STATE[DI],AL ; UPDATE DRIVE STATE
1145 0430
1146 0430 C3
1147
1148 0431
1149 0431 E8 0B32 R ; DO_DET: CALL DRIVE_DET ; TRY TO DETERMINE
1150 0434 C3 ; RET
1151
1152 0435
1153 XLAT_NEW ENDP
1154 -----
1155 ; XLAT_OLD
1156 ; TRANSLATES DISKETTE STATE LOCATIONS FROM NEW
1157 ; ARCHITECTURE TO COMPATIBLE MODE.
1158 ;
1159 ; ON ENTRY: DI : DRIVE
1160 -----
1161 XLAT_OLD PROC NEAR
1162 0435 83 FF 01 ; VALID DRIVE ?
1163 0438 77 73 ; IF INVALID BACK
1164 043F 74 6C ; IF NO DRIVE TRANSLATE DONE
1165
1166 ;----- TEST FOR SAVED DRIVE INFORMATION ALREADY SET
1167
1168 0441 8B CF ; CX,DI ; CX = DRIVE NUMBER
1169 0443 C0 E1 02 ; CL,2 ; CL = SHIFT COUNT, A=0, B=4
1170 0446 B4 02 ; MOV AH,FMT_CAPA ; LOAD MULTI DATA RATE BIT MASK
1171 0448 D2 CC ; ROR AH,CL ; ROTATE BY MASK
1172 044A 84 26 008F R ; TEST *HF_CNTRL,AH ; MULTI-DATA RATE DETERMINED ?
1173 044E 75 16 ; JNZ SAVE_SET ; IF 50, NO NEED TO RE-SAVE
1174
1175 ;----- ERASE DRIVE BITS IN *HF_CNTRL FOR THIS DRIVE
1176
1177 0450 B4 07 ; MOV AH,DRV_DET+FMT_CAPA+TRK_CAPA ; MASK TO KEEP
1178 0452 D2 CC ; ROR AH,CL ; FIX MASK TO KEEP
1179 0454 F6 04 ; NOT AH ; TRANSLATE MASK
1180 0456 20 26 008F R ; AND *HF_CNTRL,AH ; KEEP BITS FROM OTHER DRIVE INTACT
1181
1182 ;----- ACCESS CURRENT DRIVE BITS AND STORE IN *HF_CNTRL
1183
1184 045A 8A 85 0090 R ; MOV AL,*DSK_STATE[DI] ; ACCESS STATE
1185 045E 24 07 ; AL,DRV_DET+FMT_CAPA+TRK_CAPA ; KEEP DRIVE BITS
1186 0460 D2 C8 ; ROR AL,CL ; FIX FOR THIS DRIVE
1187 0462 08 06 008F R ; OR *HF_CNTRL,AL ; UPDATE SAVED DRIVE STATE
1188
1189 ;----- TRANSLATE TO COMPATIBILITY MODE
1190
1191 0466
1192 0466 8A A5 0090 R ; SAVE_SET: MOV AH,*DSK_STATE[DI] ; ACCESS STATE
1193 046A 8A FC ; MOV BH,AH ; TO BH FOR LATER
1194 046C 80 E4 C0 ; AND AH,RATE_MSK ; KEEP ONLY RATE
1195 046F 80 FC 00 ; CMP AH,RATE_500 ; RATE 500 ?
1196 0472 74 10 ; JZ CHK_144 ; YES, 1,2/1,2 OR 1,44/1,44
1197 0474 80 01 ; MOV AL,M3DIU ; AL = 360 IN 1,2 UNESTABLISHED
1198 0476 80 FC 40 ; CMP AH,RATE_300 ; RATE 300 ?
1199 0479 75 16 ; JNZ CHK_250 ; NO, 360/360 ,720/720 OR 720/1,44
1200 047B F6 C7 20 ; TEST BH,DEL_STEP ; YES, DOUBLE STEP ?
1201 047E 75 1D ; JNZ TST_DET ; YES, MUST BE 360 IN 1,2
1202
1203 0480
1204 0480 B0 07 ; UNKN0: MOV AL,MED_UNK ; 'NONE OF THE ABOVE'
1205 0482 EB 20 ; JMP SHORT AL_SET ; PROCESS COMPLETE
1206
1207 0484
1208 0484 E8 08EC R ; CHK_144: CALL CMOS_TYPE ; RETURN DRIVE TYPE IN (AL)
1209 0487 72 F7 ; JC UNKN0 ; ERROR, SET 'NONE OF THE ABOVE'
1210 0489 3C 02 ; CMP AL,02 ; 1.2MB DRIVE ?
1211 048B 75 F3 ; JNE UNKN0 ; 1.2MB, GO SET 'NONE OF THE ABOVE'
1212 048D 80 02 ; MOV AL,MIDIU ; AL = 1,2 IN 1,2 UNESTABLISHED
1213 048F EB 0C ; JMP SHORT TST_DET
1214
1215 0491
1216 0491 B0 00 ; CHK_250: MOV AL,M3DSU ; AL = 360 IN 360 UNESTABLISHED
1217 0493 80 FC 80 ; CMP AH,RATE_250 ; RATE 250 ?
1218 0496 75 E8 ; JNZ UNKN0 ; IF 50 FALL THRU
1219 0498 F6 C7 01 ; TEST BH,TRK_CAPA ; NO TRACK CAPABILITY ?
1220 049B 75 E3 ; JNZ UNKN0 ; IF 50 JUMP, FALL THRU TEST DET
1221
1222 049D
1223 049D F6 C7 10 ; TST_DET: TEST BH,MED_DET ; DETERMINED ?
1224 04A0 74 02 ; JZ AL_SET ; IF NOT THEN SET
1225 04A2 04 03 ; ADD AL,3 ; MAKE DETERMINED/ESTABLISHED
1226
1227 04A4
1228 04A4 80 A5 0090 R F8 ; AL_SET: AND *DSK_STATE[DI],NOT DRV_DET+FMT_CAPA+TRK_CAPA ; CLEAR DRIVE
1229 04A9 08 65 0090 R ; OR *DSK_STATE[DI],AL ; REPLACE WITH COMPATIBLE MODE
1230 04AD
1231 04AD C3 ; XO_OUT: RET
1232 04AE ; XLAT_OLD ENDP

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PAGE
1233
1234
1235
1236      RD_WR_VF
1237      COMMON READ, WRITE AND VERIFY;
1238      MAIN LOOP FOR STATE RETRIES.
1239
1240      ON ENTRY:      AH: READ/WRITE/VERIFY NEC PARAMETER
1241                  AL: READ/WRITE/VERIFY DMA PARAMETER
1242
1243      ON EXIT:      *DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION
1244
1245      RD_WR_VF      PROC    NEAR
1246      04AE 50      PUSH    AX          ; SAVE DMA, NEC PARAMETERS
1247      04AF E8 040F R CALL    XLAT NEW          ; TRANSLATE STATE TO PRESENT ARCH.
1248      04B0 E8 056A R CALL    INITI_1          ; INITIALIZE START AND END RATE
1249      04B5 58      POP     AX          ; RESTORE READ/WRITE/VERIFY
1250
1251      DO_AGAIN:
1252      04B6 50      PUSH    AX          ; SAVE READ/WRITE/VERIFY PARAMETER
1253      04B7 E8 05E9 R CALL    MED_CHANGE      ; MEDIA CHANGE AND RESET IF CHANGED
1254      04BA 58      POP     AX          ; RESTORE READ/WRITE/VERIFY
1255      04BB 73 03   JC      RWV_END    ; MEDIA CHANGE ERROR OR TIME-OUT
1256      04BD E9 055B R JNC     RWV
1257      04C0      JMP     RWV_END
1258
1259      RWV:      PUSH    AX          ; SAVE READ/WRITE/VERIFY PARAMETER
1260      04C1 8A B5 0090 R MOV     DH, *DSK_STATE[D1] ; GET RATE STATE OF THIS DRIVE
1261      04C5 80 E6 C0 AND     DH, RATE_MSK      ; KEEP ONLY RATE
1262      04CB E8 08EC R CALL    CMOS_TYPE        ; RETURN DRIVE TYPE IN (AL)
1263      04CB 72 46   JC      RWV_ASSUME ; ERROR IN CMOS
1264      04CD 3C 01   CMP     AL, 1      ; 40 TRACK DRIVE?
1265      04CF 75 0B   JNE     RWV_1      ; NO, BYPASS CMOS VALIDITY CHECK
1266      04D1 F6 85 0090 R 0I TEST    *DSK_STATE[D1], TRK_CAPA ; CHECK FOR 40 TRACK DRIVE
1267      04D6 74 0F   JZ      RWV_2      ; YES, CMOS IS CORRECT
1268      04D8 B0 02   MOV     AL, 2      ; CHANGE TO 1.2 M
1269      04DA E8 0B JMP     SHORT RWV_2 ; CONTINUE
1270
1271      RWV_1:      JMP     RWV_2      ; NO DRIVE SPECIFIED, CONTINUE
1272      04DC 72 09   JB      RWV_2      ; IS IT REALLY 40 TRACK?
1273      04DE F6 85 0090 R 0I TEST    *DSK_STATE[D1], TRK_CAPA ;
1274      04E3 74 08   JNZ     RWV_2      ; IT'S 40 TRACK, FIX CMOS VALUE
1275      04E7      MOV     AL, 1
1276
1277      RWV_2:      OR      AL, AL      ; TEST FOR NO DRIVE
1278      04E9 74 28   JZ      RWV_ASSUME ; ASSUME TYPE, USE MAX TRACK
1279      04EB E8 03B8 R CALL    DR_TYPE_CHECK    ; RTN CS:BX = MEDIA/DRIVE PARAM TBL
1280      04EE 72 23   JC      RWV_ASSUME ; TYPE NOT IN TABLE (BAD CMOS)
1281
1282      ;--- SEARCH FOR MEDIA/DRIVE PARAMETER TABLE
1283
1284      04F0 57      PUSH    DI          ; SAVE DRIVE #
1285      04F1 33 DB   XOR     BX, BX      ; BX = INDEX TO DR_TYPE TABLE
1286      04F3 B9 0006 MOV     CX, DR_CNT      ; CX = LOOP COUNT
1287
1288      RWV_DR_SEARCH:
1289      04F6 2E: 8A A7 0000 R MOV     AH, CS:DR_TYPE[BX] ; GET DRIVE TYPE
1290      04FB 80 E4 7F AND     AH, BITTOFF     ; MASK OUT MSB
1291      04FE 3A C4   CMP     AL, AH      ; DRIVE TYPE MATCH ?
1292      0500 75 0B   JNE     RWV_NXT_MD ; NO, CHECK NEXT DRIVE TYPE
1293
1294      RWV_DR_FND:
1295      0502 2E: 8B BF 0001 R MOV     DI, WORD PTR CS:DR_TYPE[BX+1] ; DI = MEDIA/DRIVE PARAMETER TABLE
1296
1297      RWV_MD_SEARCH:
1298      0507      CMP     DH, CS:[D1].MD_RATE ; MATCH ?
1299      0508 7E 1A   JBE     RWV_MD_FND    ; YES, GO GET 1ST SPECIFY BYTE
1300
1301      RWV_NXT_MD:
1302      050D      ADD     BX, 3          ; CHECK NEXT DRIVE TYPE
1303      050E 01 E4   LOOP    RWV_DR_SEARCH ;
1304      0512 5F      POP     DI          ; RESTORE DRIVE #
1305
1306      ;--- ASSUME PRIMARY DRIVE IS INSTALLED AS SHIPPED
1307
1308      RWV_ASSUME:
1309      0513      MOV     BX, OFFSET MD_TBL1 ; POINT TO 40 TK 250 KBS
1310      0514      TEST    *DSK_STATE[D1], TRK_CAPA ; TEST FOR 80 TRACK
1311      0515 74 09   JZ      RWV_MD_FND    ; MUST BE 40 TRACK
1312      0516 5D B8 002C R MOV     BX, OFFSET MD_TBL3 ; POINT TO 80 TK 500 KBS
1313      0517 5D B8 002C R MOV     BX, OFFSET MD_TBL3 ; GO SET SPECIFY PARAMETERS
1314
1315      ;--- CS:BX POINTS TO MEDIA/DRIVE PARAMETER TABLE
1316
1317      RWV_MD_FND:
1318      0523      MOV     BX, DI          ; BX = MEDIA/DRIVE PARAMETER TABLE
1319      0524 5F      POP     DI          ; RESTORE DRIVE #
1320
1321      ;--- SEND THE SPECIFY COMMAND TO THE CONTROLLER
1322
1323      0526      CALL    SEND_SPEC_MD ; SEND SPEC MD
1324      0527      CALL    CHK_LASRATE   ; ZF=1 ATTEMPT RATE IS SAME AS LAST RATE
1325      0528 74 03   JZ      RWV_DBL     ; YES, SKIP SEND RATE COMMAND
1326      0529      CALL    SEND_RATE    ; SEND DATA RATE TO NEC
1327
1328      RWV_DBL:
1329      0531      PUSH    BX          ; SAVE MEDIA/DRIVE PARAM ADDRESS
1330      0532      CALL    SETUP_DBL     ; CHECK FOR DOUBLE STEP
1331      0533      POP     BX          ; RESTORE ADDRESS
1332      0534 72 1A   JC      CHK_RET     ; ERROR FROM READ ID, POSSIBLE RETRY
1333      0535 58      POP     AX          ; RESTORE NEC/DMA COMMAND
1334      0536 50      PUSH    AX          ; SAVE NEC COMMAND
1335      0537      PUSH    BX          ; SAVE MEDIA/DRIVE PARAM ADDRESS
1336      0538      CALL    DMA_SETUP     ; SET UP THE DMA
1337      0539 58      POP     AX          ; RESTORE ADDRESS
1338      053A 58      POP     AX          ; RESTORE NEC COMMAND
1339      053B 72 1F   JC      RWV_BAC     ; CHECK FOR DMA BOUNDARY ERROR
1340      053C 50      PUSH    BX          ; SAVE NEC COMMAND
1341      053D 50      PUSH    BX          ; SAVE MEDIA/DRIVE PARAM ADDRESS
1342      053E      CALL    NEC_INIT      ; INITIALIZE NEC
1343      053F 58      POP     BX          ; RESTORE ADDRESS
1344      0540 72 08   JC      CHK_RET     ; ERROR - EXIT
1345      0541 58      POP     AX          ; OP CODE COMMON TO READ/WRITE/VERIFY
1346      0542 72 03   JC      RWV_COM     ; ERROR - EXIT
1347      0543 58      POP     AX          ; TERMINATE, GET STATUS, ETC.
1348      0544      CALL    NEC_TERM
1349
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1348 0552
1349 0552 E8 07E5 R      CHK_RET: CALL RETRY ; CHECK FOR SETUP RETRY
1350 0555 58             POP AX ; RESTORE READ/WRITE/VERIFY PARAMETER
1351 0556 73 03          JNC RWF_END ; CY = 0 NO RETRY
1352 0558 E9 0486 R      JMP DO_AGAIN ; CY = 1 MEANS RETRY
1353
1354 055B
1355 055B E8 07AD R      RWF_END: CALL DSTATE ; ESTABLISH STATE IF SUCCESSFUL
1356 055E E8 0827 R      CALL NUM_TRANS ; AL = NUMBER TRANSFERRED
1357
1358 0561
1359 0561 50             RWF_BAC: PUSH AX ; BAD DMA ERROR ENTRY
1360 0562 E8 0436 R      CALL XLAT_OLD ; SAVE NUMBER TRANSFERRED
1361 0565 58             POP AX ; TRANSLATE STATE TO COMPATIBLE MODE
1362 0566 E8 0854 R      CALL SETUP_END ; RESTORE NUMBER TRANSFERRED
1363 0569 C3             RET ; VARIOUS CLEANUPS
1364 056A
1365
1366
1367
1368 056A
1369 056A F6 85 0090 R 10 ; SETUP_STATE: INITIALIZES START AND END RATES.
1370 056F 75 29          JNZ TEST ; MEDIA DETERMINED ?
1371 0571 B8 0040          MOV AX,RATE_500*H*RATE_300 ; NO STATES IF DETERMINED
1372 0574 F6 85 0090 R 04 ; TEST ; AH = START RATE, AL = END RATE
1373 0579 74 0A          JZ AX_SET ; DRIVE ?
1374 057B F6 85 0090 R 02 ; TEST ; DO NOT KNOW DRIVE
1375 0580 75 03          JNZ AX_SET ; MULTI-RATE ?
1376 0582 B8 8080          MOV AX,RATE_250*X ; JUMP IF YES
1377 ; START & END RATE = 250 FOR 360 DRIVE
1378 0585
1379 0585 80 A5 0090 R 1F ; AX_SET: AND ; *DSK_STATE[D1],NOT RATE_MSK+DBL_STEP 1: TURN OFF THE RATE
1380 058A 88 A5 0090 R ; AND ; *RATE_FIRST TO TRY
1381 058E 80 26 008B R F3 ; AND ; *LASTRATE,NOT STRT_MSK ; ERASE LAST TO TRY RATE BITS
1382 0593 C0 C8 04 ; ROR AL,4 ; TO OPERATION LAST RATE LOCATION
1383 0596 08 06 008B R ; OR ; *LASTRATE,AL ; LAST RATE
1384 059A
1385 059A C3             JIC: RET
1386 059B
1387
1388
1389
1390 059B
1391 059B F6 85 0090 R 10 ; FMT_INIT: ESTABLISH STATE IF UNESTABLISHED AT FORMAT TIME.
1392 05A0 75 42          JNZ F1_OUT ; IS MEDIA ESTABLISHED
1393 05A2 E8 08EC R      CALL CMOS_TYPE ; IF SO RETURN
1394 05A5 72 3E          DEC CL_DRV ; RETURN DRIVE TYPE IN AL
1395 05A7 FE C8          DEC AL ; ERROR IN CMOS ASSUME NO DRIVE
1396 05A9 7B 3A          JS CL_DRV ; MAKE ZERO ORIGIN
1397 05AB 8A A5 0090 R ; MOV AH,*DSK_STATE[D1] ; NO DRIVE IF AL 0
1398 05AF 80 E4 0F          AND AL,NOT MED_DET+RATE_MSK ; AH = CURRENT STATE
1399 05B2 0A C0          OR AL,AL ; CHECK FOR 360
1400 05B4 75 05          JNZ N_360 ; IF 360 WILL BE 0
1401 05B6 80 CC 90          OR AH,MED_DET+RATE_250 ; ESTABLISH MEDIA
1402 05B9 EB 26          JMP SHORT SKP_STATE ; SKIP OTHER STATE PROCESSING
1403
1404 05BB
1405 05BB FE C8          DEC AL ; 1,2 M DRIVE
1406 05BD 75 0F          JNZ N_12 ; JUMP IF NOT
1407 05BF 80 CC 10          FI_RATE:OR AH,MED_DET+RATE_500 ; SET FORMAT RATE
1408 05C2 EB 1C          JMP SHORT SKP_STATE ; SKIP OTHER STATE PROCESSING
1409
1410 05C4
1411 05C4 FE C8          N_12: DEC AL ; CHECK FOR TYPE 3
1412 05C6 75 0F          JNZ N_720 ; JUMP IF NOT
1413 05C8 F6 C4 04          TEST AH,DRV_DET ; IS DRIVE DETERMINED
1414 05CB 74 10          JZ ISNT_12 ; TREAT AS NON 1,2 DRIVE
1415 05CD F6 C4 02          TEST AH,FMT_CAPA ; IS 1,2M
1416 05D0 74 0B          JZ ISNT_12 ; JUMP IF NOT
1417 05D2 80 CC 50          OR AH,MED_DET+RATE_300 ; AT RATE 300
1418 05D5 EB 09          JMP SHORT SKP_STATE ; CONTINUE
1419
1420 05D7
1421 05D7 FE C8          N_720: DEC AL ; CHECK FOR TYPE 4
1422 05D9 75 0A          JNZ CL_DRV ; NO DRIVE, CMOS BAD
1423 05DB EB E2          JMP SHORT FI_RATE
1424
1425 05DD
1426 05DD 80 CC 90          ISNT_12: OR AH,MED_DET+RATE_250 ; MUST BE RATE 250
1427
1428 05E0
1429 05E0 88 A5 0090 R ; SKP_STATE: MOV ; STORE AWAY
1430
1431 05E4
1432 05E4 C3             FI_OUT: RET
1433
1434 05E5
1435 05E5 32 E4          CL_DRV: XOR AH,AH ; CLEAR STATE
1436 05E7 EB F7          JMP SHORT SKP_STATE ; SAVE IT
1437 05E9
1438
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1445
1446 05E9
1447 05E9 E8 0B28 R      MED_CHANGE: PROC NEAR ; READ DISK CHANGE LINE STATE
1448 05EC 74 34          JZ MC_OUT ; BYPASS HANDLING DISK CHANGE LINE
1449 05EE 80 A5 0090 R EF AND ; *DSK_STATE[D1],NOT MED_DET ; CLEAR STATE FOR THIS DRIVE
1450
1451
1452
1453
1454
1455 05F3 8B CF          MOV CX,D1 ; CL = DRIVE #
1456 05F5 B0 01          MOV AL,1 ; MOTOR ON BIT MASK
1457 05F7 D2 E0          SHL AL,CL ; TO APPROPRIATE POSITION
1458 05F9 F6 D0          NOT AL ; KEEP ALL BUT MOTOR ON
1459 05FB FA          CLI ; NO INTERRUPTS
1460 05FC 20 06 003F R ; AND ; *MOTOR_STATUS,AL ; TURN MOTOR OFF INDICATOR

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1461 0600 FB          STI          ; INTERRUPTS ENABLED
1462 0601 E8 091A R   CALL        MOTOR_ON      ; TURN MOTOR ON
1463
1464
1465 ;----- THIS SEQUENCE OF SEEKS IS USED TO RESET DISKETTE CHANGE SIGNAL
1466 0604 E8 00E7 R   CALL        DISK_RESET      ; RESET NEC
1467 0607 B5 01      MOV         CH,0TH         ; MOVE TO CYLINDER 1
1468 0609 E8 0A24 R   CALL        SEEK          ; ISSUE SEEK
1469 060C 32 ED      XOR         CH,CH         ; MOVE TO CYLINDER 0
1470 060E E8 0A24 R   CALL        SEEK          ; ISSUE SEEK
1471 0611 C6 06 0041 R 06 MOV        @DSKETTE_STATUS,MEDIA_CHANGE ; STORE IN STATUS
1472
1473 0616 E8 0B28 R   OK1: CALL      READ_DSKCHNG   ; CHECK MEDIA CHANGED AGAIN
1474 0619 T4 05      JZ          OK2_             ; IF ACTIVE, NO DISKETTE, TIMEOUT
1475
1476 061B C6 06 0041 R 80 OK4: MOV        @DSKETTE_STATUS,TIME_OUT; TIMEOUT IF DRIVE EMPTY
1477
1478 0620 F9          OK2: STC                     ; MEDIA CHANGED, SET CY
1479 0621 C3          RET
1480 0622
1481 0622 F8          MC_OUT: CLC                 ; NO MEDIA CHANGED, CLEAR CY
1482 0623 C3          RET
1483 0624
1484 MED_CHANGE      ENDP
1485
1486 ; SEND_RATE
1487 ; SENDS DATA RATE COMMAND TO NEC
1488 ; ON ENTRY: DI = DRIVE #
1489 ; ON EXIT:   NONE
1490 ; REGISTERS ALTERED: DX
1491 0624
1492 SEND_RATE      PROC    NEAR
1493
1494 0624 50          PUSH     AX
1495 0625 80 26 008B R 3F AND        @LAstrate,NOT SEND_MSK ; SAVE REG.
1496 062A 8A 85 0090 R MOV        AL,@DSK_STATE[DI] ; ELSE CLEAR LAST RATE ATTEMPTED
1497 062E 24 C0      AND        AL,SEND_MSK ; GET RATE STATE OF THIS DRIVE
1498 0630 08 06 008B R OR         @LAstrate,AL ; KEEP ONLY RATE BITS
1499 0634 C0 C0 02   ROL        AL,2 ; SAVE NEW RATE FOR NEXT CHECK
1500 0637 BA 03F7    MOV        DX,03F7H ; MOVE TO BIT OUTPUT POSITIONS
1501 063A EE          OUT        DX,AL ; OUTPUT NEW DATA RATE
1502
1503 063B 58          POP      AX
1504 063D C3          RET
1505
1506 SEND_RATE      ENDP
1507
1508 ;-----
1509 ; CHK_LAstrate
1510 ; CHECK PREVIOUS DATA RATE SENT TO THE CONTROLLER.
1511 ; ON ENTRY: DI = DRIVE #
1512 ; ON EXIT:   ZF = 1 DATA RATE IS THE SAME AS LAST RATE SENT TO NEC
1513 ;           ZF = 0 DATA RATE IS DIFFERENT FROM LAST RATE
1514 ; REGISTERS ALTERED: NONE
1515
1516 063D
1517 063D 50          CHK_LAstrate PROC    NEAR
1518 063E 8A 26 008B R MOV        AH,@LAstrate ; SAVE REG
1519 0642 8A 85 0090 R MOV        AL,@DSK_STATE[DI] ; GET LAST DATA RATE SELECTED
1520 0646 25 C0C0    AND        AL,SEND_MSK*X ; GET RATE STATE OF THIS DRIVE
1521 0649 3A C4      CMP        AL,AH ; KEEP ONLY RATE BITS OF BOTH
1522                                     ; COMPARE TO PREVIOUSLY TRIED
1523 064B 58          POP      AX ; ZF = 1 RATE IS THE SAME
1524 064C C3          RET ; RESTORE REG.
1525 064D
1526 CHK_LAstrate   ENDP
1527
1528 SUBTTL (DSK3.ASM)

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1528                                     PAGE
1529 -----
1530 ; DMA_SETUP
1531 ; THIS ROUTINE SETS UP THE DMA FOR READ/WRITE/VERIFY
1532 ; OPERATIONS.
1533 ;
1534 ; ON ENTRY: AL = DMA COMMAND
1535 ;
1536 ; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION
1537 -----
1538 064D DMA_SETUP PROC NEAR
1539 064D FA CL1 ; DISABLE INTERRUPTS DURING DMA SET-UP
1540 064E E6 OC OUT DMA+12,AL ; SET THE FIRST/LAST F/F
1541 0650 EB 00 JMP $+2 ; WAIT FOR I/O
1542 0652 E6 0B OUT DMA+11,AL ; OUTPUT THE MODE BYTE
1543 0654 3C 42 CMP AL,42H ; DMA VERIFY COMMAND
1544 0656 75 04 JNE NOT_VERIFY ; NO
1545 0658 33 C0 XOR AX,AX ; START ADDRESS
1546 065A EB 10 JMP SHORT J33
1547 065C NOT_VERIFY
1548 065C 8C C0 MOV AX,EC ; GET THE ES VALUE
1549 065E C1 C0 04 ROL AX,4 ; ROTATE LEFT
1550 0661 8A E8 MOV CH,AL ; GET HIGHEST NIBBLE OF ES TO CH
1551 0663 24 F0 AND AL,11110000B ; ZERO THE LOW NIBBLE FROM SEGMENT
1552 0665 03 46 02 ADD AX,[BP+2] ; TEST FOR CARRY FROM ADDITION
1553 0668 73 02 JNC J33
1554 066A FE C5 J33: INC CH ; CARRY MEANS HIGH 4 BITS MUST BE INC
1555 066C PUSH AX ; SAVE START ADDRESS
1556 066D 50 OUT DMA+4,AL ; OUTPUT LOW ADDRESS
1557 066F EB 00 JMP $+2 ; WAIT FOR I/O
1558 0671 8A C4 MOV AL,AH
1559 0673 E6 04 OUT DMA+4,AL ; OUTPUT HIGH ADDRESS
1560 0675 8A C5 MOV AL,CH ; GET HIGH 4 BITS
1561 0677 EB 00 JMP $+2 ; I/O WAIT STATE
1562 0679 24 0F AND AL,00001111B
1563 067B E6 81 OUT 081H,AL ; OUTPUT HIGH 4 BITS TO PAGE REGISTER
1564
1565 ;----- DETERMINE COUNT
1566
1567
1568 067D 8B C6 MOV AX,S1 ; AL = # OF SECTORS
1569 067F 86 C4 XCHG AL,AH ; AH = # OF SECTORS
1570 0681 2A C0 SUB AL,AL ; AL = 0, AX = # OF SECTORS * 256
1571 0683 D1 E8 SHR AX,1 ; AX = # SECTORS * 128
1572 0685 50 PUSH AX ; SAVE # OF SECTORS * 128
1573 0686 92 03 MOV DL,3 ; GET BYTES/SECTOR PARAMETER
1574 0688 E8 0905 R CALL GET_PARM ;
1575 068B 8A CC MOV CL,AH ; SHIFT COUNT (0=128, 1=256 ETC)
1576 068D 58 POP AX ; AX = # OF SECTORS * 128
1577 068E D3 E0 SHL AX,CL ; SHIFT BY PARAMETER VALUE
1578 0690 48 DEC AX ; -1 FOR DMA VALUE
1579 0691 50 PUSH AX ; SAVE COUNT VALUE
1580 0692 E6 05 OUT DMA+5,AL ; LOW BYTE OF COUNT
1581 0694 EB 00 JMP $+2 ; WAIT FOR I/O
1582 0696 5A C4 MOV AL,AH
1583 0698 E6 05 OUT DMA+5,AL ; HIGH BYTE OF COUNT
1584 069A FB STI ; RE-ENABLE INTERRUPTS
1585 069B 59 POP CX ; RECOVER COUNT VALUE
1586 069C 58 POP AX ; RECOVER ADDRESS VALUE
1587 069D 03 C1 ADD AX,CX ; ADD, TEST FOR 64K OVERFLOW
1588 069F 90 02 MOV AL,2 ; MODE FOR 8237
1589 06A1 EB 00 JMP $+2 ; WAIT FOR I/O
1590 06A3 E6 0A OUT DMA+10,AL ; INITIALIZE THE DISKETTE CHANNEL
1591
1592 06A5 73 05 JNC NO_BAD ; CHECK FOR ERROR
1593 06A7 C6 06 0041 R 09 MOV 0DSKETTE_STATUS,DMA_BOUNDARY ; SET ERROR
1594
1595 NO_BAD: RET ; CY SET BY ABOVE IF ERROR
1596 06AC C3
1597 06AD DMA_SETUP ENDP

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1598 PAGE
1599 -----
1600 FMTDMA_SET
1601 ; THIS ROUTINE SETS UP THE DMA CONTROLLER FOR A FORMAT
1602 ; OPERATION.
1603 ;
1604 ; ON ENTRY: NOTHING REQUIRED
1605 ;
1606 ; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION
1607 ;
1608 FMTDMA_SET PROC NEAR
1609 MOV AL,04AH ; WILL WRITE TO THE DISKETTE
1610 OUT CL1 ; DISABLE INTERRUPTS DURING DMA SET-UP
1611 OUT DMA+12,AL ; SET THE FIRST/LAST FIF
1612 JMP $+2 ; WAIT FOR I/O
1613 OUT DMA+11,AL ; OUTPUT THE MODE BYTE
1614 ;
1615 MOV AX,ES ; GET THE ES VALUE
1616 ROL AX,4 ; ROTATE LEFT
1617 MOV CH,AL ; GET HIGHEST NIBBLE OF ES TO CH
1618 AND AL,11110000B ; ZERO THE LOW NIBBLE FROM SEGMENT
1619 ADD AX,[BP+2] ; TEST FOR CARRY FROM ADDITION
1620 JNC J33A
1621 INC J33A ; CARRY MEANS HIGH 4 BITS MUST BE INC
1622 ;
1623 PUSH AX ; SAVE START ADDRESS
1624 OUT DMA+4,AL ; OUTPUT LOW ADDRESS
1625 JMP $+2 ; WAIT FOR I/O
1626 MOV AL,AH
1627 OUT DMA+4,AL ; OUTPUT HIGH ADDRESS
1628 MOV AL,CH ; GET HIGH 4 BITS
1629 JMP $+2 ; I/O WAIT STATE
1630 AND AL,00001111B ; OUTPUT HIGH 4 BITS TO PAGE REGISTER
1631 OUT 081H,AL
1632 ;
1633 ;----- DETERMINE COUNT
1634 ;
1635 MOV DL,4 ; SECTORS/TRACK VALUE IN PARM TABLE
1636 CALL GET_PARM ;
1637 MOV AL,AH ; AL = SECTORS/TRACK VALUE
1638 SUB AH,AH ; AX = SECTORS/TRACK VALUE
1639 SHL AX,2 ; AX = SEC/TRK * 4 (OFFSET FOR C,H,R,N)
1640 DEC AX ; +1 FOR DMA VALUE
1641 PUSH AX ; SAVE # OF BYTES TO BE TRANSFERRED
1642 OUT DMA+5,AL ; LOW BYTE OF COUNT
1643 JMP $+2 ; WAIT FOR I/O
1644 MOV AL,AH
1645 OUT DMA+5,AL ; HIGH BYTE OF COUNT
1646 STI ; RE-ENABLE INTERRUPTS
1647 POP CX ; RECOVER COUNT VALUE
1648 POP AX ; RECOVER ADDRESS VALUE
1649 ADD AX,CX ; ADD, TEST FOR 64K OVERFLOW
1650 MOV AL,2 ; MODE FOR 8237
1651 JMP $+2 ; WAIT FOR I/O
1652 OUT DMA+10,AL ; INITIALIZE THE DISKETTE CHANNEL
1653 ;
1654 JNC FMTDMA_OK ; CHECK FOR ERROR
1655 MOV 0DSKETTE_STATUS,DMA_BOUNDARY ; SET ERROR
1656 ;
1657 FMTDMA_OK:
1658 RET ; CY SET BY ABOVE IF ERROR
1659 FMTDMA_SET ENDP
1660 ;
1661 ;----- NEC_INIT
1662 ; THIS ROUTINE SEEKS TO THE REQUESTED TRACK AND
1663 ; INITIALIZES THE NEC FOR THE READ/WRITE/VERIFY/FORMAT
1664 ; OPERATION.
1665 ;
1666 ; ON ENTRY: AH : NEC COMMAND TO BE PERFORMED
1667 ;
1668 ; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION
1669 ;
1670 NEC_INIT PROC NEAR
1671 PUSH AX ; SAVE NEC COMMAND
1672 CALL MOTOR_ON ; TURN MOTOR ON FOR SPECIFIC DRIVE
1673 ;
1674 ;----- DO THE SEEK OPERATION
1675 ;
1676 MOV CH,[BP+1] ; CH = TRACK #
1677 CALL SEEK ; MOVE TO CORRECT TRACK
1678 POP AX ; RECOVER COMMAND
1679 JC ER_1 ; ERROR ON SEEK
1680 MOV BX,OFFSET ER_1 ; LOAD ERROR ADDRESS
1681 PUSH BX ; PUSH NEC_OUT ERROR RETURN
1682 ;
1683 ;----- SEND OUT THE PARAMETERS TO THE CONTROLLER
1684 ;
1685 CALL NEC_OUTPUT ; OUTPUT THE OPERATION COMMAND
1686 MOV AX,S1 ; AH = HEAD #
1687 MOV BX,D1 ; BL = DRIVE #
1688 SAL AH,2 ; MOVE IT TO BIT 2
1689 AND AH,00000100B ; ISOLATE THAT BIT
1690 OR AH,BL ; OR IN THE DRIVE NUMBER
1691 CALL NEC_OUTPUT ; FALL THRU CY SET IF ERROR
1692 POP BX ; THROW AWAY ERROR RETURN
1693 ;
1694 RET
1695 NEC_INIT ENDP
1696 ;
1697 ;----- RWV_COM
1698 ; THIS ROUTINE SENDS PARAMETERS TO THE NEC SPECIFIC
1699 ; TO THE READ/WRITE/VERIFY OPERATIONS.
1700 ;
1701 ; ON ENTRY: CS:BX = ADDRESS OF MEDIA/DRIVE PARAMETER TABLE
1702 ; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION
1703 ;
1704 RWV_COM PROC NEAR
1705 MOV AX,OFFSET ER_2 ; LOAD ERROR ADDRESS
1706 PUSH AX ; PUSH NEC_OUT ERROR RETURN
1707 MOV AH,[BP+1] ; OUTPUT TRACK #
1708 CALL NEC_OUTPUT ;
1709 MOV AX,S1 ; OUTPUT HEAD #
1710 CALL NEC_OUTPUT ;
1711 MOV AH,[BP] ; OUTPUT SECTOR #

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1712 0737 E8 09F8 R      CALL    NEC_OUTPUT
1713 073A B2 03          MOV     DL,3
1714 073C E8 0905 R      CALL    GET_PARM
1715 073F E8 09F8 R      CALL    NEC_OUTPUT
1716 0742 B2 04          MOV     DL,4
1717 0744 E8 0905 R      CALL    GET_PARM
1718 0747 E8 09F8 R      CALL    NEC_OUTPUT
1719                      ;
1720 074A 2E: 8A 67 05     MOV     AH,CS:[BX].MD_GAP
1721 074E E8 09F8 R      CALL    NEC_OUTPUT
1722 0751 B2 06          MOV     DL,6
1723 0753 E8 0905 R      CALL    GET_PARM
1724 0756 E8 09F8 R      CALL    NEC_OUTPUT
1725 0759 58             POP      AX
1726 075A             ER_2:
1727 075A C3             RET
1728 075B             RFW COM ENDP
1729
1730 -----
1731 ; NEC_TERM
1732 ; THIS ROUTINE WAITS FOR THE OPERATION THEN ACCEPTS
1733 ; THE STATUS FROM THE NEC FOR THE READ/WRITE/VERIFY/
1734 ; FORMAT OPERATION.
1735 ;
1736 ; ON EXIT: 0DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION
1737 -----
1737 075B             NEC_TERM PROC NEAR
1738
1739 ;----- LET THE OPERATION HAPPEN
1740
1741 075B 56             PUSH     SI
1742 075C E8 0AC1 R      CALL    WAIT_INT
1743 075F 9C             PUSHF
1744 0760 E8 0AE9 R      CALL    RESULTS
1745 0763 72 45          JC      SET_END_POP
1746 0765 9D             POPF
1747 0766 72 3A          JC      SET_END
1748                      ;
1749 ;----- CHECK THE RESULTS RETURNED BY THE CONTROLLER
1750
1751 0768 FC             CLD
1752 0769 BE 0042 R     MOV     SI,OFFSET 0NEC_STATUS
1753 076C AC             LODS     0NEC_STATUS
1754 076D 24 C0          AND     AL,1000000B
1755 076F 74 31          JZ      SET_END
1756 0771 3C 40          CMP     AL,01000000B
1757 0773 75 27          JNZ     J18
1758                      ;
1759 ;----- ABNORMAL TERMINATION, FIND OUT WHY
1760
1761 0775 AC             LODS     0NEC_STATUS
1762 0776 D0 E0          SAL     AL,1
1763 0778 B4 04          MOV     AH,RECORD_NOT_FND
1764 077A 72 22          JC      J19
1765 077C C0 E0 02      SAL     AL,2
1766 077F B4 10          MOV     AH,BAD_CRC
1767 0781 72 18          JC      J19
1768 0783 D0 E0          SAL     AL,1
1769 0785 B4 08          MOV     AH,BAD_DMA
1770 0787 72 15          JC      J19
1771 0789 C0 E0 02      SAL     AL,2
1772 078C B4 04          MOV     AH,RECORD_NOT_FND
1773 078E 72 0E          JC      J19
1774 0790 D0 E0          SAL     AL,1
1775 0792 B4 03          MOV     AH,WRITE_PROTECT
1776 0794 72 08          JC      J19
1777 0796 D0 E0          SAL     AL,1
1778 0798 B4 02          MOV     AH,BAD_ADDR_MARK
1779 079A 72 02          JC      J19
1780
1781 ;----- NEC MUST HAVE FAILED
1782 079C             J18:
1783 079C B4 20          MOV     AH,BAD_NEC
1784 079E             OR
1785 079E 08 26 0041 R   OR     0DSKETTE_STATUS,AH
1786 07A2             SET_END:
1787 07A2 80 3E 0041 R 01 CMP     0DSKETTE_STATUS,1
1788 07A7 F5             CMC
1789 07A8 5E             POP      SI
1790 07A9 C3             RET
1791
1792 07AA             SET_END_POP:
1793 07AA 9D             POPF
1794 07AB EB F5             JMP     SHORT SET_END
1795 07AD             NEC_TERM ENDP
1796 -----
1797 ; DSTATE: ESTABLISH STATE UPON SUCCESSFUL OPERATION.
1798 -----
1799 07AD             DSTATE PROC NEAR
1800 07AD 80 3E 0041 R 00 CMP     0DSKETTE_STATUS,0
1801 07B2 75 30          JNZ     SETBAC
1802 07B4 80 8D 0090 R 10 OR     00SK_STATE[D1],MD_DET
1803 07B9 F6 85 0090 R 04 TEST    00SK_STATE[D1],DRV_DET
1804 07BE 75 24          JNZ     SETBAC
1805 07C0 8A 85 0090 R 00 MOV     AL,00SK_STATE[D1]
1806 07C4 24 C0          AND     AL,RATE_MSK
1807 07C6 3C 80          CMP     AL,RATE_250
1808 07C8 75 15          JNE     M_12
1809                      ;
1810 ;--- CHECK IF IT IS 1.44M
1811
1812 07CA E8 08EC R      CALL    CMDS_TYPE
1813 07CD 72 10          JC      M_12
1814 07CF 3C 04          CMP     AL,04
1815 07D1 74 0C          JE      M_12
1816 07D3             M_120:
1817 07D3 80 A5 0090 R FD AND     00SK_STATE[D1],NOT_FMT_CAPA
1818 07D8 80 8D 0090 R 04 OR     00SK_STATE[D1],DRV_DET
1819 07DD EB 05             JMP     SHORT SETBAC
1820
1821 07DF 80 8D 0090 R 06 M_12: OR     00SK_STATE[D1],DRV_DET+_FMT_CAPA
1822                      ;
1823 07E4             SETBAC:
1824 07E4 C3             RET
1825 07E5             DSTATE ENDP

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1826      ;-----
1827      ; RETRY
1828      ; DETERMINES WHETHER A RETRY IS NECESSARY. IF RETRY IS
1829      ; REQUIRED THEN STATE INFORMATION IS UPDATED FOR RETRY.
1830      ;
1831      ; ON EXIT:      CY = 1 FOR RETRY, CY = 0 FOR NO RETRY
1832      ;-----
1833 07E5      RETRY      PROC      NEAR
1834 07E5 80 3E 0041 R 00      CMP      @DSKETTE_STATUS,0      ; GET STATUS OF OPERATION
1835 07EA 74 39      JZ      NO_RETRY      ; SUCCESSFUL OPERATION
1836 07EC 80 3E 0041 R 80      CMP      @DSKETTE_STATUS,TIME_OUT      ; IF TIME OUT NO RETRY
1837 07F1 74 32      JZ      NO_RETRY      ;
1838 07F3 8A A5 0090 R      MOV      AH,@DSK_STATE[D1]      ; GET MEDIA STATE OF DRIVE
1839 07F7 F6 C4 10      TEST     AH,MED_DET      ; ESTABLISHED/DETERMINED ?
1840 07FA 75 29      JNZ      NO_RETRY      ; IF ESTABLISHED STATE THEN TRUE ERROR
1841 07FC 80 E4 C0      AND      AH,RATE_MSK      ; ISOLATE RATE
1842 07FF 8A 2E 00BB R      MOV      CH,ALASTRATE      ; GET START OPERATION STATE
1843 0803 C0 C5 04      ROL      CH,4      ; TO CORRESPONDING BITS
1844 0806 80 E5 C0      AND      CH,RATE_MSK      ; ISOLATE RATE BITS
1845 0809 3A EC      CMP      CH,AH      ; ALL RATES TRIED
1846 080B 74 18      JE      NO_RETRY      ; IF YES, THEN TRUE ERROR
1847
1848      ;
1849      ; SETUP STATE INDICATOR FOR RETRY ATTEMPT TO NEXT RATE
1850      ; 00000000B (500) -> 10000000B (250)
1851      ; 10000000B (250) -> 01000000B (300)
1852      ; 01000000B (300) -> 00000000B (500)
1853 080D 80 FC 01      CMP      AH,RATE_500+1      ; SET CY FOR RATE 500
1854 0810 D0 DC      RCR      AH,1      ; TO NEXT STATE
1855 0812 80 E4 C0      AND      AH,RATE_MSK      ; KEEP ONLY RATE BITS
1856 0815 80 A5 0090 R IF      AND      @DSK_STATE[D1],NOT RATE_MSK+DBL_STEP      ; RATE, DBL STEP OFF
1857 081A 08 A5 0090 R      MOV      @DSK_STATE[D1],AH      ; TURN ON NEW RATE
1858 081E C6 06 0041 R 00      MOV      @DSKETTE_STATUS,0      ; RESET STATUS FOR RETRY
1859 0823 F9      STC      ; SET CARRY FOR RETRY
1860 0824 C3      RET      ; RETRY RETURN
1861
1862 0825      NO_RETRY:      CLC      ; CLEAR CARRY NO RETRY
1863 0825 F8      RET      ; NO RETRY RETURN
1864 0826 C3
1865 0827      RETRY      ENDP
1866      ;-----
1867      ; NUM_TRANS
1868      ; THIS ROUTINE CALCULATES THE NUMBER OF SECTORS THAT
1869      ; WERE ACTUALLY TRANSFERRED TO/FROM THE DISKETTE.
1870      ;
1871      ; ON ENTRY:      [BP+1] = TRACK
1872      ;                  SI+HI = HEAD
1873      ;                  [BP] = START SECTOR
1874      ;
1875      ; ON EXIT:      AL = NUMBER ACTUALLY TRANSFERRED
1876      ;-----
1877 0827      NUM_TRANS      PROC      NEAR
1878 0827 32 C0      XOR      AL,AL      ; CLEAR FOR ERROR
1879 0829 80 3E 0041 R 00      CMP      @DSKETTE_STATUS,0      ; CHECK FOR ERROR
1880 082E 75 23      JNZ      NT_OUT      ; IF ERROR 0 TRANSFERRED
1881 0830 B2 04      MOV      DL,4      ; SECTORS/TRACK OFFSET TO DL
1882 0832 E8 0905 R      CALL     BL,@SEC_STATUS+5      ; AH = SECTORS/TRACK
1883 0835 8A 1E 0047 R      MOV      BL,@SEC_STATUS+5      ; GET ENDING SECTOR
1884 0839 8B EC      MOV      CX,SI      ; CH = HEAD # STARTED
1885 083B 3A 2E 0046 R      CMP      CH,@NEC_STATUS+4      ; GET HEAD ENDED UP ON
1886 083F 75 0B      JNZ      DIF_HD      ; IF ON SAME HEAD, THEN NO ADJUST
1887
1888 0841 8A 2E 0045 R      MOV      CH,@NEC_STATUS+3      ; GET TRACK ENDED UP ON
1889 0845 3A 6E 01      CMP      CH,[BP+1]      ; IS IT ASKED FOR TRACK
1890 0848 74 04      JZ      SAME_TRK      ; IF SAME TRACK NO INCREASE
1891
1892 084A 02 DC      ADD      BL,AH      ; ADD SECTORS/TRACK
1893 084C      DIF_HD:      ADD      BL,AH      ; ADD SECTORS/TRACK
1894 084E      SAME_TRK:      SUB      BL,[BP]      ; SUBTRACT START FROM END
1895 084E 2A 5E 00      MOV      AL,BL      ; TO AL
1896 084E 2A 5E 00
1897 0851 8A C3
1898
1899 0853      NT_OUT:      RET
1900 0853 C3
1901 0854      NUM_TRANS      ENDP
1902      ;-----
1903      ; SETUP_END
1904      ; RESTORES *MOTOR COUNT TO PARAMETER PROVIDED IN TABLE
1905      ; AND LOADS @DSKETTE_STATUS TO AH, AND SETS CY.
1906      ;
1907      ; ON EXIT:      AH, @DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION
1908      ;-----
1909 0854      SETUP_END      PROC      NEAR
1910 0854 B2 02      MOV      DL,2      ; GET THE MOTOR WAIT PARAMETER
1911 0856 50      PUSH     AX      ; SAVE NUMBER TRANSFERRED
1912 0857 E8 0905 R      CALL     GET_PARM      ;
1913 085A 8B 26 0040 R      MOV      @MOTOR_COUNT,AH      ; STORE UPON RETURN
1914 085E 58      POP      AX      ; RESTORE NUMBER TRANSFERRED
1915 085F 8A 26 0041 R      MOV      AH,@DSKETTE_STATUS      ; GET STATUS OF OPERATION
1916 0863 0A E4      OR      AH,AH      ; CHECK FOR ERROR
1917 0865 74 02      JZ      NO_ERR      ; NO ERROR
1918 0867 32 C0      XOR      AL,AL      ; CLEAR NUMBER RETURNED
1919
1920 0869      NO_ERR:      CMP      AH,1      ; SET THE CARRY FLAG TO INDICATE
1921 0869 80 FC 01      CMP      AH,1      ; SUCCESS OR FAILURE
1922 086C F5      CMC      ;
1923 086D C3      RET      ;
1924 086E      SETUP_END      ENDP

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1925 PAGE
1926 -----
1927 ; SETUP_DBL
1928 ; CHECK DOUBLE STEP.
1929 ; ON ENTRY:
1930 ; D1 = DRIVE
1931 ; ON EXIT: CY = 1 MEANS ERROR
1932 -----
1933 086E
1934 086E 8A A5 0090 R
1935 0872 F6 C4 10
1936 0875 75 5E
1937
1938 SETUP_DBL PROC NEAR
1939 MOV AH,DSK_STATE[D1] ; ACCESS STATE
1940 TEST AH,MED_DET ; ESTABLISHED STATE ?
1941 JNZ NO_DBL ; IF ESTABLISHED THEN DOUBLE DONE
1942
1943 ;----- CHECK FOR TRACK 0 TO SPEED UP ACKNOWLEDGE OF UNFORMATTED DISKETTE
1944
1945 MOV #SEEK_STATUS,0 ; SET RECALIBRATE REQUIRED ON ALL DRIVES
1946 CALL MOTOR_ON ; ENSURE MOTOR STAY ON
1947 MOV CH,0 ; LOAD TRACK 0
1948 CALL SEEK ; SEEK TO TRACK 0
1949 CALL READ_ID ; READ ID FUNCTION
1950 JC SD_ERR ; IF ERROR NO TRACK 0
1951
1952 ;----- INITIALIZE START AND MAX TRACKS (TIMES 2 FOR BOTH HEADS)
1953
1954 MOV CX,0450H ; START, MAX TRACKS
1955 TEST #DSK_STATE[D1],TRK_CAPA ; TEST FOR 80 TRACK CAPABILITY
1956 JZ CNT_OK ; IF NOT COUNT IS SETUP
1957 MOV CL,0A0H ; MAXIMUM TRACK 1.2 MB
1958
1959 ; ATTEMPT READ ID OF ALL TRACKS, ALL HEADS UNTIL SUCCESS; UPON SUCCESS,
1960 ; MUST SEE IF ASKED FOR TRACK IN SINGLE STEP MODE = TRACK ID READ; IF NOT
1961 ; THEN SET DOUBLE STEP ON.
1962
1963 CNT_OK: MOV #MOTOR_COUNT,OFFH ; ENSURE MOTOR STAYS ON FOR OPERATION
1964 PUSH CX ; SAVE TRACK, COUNT
1965 MOV #DSKETTE_STATUS,0 ; CLEAR STATUS, EXPECT ERRORS
1966 XOR AX,AX ; CLEAR AX
1967 SHR CH,1 ; HALVE TRACK, CY = HEAD
1968 RCL AL,3 ; AX = HEAD IN CORRECT BIT
1969 PUSH AX ; SAVE HEAD
1970 CALL SEEK ; SEEK TO TRACK
1971 POP AX ; RESTORE HEAD
1972 OR DI,AX ; D1 = HEAD OR'D DRIVE
1973 CALL READ_ID ; READ ID HEAD 0
1974 PUSHF ; SAVE RETURN FROM READ_ID
1975 AND DI,11111011B ; TURN OFF HEAD 1 BIT
1976 POPF ; RESTORE ERROR RETURN
1977 POP CX ; RESTORE COUNT
1978 JNC DO_CHK ; IF OK, ASKED = RETURNED TRACK ?
1979 INC CH ; INC FOR NEXT TRACK
1980 CMP CH,CL ; REACHED MAXIMUM YET
1981 JNZ CNT_OK ; CONTINUE TILL ALL TRIED
1982
1983 ;----- FALL THRU, READ ID FAILED FOR ALL TRACKS
1984
1985 SD_ERR: STC ; SET CARRY FOR ERROR
1986 RET ; SETUP_DBL ERROR EXIT
1987
1988 DO_CHK: MOV CL,#NEC_STATUS+3 ; LOAD RETURNED TRACK
1989 MOV #DSK_TRK[D1],CL ; STORE TRACK NUMBER
1990 SHR CH,1 ; HALVE TRACK
1991 CMP CH,CL ; IS IT THE SAME AS ASKED FOR TRACK
1992 JZ NO_DBL ; IF SAME THEN NO DOUBLE STEP
1993 OR #DSK_STATE[D1],DBL_STEP ; TURN ON DOUBLE STEP REQUIRED
1994
1995 NO_DBL: CLC ; CLEAR ERROR FLAG
1996 RET
1997
1998 SETUP_DBL ENDP
1999
2000 ;-----
2001 ; READ_ID
2002 ; READ ID FUNCTION.
2003 ; ON ENTRY: D1 = BIT 2 = HEAD; BITS 1,0 = DRIVE
2004 ; ON EXIT: D1 = BIT 2 IS RESET, BITS 1,0 = DRIVE
2005 ; #DSKETTE_STATUS, CY REFLECTS STATUS OF OPERATION
2006 -----
2007 READ_ID PROC NEAR
2008 MOV AX,OFFSET ER_3 ; MOVE NEC OUTPUT ERROR ADDRESS
2009 PUSH AX
2010 MOV AH,4AH ; READ ID COMMAND
2011 CALL NEC_OUTPUT ; TO CONTROLLER
2012 MOV AX,D1 ; DRIVE # TO AH, HEAD 0
2013 CALL NEC_OUTPUT ; TO CONTROLLER
2014 CALL NEC_TERM ; WAIT FOR OPERATION, GET STATUS
2015 POP AX ; THROW AWAY ERROR ADDRESS
2016
2017 ER_3: RET
2018
2019 READ_ID ENDP
2020
2021 ;-----
2022 ; CMOS_TYPE
2023 ; RETURNS DISKETTE TYPE FROM CMOS
2024 ; ON ENTRY: D1 = DRIVE #
2025 ; ON EXIT: AL = TYPE; CY REFLECTS STATUS
2026 -----
2027 CMOS_TYPE PROC NEAR
2028 MOV AL,CMOS_DIAG ; CMOS DIAGNOSTIC STATUS BYTE ADDRESS
2029 CALL CMOS_READ ; GET CMOS STATUS
2030 TEST AL,BAD_BAT+BAD_CKSUM ; BATTERY GOOD AND CHECKSUM VALID ?
2031 JNZ BAD_CM ; SET CY = 1 INDICATING ERROR FOR RETURN
2032 ; ERROR IF EITHER BIT ON
2033
2034 MOV AL,CMOS_DISKETTE ; ADDRESS OF DISKETTE BYTE IN CMOS
2035 CALL CMOS_READ ; GET DISKETTE BYTE
2036 OR DI,DT ; SEE WHICH DRIVE IN QUESTION
2037 ROR AL,4 ; IF DRIVE 1, DATA IN LOW NIBBLE
2038 ; EXCHANGE NIBBLES IF SECOND DRIVE
2039
2040 TB: AND AL,00FH ; KEEP ONLY DRIVE DATA, RESET CY = 0
2041
2042 BAD_CM: RET
2043
2044 CMOS_TYPE ENDP

```

```

2039      GET_PARM
2040      ;
2041      ; THIS ROUTINE FETCHES THE INDEXED POINTER FROM THE
2042      ; DISK BASE BLOCK POINTED TO BY THE DATA VARIABLE
2043      ; *DISK POINTER. A BYTE FROM THAT TABLE IS THEN MOVED
2044      ; INTO AH, THE INDEX OF THAT BYTE BEING THE PARAMETER
2045      ; IN DL.
2046      ;
2047      ; ON ENTRY: DL = INDEX OF BYTE TO BE FETCHED
2048      ;
2049      ; ON EXIT: AH = THAT BYTE FROM BLOCK
2050      ; AL,DH DESTROYED
2051      ;
2052 0905  GET_PARM PROC NEAR
2053 0905 1E      PUSH DS
2054 0906 56      PUSH SI
2055 0907 28 C0   SUB AX,AX ; DS = 0, BIOS DATA AREA
2056 0909 6E D8   MOV DS,AX ;
2057 090B 87 D3   XCHG DX,BX ; BL = INDEX
2058 090D 2A FF   SUB BH,BH ; BX = INDEX
2059      ASSUME DS:ABS0
2060 090F C5 36 0075 R LDS SI,*DISK POINTER ; POINT TO BLOCK
2061 0913 8A 20   MOV AH,[SI+BX] ; GET THE WORD
2062 0915 8B D3   XCHG DX,BX ; RESTORE BX
2063 0917 5E     POP SI
2064 0918 1F     POP DX
2065 0919 C3     RET
2066      ASSUME DS:DATA
2067 091A      GET_PARM ENDP
2068      ;
2069      ; MOTOR_ON
2070      ; TURN MOTOR ON AND WAIT FOR MOTOR START UP TIME. THE *MOTOR_COUNT
2071      ; IS REPLACED WITH A SUFFICIENTLY HIGH NUMBER (0FFH) TO ENSURE
2072      ; THAT THE MOTOR DOES NOT GO OFF DURING THE OPERATION. IF THE
2073      ; MOTOR NEEDED TO BE TURNED ON, THE MULTITASKING HOOK FUNCTION
2074      ; (AX=0FFDH, INT 15H) IS CALLED TELLING THE OPERATING SYSTEM
2075      ; THAT THE BIOS IS ABOUT TO WAIT FOR MOTOR START UP. IF THIS
2076      ; FUNCTION RETURNS WITH CY = 1, IT MEANS THAT THE MINIMUM WAIT
2077      ; HAS BEEN COMPLETED. AT THIS POINT A CHECK IS MADE TO ENSURE
2078      ; THAT THE MOTOR WASN'T TURNED OFF BY THE TIMER. IF THE HOOK DID
2079      ; NOT WAIT, THE WAIT FUNCTION (AH=086H) IS CALLED TO WAIT THE
2080      ; PRESCRIBED AMOUNT OF TIME. IF THE CARRY FLAG IS SET ON RETURN,
2081      ; IT MEANS THAT THE FUNCTION IS IN USE AND DID NOT PERFORM THE
2082      ; WAIT. A TIMER WAIT LOOP WILL THEN DO THE WAIT.
2083      ;
2084      ; ON ENTRY: DI = DRIVE #
2085      ;
2086      ; ON EXIT: AX,CX,DX DESTROYED
2087      ;
2088 091A      MOTOR_ON PROC NEAR
2089 091A 53      PUSH BX ; SAVE REG.
2090 091B E8 0965 R CALL TURN_ON ; TURN ON MOTOR
2091 091E 72 43   JC MOT_TS_ON ; IF CY=1 NO WAIT
2092 0920 E8 0435 R CALL XLAT_OLD ; TRANSLATE STATE TO COMPATIBLE MODE
2093 0923 B8 90FD MOV AX,090FDH ; LOAD WAIT CODE & TYPE
2094 0926 CD 15   INT 15H ; TELL OPERATING SYSTEM ABOUT TO DO WAIT
2095 0928 9C      PUSHF ; SAVE CY FOR TEST
2096 0929 E8 040F R CALL XLAT_NEW ; TRANSLATE STATE TO PRESENT ARCH.
2097 092C 9D      POPF ; RESTORE CY FOR TEST
2098 092D 73 05   JNC M_WAIT ; BYPASS LOOP IF OP SYSTEM HANDLED WAIT
2099 092F E8 0965 R CALL TURN_ON ; CHECK AGAIN IF MOTOR ON
2100 0932 72 2F   JC MOT_TS_ON ; IF NO WAIT MEANS IT IS ON
2101      ;
2102 0934      M_WAIT: MOV DL,10 ; GET THE MOTOR WAIT PARAMETER
2103 0934 B2 0A     CALL GET_PARM
2104 0936 E8 0905 R MOV AL,AH ; AL = MOTOR WAIT PARAMETER
2105 0939 8A C4   MOV AH,AH ; AX = MOTOR WAIT PARAMETER
2106 093B 32 E4   XOR AH,AH ; SEE IF AT LEAST A SECOND IS SPECIFIED
2107 093D 3C 08   CMP AL,8 ; IF YES, CONTINUE
2108 093F 73 02   JAE GP2 ; ONE SECOND WAIT FOR MOTOR START UP
2109 0941 B0 08   MOV AL,8
2110      ;
2111      ; ---- AX CONTAINS NUMBER OF 1/8 SECONDS (125000 MICROSECONDS) TO WAIT
2112      ;
2113 0943 50      GP2: PUSH AX ; SAVE WAIT PARAMETER
2114 0944 BA F424 MOV DX,62500 ; LOAD LARGEST POSSIBLE MULTIPLIER
2115 0947 F7 E2   MUL DX ; MULTIPLY BY HALF OF WHAT'S NECESSARY
2116 0949 8B CA   MOV CX,DX ; CX = HIGH WORD
2117 094B 8B D0   MOV DX,AX ; CX,DX = 1/2 * (# OF MICROSECONDS)
2118 094D F8     CLC ; CLEAR CARRY FOR ROTATE
2119 094E D1 D2   RCL DX,1 ; DOUBLE LOW WORD, CY CONTAINS OVERFLOW
2120 0950 D1 D1   RCL CX,1 ; DOUBLE HI, INCLUDING LOW WORD OVERFLOW
2121 0952 B4 86   MOV AH,86H ; LOAD WAIT CODE
2122 0954 CD 15   INT 15H ; PERFORM WAIT
2123 0956 56     POP AX ; RESTORE WAIT PARAMETER
2124 0957 73 0A   JNC MOT_IS_ON ; CY MEANS WAIT COULD NOT BE DONE
2125      ;
2126      ; ---- FOLLOWING LOOPS REQUIRED WHEN RTC WAIT FUNCTION IS ALREADY IN USE
2127      ;
2128 0959      J13:
2129 0959 B9 205E MOV CX,8286 ; COUNT FOR 1/8 SECOND AT 15.08573T US
2130 095C E8 0000 E CALL WAITF ; GO TO FIXED WAIT ROUTINE
2131 095F FE C8   DEC CH ; DECREMENT TIME VALUE
2132 0961 75 F6   JNZ J13 ; ARE WE DONE YET
2133      ;
2134 0963      MOT_IS_ON: POP BX ; RESTORE REG.
2135 0963 5B     POP RET
2136 0964 C3     RET
2137 0965      MOTOR_ON ENDP
2138      ;
2139      ; TURN_ON
2140      ; TURN MOTOR ON AND RETURN WAIT STATE.
2141      ;
2142      ; ON ENTRY: DI = DRIVE #
2143      ;
2144      ; ON EXIT: CY = 0 MEANS WAIT REQUIRED
2145      ; CY = 1 MEANS NO WAIT REQUIRED
2146      ; AX,BX,CX,DX DESTROYED
2147      ;
2148 0965      TURN_ON PROC NEAR
2149 0965 8B DF   MOV BX,DI ; BX = DRIVE #
2150 0967 8A CB   MOV CL,BL ; CL = DRIVE #
2151 0969 C3 04   ROL BL,4 ; BL = DRIVE SELECT
2152 096C FA     CLI ; NO INTERRUPTS WHILE DETERMINING STATUS

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2153 096D C6 06 0040 R FF      MOV     MOTOR_COUNT,OFFH      ; ENSURE MOTOR STAYS ON FOR OPERATION
2154 0972 A0 003F R             MOV     AL,MOTOR_STATUS      ; GET DIGITAL OUTPUT REGISTER REFLECTION
2155 0975 24 30                 AND     AL,00010000B      ; KEEP ONLY DRIVE SELECT BITS
2156 0977 BA 01                 MOV     AH,1          ; MASK FOR DETERMINING MOTOR BIT
2157 0979 D2 E4                 SHL     AH,CL         ; AH = MOTOR ON, A=00000001, B=00000010
2158
2159 ; AL = DRIVE SELECT FROM MOTOR_STATUS
2160 ; BL = DRIVE SELECT DESIRED
2161 ; AH = MOTOR ON MASK DESIRED
2162
2163 097B 3A C3                 CMP     AL,BL         ; REQUESTED DRIVE ALREADY SELECTED ?
2164 097D 75 06                 JNZ     TURN_IT_ON    ; IF NOT SELECTED JUMP
2165 097F 84 26 003F R         TEST    AL,MOTOR_STATUS ; TEST MOTOR ON BIT
2166 0983 75 2C                 JNZ     NO_MOT_WAIT    ; JUMP IF MOTOR ON AND SELECTED
2167
2168 0985
2169 0985 0A E3                 TURN_IT_ON:          ;
2170 0987 6A 3E 003F R         OR      BH,MOTOR_STATUS ; AH,BL
2171 098B 80 E7 0F             MOV     BH,00001111B ; AH = DRIVE SELECT AND MOTOR ON
2172 098E 80 26 003F R CF     AND     MOTOR_STATUS,11001111B ; SAVE COPY OF MOTOR STATUS BEFORE
2173 0993 08 26 003F R         OR      MOTOR_STATUS,AH ; KEEP ONLY MOTOR BITS
2174 0997 A0 003F R         AL,MOTOR_STATUS      ; CLEAR OUT DRIVE SELECT
2175 099A 0A D8                 BL,AH                 ; OR IN DRIVE SELECTED AND MOTOR ON
2176 099C 80 83 0F             AND     BL,00001111B ; GET DIGITAL OUTPUT REGISTER REFLECTION
2177 099F 3B F3                 STI                     ; BL=MOTOR_STATUS AFTER, BH=BEFORE
2178 09A0 24 3F             AND     AL,00111111B ; KEEP ONLY MOTOR BITS
2179 09A2 C0 C0 04             ROL     AL,4           ; STRIP AWAY UNWANTED BITS
2180 09A5 0C 0C             OR      AL,00001100B ; PUT BITS IN DESIRED POSITIONS
2181 09A7 BA 03F2            MOV     DX,03F2H       ; NO RESET, ENABLE DMA/INTERRUPT
2182 09AA EE                 OUT     DX,AH           ; SELECT DRIVE AND TURN ON MOTOR
2183 09AB 3A DF             CMP     BL,BH          ; NEW MOTOR TURNED ON ?
2184 09AD 74 02             JZ      NO_MOT_WAIT    ; NO WAIT REQUIRED IF JUST SELECT
2185 09AF F8                 CLC                     ; SET CARRY MEANING WAIT
2186 09B0 C3                 RET
2187
2188 09B1
2189 09B1 F9                 NO_MOT_WAIT:          ;
2190 09B2 FB                 STC                     ; SET NO WAIT REQUIRED
2191 09B3 C3                 RET                     ; INTERRUPTS BACK ON
2192 09B4
2193
2194
2195
2196
2197
2198
2199
2200
2201 09B4
2202 09B4 B2 09             HD_WAIT:              ;
2203 09B6 E8 0905 R         CALL    GET_PARM       ; GET HEAD SETTLE PARAMETER
2204 09B9 F6 06 003F R 80    TEST    MOTOR_STATUS,10000000B ;
2205 09BE 74 14             JSNT    WRITE           ; SEE IF A WRITE OPERATION
2206 09C0 0A E4             OR      AH,AH           ; IF NOT, DO NOT ENFORCE ANY VALUES
2207 09C2 75 14             JNZ     DO_WAIT         ; CHECK FOR ANY WAIT?
2208 09C4 BA 0F             MOV     AH,HD12_SETTLE ; IF THERE DO NOT ENFORCE
2209 09C6 84 85 0090 R     MOV     AL,DSK_STATE[D1] ; LOAD STATE
2210 09CA 24 C0             AND     AL,RATE_MSK     ; KEEP ONLY RATE
2211 09CC 3C 80             CMP     AL,RATE_250     ; 1/2 M DRIVE ?
2212 09CE 75 08             JNZ     DO_WAIT         ; DEFAULT HEAD SETTLE LOADED
2213
2214 09D0 BA 14             GP3:   MOV     AH,HD320_SETTLE ; USE 320/360 HEAD SETTLE
2215 09D2 E4 04             JMP     SHORT DO_WAIT   ;
2216
2217 09D4
2218 09D4 0A E4             JSNT    WRITE           ;
2219 09D6 74 1F             OR      AH,AH           ; CHECK FOR NO WAIT
2220
2221
2222
2223
2224
2225
2226
2227
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2229
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2233
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2237
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2240
2241
2242
2243
2244
2245
2246
2247
2248
2249
2250
2251
2252
2253
2254
2255
2256
2257
2258
2259
2260
2261
2262
2263
2264
2265
2266
09D8 8A C4             DO_WAIT: MOV     AL,AH     ; AL = # MILLISECONDS
09DA 32 E4             XOR      AH,AH           ; AX = # MILLISECONDS
09DC 50                 PUSH     AX              ; SAVE HEAD SETTLE PARAMETER
09DE BA 0F             MOV     DX,1000          ; SET UP FOR MULTIPLY TO MICROSECONDS
09E0 F7 E2             MUL     DX               ; DX,AX = # MICROSECONDS
09E2 8B CA             MOV     CX,DX            ; CX,AX = # MICROSECONDS
09E4 8B D0             MOV     DX,AX            ; CX,DX = # MICROSECONDS
09E6 BA 86             MOV     AH,86H           ; LOAD WAIT CODE
09E8 CD 15             INT     15H             ; PERFORM WAIT
09EA 58                 POP      AX              ; RESTORE HEAD SETTLE PARAMETER
09EB 73 0A             JNC     HW_DONE          ; CHECK FOR EVENT WAIT ACTIVE
2234
2235 09ED
2236 09ED B9 0042          J29:   MOV     CX,66      ; 1 MILLISECOND LOOP
2237 09F0 E8 0000 E       CALL    WAITF          ; COUNT AT 15.085737 US PER COUNT
2238 09F3 FE C9             DEC     AL               ; DELAY FOR 1 MILLISECOND
2239 09F5 75 F6             JNZ     J29              ; DECREMENT THE COUNT
2240 09F7
2241 09F7 C3             HW_DONE: RET             ; DO AL MILLISECOND # OF TIMES
2242 09F8
2243
2244
2245
2246
2247
2248
2249
2250
2251
2252
2253
2254
2255
2256
2257
2258
2259
2260
2261
2262
2263
2264
2265
2266
09F8
09F8 53                 NEC_OUTPUT:          ;
09F9 BA 03F4            MOV     DX,03F4H        ; THIS ROUTINE SENDS A BYTE TO THE NEC CONTROLLER AFTER
09FC B3 02             MOV     BL,2             ; TESTING FOR CORRECT DIRECTION AND CONTROLLER READY THIS
09FE 33 C9             XOR      CX,CX           ; ROUTINE WILL TIME OUT IF THE BYTE IS NOT ACCEPTED WITHIN
; A REASONABLE AMOUNT OF TIME, SETTING THE DISKETTE STATUS
; ON COMPLETION.
;
; ON ENTRY:
; AH = BYTE TO BE OUTPUT
;
; ON EXIT:
; CY = 0 SUCCESS
; CY = 1 FAILURE -- DISKETTE STATUS UPDATED
; IF A FAILURE HAS OCCURRED, THE RETURN IS MADE
; ONE LEVEL HIGHER THAN THE CALLER OF NEC_OUTPUT.
; THIS REMOVES THE REQUIREMENT OF TESTING AFTER
; EVERY CALL OF NEC_OUTPUT.
; AX,CX,DX DESTROYED
;
; NEC_OUTPUT PROC NEAR
09F8 53                 PROC NEAR
09F9 BA 03F4            MOV     DX,03F4H        ; SAVE REG.
09FC B3 02             MOV     BL,2             ; STATUS PORT
09FE 33 C9             XOR      CX,CX           ; HIGH ORDER COUNTER
; COUNT FOR TIME OUT

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2267
2268 0A00 EC J23: IN AL,DX ; GET STATUS
2269 0A01 24 C0 AND AL,11000000B ; KEEP STATUS AND DIRECTION
2270 0A03 3C 80 CMP AL,10000000B ; STATUS AND DIRECTION 0 ?
2271 0A05 74 0F JZ J27 ; STATUS AND DIRECTION OK
2272 0A07 E2 F7 LOOP J23 ; CONTINUE TILL CX EXHAUSTED
2273
2274 0A09 FE CB DEC BL ; DECREMENT COUNTER
2275 0A0B 75 F3 JNZ J23 ; REPEAT TILL DELAY FINISHED, CX = 0
2276
2277
2278
2279 0A0D 80 0E 0041 R 80 OR ;#DSKETTE_STATUS,TIME_OUT
2280 0A12 58 BX ; RESTORE REG.
2281 0A13 58 POP AX ; DISCARD THE RETURN ADDRESS
2282 0A14 F9 STC ; INDICATE ERROR TO CALLER
2283 0A15 C3 RET
2284
2285
2286
2287 0A16 J27: ; GET BYTE TO OUTPUT
2288 0A16 8A C4 INC DX ; DATA PORT = STATUS PORT + 1
2289 0A18 42 OUT DX,AL ; OUTPUT THE BYTE
2290 0A19 EE
2291
2292 0A1A 9C PUSHF ; SAVE FLAGS
2293 0A1B B9 0003 MOV CX,3 ; 30 TO 45 MICROSECOND WAIT FOR
2294 0A1E E8 0000 E CALL WAITF ; NEC FLAGS UPDATE CYCLE
2295 0A21 90 POPF ; RESTORE FLAGS FOR EXIT
2296 0A22 5B POP BX ; RESTORE REG.
2297 0A23 C3 RET ; CY = 0 FROM TEST INSTRUCTION
2298 0A24
2299
2300
2301
2302
2303
2304
2305
2306
2307
2308
2309
2310
2311
2312 0A24
2313 0A24 8B 0F SEEK PROC NEAR
2314 0A26 80 01 MOV BX,DI ; BX = DRIVE #
2315 0A28 86 C9 XCHG CL,BL ; ESTABLISH MASK FOR RECALIBRATE TEST
2316 0A2A D2 C0 ROL AL,CL ; GET DRIVE VALUE INTO CL
2317 0A2C 86 C9 XCHG CL,BL ; SHIFT MASK BY THE DRIVE VALUE
2318 0A2E 84 06 003E R TEST AL,#SEEK_STATUS ; RECOVER TRACK VALUE
2319 0A32 75 1C JNZ J28A ; TEST FOR RECALIBRATE REQUIRED
2320
2321 0A34 08 06 003E R OR ;#SEEK_STATUS,AL ; TURN ON THE NO RECALIBRATE BIT IN FLAG
2322 0A36 E8 0A83 R CALL RECAL ; RECALIBRATE DRIVE
2323 0A3B 73 0A JNC AFT_RECAL ; RECALIBRATE DONE
2324
2325
2326
2327 0A3D C6 06 0041 R 00
2328 0A42 E8 0A83 R
2329 0A45 72 3B JC
2330
2331 0A47
2332 0A47 C6 85 0094 R 00
2333 0A4C 0A ED
2334 0A4E 74 2D
2335
2336
2337
2338 0A50 F6 85 0090 R 20
2339 0A55 74 02
2340 0A57 D0 E5
2341
2342 0A59 3A AD 0094 R
2343 0A5D 74 23 JC
2344
2345 0A5F BA 0A82 R
2346 0A62 52
2347 0A63 8B AD 0094 R
2348 0A67 B4 0F
2349 0A69 E8 09F8 R
2350 0A6C 8B 0F
2351 0A6E 8A E3
2352 0A70 E8 09F8 R
2353 0A73 8A A5 0094 R
2354 0A77 E8 09F8 R
2355 0A7A E8 0A9A R
2356
2357
2358
2359 0A7D
2360 0A7D 9C
2361 0A7E E8 09B4 R
2362 0A81 9D
2363 0A82
2364 0A82
2365 0A82 C3
2366 0A83
2367
2368
2369
2370
2371
2372
2373
2374
2375 0A83
2376 0A83 51
2377 0A84 B8 0A98 R
2378 0A87 50
2379 0A88 B4 07
2380 0A8A E8 09F8 R

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2381 0A8D 8B DF      MOV     BX,DI          ; BX = DRIVE #
2382 0A8F 5A E3      MOV     AH,BL          ;
2383 0A91 E8 09F8 R  CALL     NEC_OUTPUT        ; OUTPUT THE DRIVE NUMBER
2384 0A94 E8 0A9A R  CALL     CHK_STAT_2        ; GET THE INTERRUPT AND SENSE INT STATUS
2385 0A97 58          POP      AX          ; THROW AWAY ERROR
2386 0A98            RC_BACK:
2387 0A98 59          POP      CX
2388 0A99 C3          RET
2389 0A9A            RECAL:
2390            ENDP
-----
2391            ; CHK_STAT_2
2392            ; THIS ROUTINE HANDLES THE INTERRUPT RECEIVED AFTER
2393            ; RECALIBRATE OR SEEK TO THE ADAPTER. THE
2394            ; INTERRUPT IS WAITED FOR, THE INTERRUPT STATUS SENSED,
2395            ; AND THE RESULT RETURNED TO THE CALLER.
2396            ;
2397            ; ON EXIT:      *DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION.
2398            ;
2399 0A9A            PROC     NEAR
2400 0A9A 88 0AB8 R     MOV     AX,OFFSET CS_BACK ; LOAD NEC_OUTPUT ERROR ADDRESS
2401 0A9D 50          PUSH    AX
2402 0A9E E8 0AC1 R  CALL     WAIT_INT         ; WAIT FOR THE INTERRUPT
2403 0AA1 72 14      JC       J34          ; IF ERROR, RETURN IT
2404 0AA3 B4 08      MOV     AH,08H        ; SENSE INTERRUPT STATUS COMMAND
2405 0AA5 E8 09F8 R  CALL     NEC_OUTPUT        ; READ IN THE RESULTS
2406 0AA8 E8 0AE9 R  CALL     RESULTS
2407 0AAB 72 0A      JC       J34          ;
2408 0AAD 40 0042 R  MOV     AL,NEC_STATUS        ; GET THE FIRST STATUS BYTE
2409 0AB0 24 60      AND     AL,01100000B   ; ISOLATE THE BITS
2410 0AB2 3C 60      CMP     AL,01100000B   ; TEST FOR CORRECT VALUE
2411 0AB4 74 03      JZ       J35          ; IF ERROR, GO MARK IT
2412 0AB6 F8        CLC
2413 0AB7            J34:
2414 0AB7 58          POP      AX          ; THROW AWAY ERROR RETURN
2415 0AB8            CS_BACK:
2416 0AB8 C3          RET
2417
2418 0AB9            J35:
2419 0AB9 80 0E 0041 R  OR      *DSKETTE_STATUS,BAD_SEEK ; ERROR RETURN CODE
2420 0ABE F9          STC
2421 0ABF EB F6      JMP     SHORT J34
2422 0AC1            ENDP
-----
2423            ; WAIT_INT
2424            ; THIS ROUTINE WAITS FOR AN INTERRUPT TO OCCUR A TIME OUT :
2425            ; ROUTINE TAKES PLACE DURING THE WAIT, SO THAT AN ERROR :
2426            ; MAY BE RETURNED IF THE DRIVE IS NOT READY.
2427            ;
2428            ; ON EXIT:      *DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION.
2429            ;
2430            ;
2431 0AC1            PROC     NEAR
2432 0AC1 FB          STC
2433 0AC2 F8          CLC
2434 0AC3 B8 9001 R  MOV     AX,09001H          ; TURN ON INTERRUPTS, JUST IN CASE
2435 0AC6 CD 15      INT     15H          ; CLEAR TIMEOUT INDICATOR
2436 0AC8 72 11      JC       J36A       ; LOAD WAIT CODE AND TYPE
2437 0ACA B3 0A      MOV     BL,10        ; PERFORM OTHER FUNCTION
2438 0ACC 33 C9      XOR     CX,CX        ; BYPASS TIMING LOOP IF TIMEOUT DONE
2439 0ACE            J36:
2440 0ACE F6 06 003E R 80 TEST     *SEEK_STATUS,INT_FLAG ; TEST FOR INTERRUPT OCCURRING
2441 0AD3 75 0C      JNZ      J37         ;
2442 0AD5 E2 F7      LOOP    J36         ; COUNT DOWN WHILE WAITING
2443 0AD7 FE CB      DEC     BL          ; SECOND LEVEL COUNTER
2444 0AD9 75 F3      JNZ     J36
2445
2446 0ADB 80 0E 0041 R 80 J36A:  OR      *DSKETTE_STATUS,TIME_OUT ; NOTHING HAPPENED
2447 0AD9 F9          STC              ; ERROR RETURN
2448 0AE1            J37:
2449 0AE1 9C          PUSHF    ; SAVE CURRENT CARRY
2450 0AE2 80 26 003E R 7F POPF     *SEEK_STATUS,NOT INT_FLAG ; TURN OFF INTERRUPT FLAG
2451 0AE7 9D          RET              ; RECOVER CARRY
2452 0AE8 C3          RET              ; GOOD RETURN CODE
2453 0AE9            WAIT_INT:
2454            ENDP
-----
2455            ; RESULTS
2456            ; THIS ROUTINE WILL READ ANYTHING THAT THE NEC CONTROLLER :
2457            ; RETURNS FOLLOWING AN INTERRUPT.
2458            ;
2459            ; ON EXIT:      *DSKETTE_STATUS, CY REFLECT STATUS OF OPERATION.
2460            ; AX,BX,CX,DX DESTROYED
2461            ;
2462 0AE9            PROC     NEAR
2463 0AE9 57          PUSH    DI
2464 0AEA BF 0042 R  MOV     DI,OFFSET *NEC_STATUS ; POINTER TO DATA AREA
2465 0AED B3 07      MOV     BL,7         ; MAX STATUS BYTES
2466 0AEF BA 03F4 R  MOV     DX,03F4H          ; STATUS PORT
2467
2468            ;----- WAIT FOR REQUEST FOR MASTER
2469
2470 0AF2 B7 02      MOV     BH,2         ; HIGH ORDER COUNTER
2471 0AF4 33 C9      XOR     CX,CX        ; COUNTER
2472 0AF6            J39:
2473 0AF6 EC          IN      AL,DX        ; WAIT FOR MASTER
2474 0AF7 24 C0      AND     AL,11000000B ; GET STATUS
2475 0AF9 3C C0      CMP     AL,11000000B ; KEEP ONLY STATUS AND DIRECTION
2476 0AFB 74 0E      JZ       J42         ; STATUS 1 AND DIRECTION ?
2477 0AFD E2 F7      LOOP    J39         ; STATUS AND DIRECTION OK
2478            ;
2479 0AFF FE CF      DEC     BH          ; STATUS TIMEOUT
2480 0B01 75 F3      JNZ     J39         ; DECREMENT HIGH ORDER COUNTER
2481            ; REPEAT TILL DELAY DONE
2482 0B03 80 0E 0041 R 80 OR      *DSKETTE_STATUS,TIME_OUT ; SET ERROR RETURN
2483 0B08 F9          STC              ; POP REGISTERS AND RETURN
2484 0B09 EB 1B      JMP     SHORT POPRES
2485
2486            ;----- READ IN THE STATUS
2487
2488 0B0B            J42:
2489            ;
2490 0B0B 42          JMP     $+2          ; I/O DELAY
2491 0B0C EC          INC     DX          ; POINT AT DATA PORT
2492 0B0D 88 05      IN      AL,DX        ; GET THE DATA
2493 0B0F 47          MOV     [DI],AL    ; STORE THE BYTE
2494            ; INCREMENT THE POINTER

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2495 0B10 B9 0003      MOV     CX,3          ; MINIMUM 24 MICROSECONDS FOR NEC
2496 0B13 E8 0000 E     CALL    WAITF          ; WAIT 30 TO 45 MICROSECONDS
2497 0B16 4A           DEC     DX          ; POINT AT STATUS PORT
2498 0B17 EC           IN      AL,DX         ; GET STATUS
2499 0B18 A8 10        TEST    AL,00010000B    ; TEST FOR NEC STILL BUSY
2500 0B1A 74 0A        JZ      POPRES      ; RESULTS DONE ?
2501
2502 0B1C FE CB         DEC     BL          ; DECREMENT THE STATUS COUNTER
2503 0B1E 75 D2         JNZ     R10         ; GO BACK FOR MORE
2504 0B20 80 0E 0041 R 20 OR      R10         ; TOO MANY STATUS BYTES
2505 0B25 F9           STC          ; SET ERROR FLAG
2506
2507 ;----- RESULT OPERATION IS DONE
2508
2509 0B26      POPRES:   POP     DI          ; RETURN WITH CARRY SET
2510 0B28 5F           RET
2511 0B27 C3           RESULTS ENDP
2512 0B28
2513 ;-----
2514 READ_DSKCHNG
2515 READS THE STATE OF THE DISK CHANGE LINE.
2516
2517 ON ENTRY: DI = DRIVE #
2518
2519 ON EXIT: DI = DRIVE #
2520 ZF = 0 : DISK CHANGE LINE INACTIVE
2521 ZF = 1 : DISK CHANGE LINE ACTIVE
2522 AX,CX,DX DESTROYED
2523
2524 0B28      READ_DSKCHNG  PROC    NEAR
2525 0B28 E8 091A R     CALL    MOTOR_ON      ; TURN ON THE MOTOR IF OFF
2526 0B2B BA 03F7 H     MOV     DX,03F7H    ; ADDRESS DIGITAL INPUT REGISTER
2527 0B2E EC           IN      AL,DX         ; INPUT DIGITAL INPUT REGISTER
2528 0B2F A8 80        TEST    AL,DSK_CHG    ; CHECK FOR DISK CHANGE LINE ACTIVE
2529 0B31 C3           RET          ; RETURN TO CALLER WITH ZERO FLAG SET
2530 0B32      READ_DSKCHNG  ENDP
2531
2532 ;-----
2533 DRIVE_DET
2534 DETERMINES WHETHER DRIVE IS 80 OR 40 TRACKS AND
2535 UPDATES STATE INFORMATION ACCORDINGLY.
2536
2537 ON ENTRY: DI = DRIVE #
2538
2539 0B32      DRIVE_DET    PROC    NEAR
2540 0B32 E8 091A R     CALL    MOTOR_ON      ; TURN ON MOTOR IF NOT ALREADY ON
2541 0B35 E8 0A83 R     CALL    RECAL      ; RECALIBRATE DRIVE
2542 0B38 72 3C        JC      DD_BAC      ; ASSUME NO DRIVE, PRESENT
2543 0B3A B5 30        MOV     CH,TRK_SLAP    ; SEEK TO TRACK 48
2544 0B3C E8 0A24 R     CALL    SEEK      ;
2545 0B3F 72 35        JC      DD_BAC      ; ERROR NO DRIVE
2546 0B41 B5 0B        MOV     CH,QUIET_SEEK+1 ; SEEK TO TRACK 10
2547 0B43
2548 0B43 FE CD         DEC     CH          ; DECREMENT TO NEXT TRACK
2549 0B45 51           PUSH    CX          ; SAVE TRACK
2550 0B46 E8 0A24 R     CALL    SEEK      ; POP AND RETURN
2551 0B49 72 2C        JC      POP_BAC      ; LOAD NEC OUTPUT ERROR ADDRESS
2552 0B4E 50           PUSH    AX          ;
2553 0B4F B4 04         MOV     AH,SENSE_DRV_ST    ; SENSE DRIVE STATUS COMMAND BYTE
2554 0B51 E8 09F8 R     CALL    NEC_OUTPUT    ; OUTPUT TO NEC
2555 0B54 0B C7        MOV     AX,DI          ; AL = DRIVE
2556 0B56 BA E0        MOV     AH,AL         ; AH = DRIVE
2557 0B58 E8 09F8 R     CALL    NEC_OUTPUT    ; OUTPUT TO NEC
2558 0B5B E8 0AEC R     CALL    RESULTS    ; GO GET STATUS
2559 0B5E 58           POP     AX          ; THROW AWAY ERROR ADDRESS
2560 0B5F 59           POP     CX          ; RESTORE TRACK
2561 0B60 F6 06 0042 R 10 TEST    #NEC_STATUS,HOME ; TRACK 0 ?
2562 0B65 74 DC        JZ      SK_GTN      ; GO TILL TRACK 0
2563 0B67 0A ED        OR      CH,CH         ; IS HOME AT TRACK 0 ?
2564 0B69 74 06        JZ      IS_80       ; MUST BE 80 TRACK DRIVE
2565
2566 ;
2567 ; DRIVE IS A 360; SET DRIVE TO DETERMINED;
2568 ; SET MEDIA TO DETERMINED AT RATE 250.
2569 0B6B 80 8D 0090 R 94 OR      #OSK_STATE[DI],DRV_DET+MED_DET+RATE 250
2570 0B70 C3           RET          ; ALL INFORMATION SET
2571
2572 0B71      IS_80:      OR      #OSK_STATE[DI],TRK_CAPA ; SETUP 80 TRACK CAPABILITY
2573 0B71 80 8D 0090 R 01
2574 0B76      DD_BAC:    RET
2575 0B76 C3           POP_BAC:
2576
2577 0B77      POP_BAC:   POP     CX          ; THROW AWAY
2578 0B77 59           RET
2579 0B78 C3
2580
2581 0B79      DRIVE_DET  ENDP
2582
2583 ;-----
2584 DISK_INT
2585 THIS ROUTINE HANDLES THE DISKETTE INTERRUPT.
2586
2587 ON EXIT: THE INTERRUPT FLAG IS SET IN #SEEK_STATUS.
2588
2589 0B79      DISK_INT_1  PROC    FAR
2590 0B79 50           PUSH    AX          ; ENTRY POINT FOR ORG 0EF5H
2591 0B7A 1E           PUSH    DS          ; SAVE WORK REGISTER
2592 0B7B E8 0000 E     CALL    DOS         ; SAVE REGISTERS
2593 0B7E 80 0E 003E R 80 OR      #SEEK_STATUS,INT_FLAG ; SETUP DATA ADDRESSING
2594 0B83 1F           POP     DS          ; TURN ON INTERRUPT OCCURRED
2595 0B84 B0 20        MOV     AL,E01      ; RESTORE USER (DS)
2596 0B86 E6 20        OUT     INTA00,AL    ; END OF INTERRUPT MARKER
2597 0B88 FB          STI          ; INTERRUPT CONTROL PORT
2598 0B89 B8 9101      MOV     AX,09101H    ; RE-ENABLE INTERRUPTS
2599 0B8C CD 15        INT     15H         ; INTERRUPT POST CODE AND TYPE
2600 0B8F CF          POP     AX          ; GO PERFORM OTHER TASK
2601 0B90      DISK_INT_1  IRET         ; RECOVER REGISTER
2602      ENDP          ; RETURN FROM INTERRUPT

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2602 PAGE
2603 -----
2604 ; DSKETTE SETUP
2605 ; THIS ROUTINE DOES A PRELIMINARY CHECK TO SEE WHAT TYPE
2606 ; OF DISKETTE DRIVES ARE ATTACH TO THE SYSTEM.
2607 ; -----
2608 DSKETTE_SETUP PROC NEAR
2609     PUSH AX ; SAVE REGISTERS
2610     PUSH BX
2611     PUSH CX
2612     PUSH DX
2613     PUSH DI
2614     PUSH DS
2615     CALL DDS ; POINT DATA SEGMENT TO BIOS DATA AREA
2616     OR     RTC_WAIT_FLAG,01 ; NO RTC WAIT, FORCE USE OF LOOP
2617     XOR     DI,DI ; INITIALIZE DRIVE POINTER
2618     MOV     WORD PTR DSK_STATE,0 ; INITIALIZE STATES
2619     AND     LAstrate,NOT STRT_MSK*SEND_MSK ; CLEAR START & SEND
2620     OR     LAstrate,SEND_MSK ; INITIALIZE SENT TO IMPOSSIBLE
2621     MOV     Sseek_status,0 ; INDICATE RECALIBRATE NEEDED
2622     MOV     MOTOR_COUNT,0 ; INITIALIZE MOTOR COUNT
2623     MOV     MOTOR_STATUS,0 ; INITIALIZE DRIVES TO OFF STATE
2624     MOV     DSKETTE_STATUS,0 ; NO ERRORS
2625
2626 SUP0:
2627     CALL DRIVE_DET ; DETERMINE DRIVE
2628     CALL XLAT_OLD ; TRANSLATE STATE TO COMPATIBLE MODE
2629     INC     DI ; POINT TO NEXT DRIVE
2630     CMP     DI,MAX_DRV ; SEE IF DONE
2631     JNZ     SUP0 ; REPEAT FOR EACH DRIVE
2632     MOV     Sseek_status,0 ; FORCE RECALIBRATE
2633     AND     RTC_WAIT_FLAG,0FEH ; ALLOW FOR RTC WAIT
2634     CALL SETUP_END ; VARIOUS CLEANUPS
2635     POP     DS ; RESTORE CALLERS REGISTERS
2636     POP     DI
2637     POP     DX
2638     POP     CX
2639     POP     BX
2640     POP     AX
2641     RET
2642 DSKETTE_SETUP ENDP
2643 CODE ENDS
2644 END
  
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1      PAGE 118,121
2      TITLE DISK ----- 09/25/85 FIXED DISK BIOS
3      .286C
4      .LIST
5      0000      CODE      SEGMENT BYTE PUBLIC
6
7      PUBLIC   DISK_IO
8      PUBLIC   DISK_SETUP
9      PUBLIC   HD_INT
10
11      EXTRN    CMOS_READ:NEAR
12      EXTRN    CMOS_WRITE:NEAR
13      EXTRN    DOS:NEAR
14      EXTRN    EMSG:NEAR
15      EXTRN    F1780:NEAR
16      EXTRN    F1781:NEAR
17      EXTRN    F1782:NEAR
18      EXTRN    F1790:NEAR
19      EXTRN    F1791:NEAR
20      EXTRN    FD_TBL:NEAR
21
22      --- INT 13H ---
23      :
24      : FIXED DISK I/O INTERFACE
25      :
26      : THIS INTERFACE PROVIDES ACCESS TO 5 1/4" FIXED DISKS THROUGH
27      : THE IBM FIXED DISK CONTROLLER.
28      :
29      : THE BIOS ROUTINES ARE MEANT TO BE ACCESSED THROUGH
30      : SOFTWARE INTERRUPTS ONLY. ANY ADDRESSES PRESENT IN
31      : THESE LISTINGS ARE INCLUDED ONLY FOR COMPLETENESS,
32      : NOT FOR REFERENCE. APPLICATIONS WHICH REFERENCE ANY
33      : ABSOLUTE ADDRESSES WITHIN THE CODE SEGMENTS OF BIOS
34      : VIOLATE THE STRUCTURE AND DESIGN OF BIOS.
35      :
36      :-----
37      :
38      : INPUT (AH) = HEX COMMAND VALUE
39      :
40      : (AH) = 00H RESET DISK (DL = 80H,81H) / DISKETTE
41      : (AH) = 01H READ THE STATUS OF THE LAST DISK OPERATION INTO (AL)
42      : NOTE: DL < 80H - DISKETTE
43      :       DL > 80H - DISK
44      : (AH) = 02H READ THE DESIRED SECTORS INTO MEMORY
45      : (AH) = 03H WRITE THE DESIRED SECTORS FROM MEMORY
46      : (AH) = 04H VERIFY THE DESIRED SECTORS
47      : (AH) = 05H FORMAT THE DESIRED TRACK
48      : (AH) = 06H UNUSED
49      : (AH) = 07H UNUSED
50      : (AH) = 08H RETURN THE CURRENT DRIVE PARAMETERS
51      : (AH) = 09H INITIALIZE DRIVE CHARACTERISTICS
52      : INTERRUPT 41 POINTS TO DATA BLOCK FOR DRIVE 0
53      : INTERRUPT 46 POINTS TO DATA BLOCK FOR DRIVE 1
54      :
55      : (AH) = 0AH READ LONG
56      : (AH) = 0BH WRITE LONG (READ & WRITE LONG ENCOMPASS 512 + 4 BYTES ECC)
57      : (AH) = 0CH SEEK
58      : (AH) = 0DH ALTERNATE DISK RESET (SEE DL)
59      : (AH) = 0EH UNUSED
60      : (AH) = 0FH UNUSED
61      : (AH) = 10H TEST DRIVE READY
62      : (AH) = 11H RECALIBRATE
63      : (AH) = 12H UNUSED
64      : (AH) = 13H UNUSED
65      : (AH) = 14H CONTROLLER INTERNAL DIAGNOSTIC
66      : (AH) = 15H READ DASD TYPE
67      :
68      :-----
69      :
70      : REGISTERS USED FOR FIXED DISK OPERATIONS
71      :
72      : (DL) - DRIVE NUMBER (80H-81H FOR DISK, VALUE CHECKED)
73      : (DH) - HEAD NUMBER (0-15 ALLOWED, NOT VALUE CHECKED)
74      : (CH) - CYLINDER NUMBER (0-1023, NOT VALUE CHECKED) (SEE CL)
75      : (CL) - SECTOR NUMBER (1-17, NOT VALUE CHECKED)
76      :
77      : NOTE: HIGH 2 BITS OF CYLINDER NUMBER ARE PLACED
78      : (10 BITS TOTAL)
79      :
80      : (AL) - NUMBER OF SECTORS (MAXIMUM POSSIBLE RANGE 1-80H,
81      : FOR READ/WRITE LONG 1-79H)
82      :
83      : (ESI:BX) - ADDRESS OF BUFFER FOR READS AND WRITES,
84      : (NOT REQUIRED FOR VERIFY)
85      :
86      : FORMAT (AH=5) ESI:BX POINTS TO A 512 BYTE BUFFER. THE FIRST
87      : 2*(SECTORS/TRACK) BYTES CONTAIN F,N FOR EACH SECTOR.
88      : F = 00H FOR A GOOD SECTOR
89      : 80H FOR A BAD SECTOR
90      : N = SECTOR NUMBER
91      : FOR AN INTERLEAVE OF 2 AND 17 SECTORS/TRACK
92      : THE TABLE SHOULD BE:
93      :
94      : DB 00H,01H,00H,0AH,00H,02H,00H,0BH,00H,03H,00H,0CH
95      : DB 00H,04H,00H,0DH,00H,05H,00H,0EH,00H,06H,00H,0FH
96      : DB 00H,07H,00H,10H,00H,08H,00H,11H,00H,09H
97      :
98      :-----

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5-114 DISK

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188 PAGE
189
190
191 ;
192 ; HARDWARE SPECIFIC VALUES
193 ;
194 ; - CONTROLLER I/O PORT
195 ;
196 ; > WHEN READ FROM:
197 ; HF_PORT+0 - READ DATA (FROM CONTROLLER TO CPU)
198 ; HF_PORT+1 - GET ERROR REGISTER
199 ; HF_PORT+2 - GET SECTOR COUNT
200 ; HF_PORT+3 - GET SECTOR NUMBER
201 ; HF_PORT+4 - GET CYLINDER LOW
202 ; HF_PORT+5 - GET CYLINDER HIGH (2 BITS)
203 ; HF_PORT+6 - GET SIZE/DRIVE/HEAD
204 ; HF_PORT+7 - GET STATUS REGISTER
205 ;
206 ; > WHEN WRITTEN TO:
207 ; HF_PORT+0 - WRITE DATA (FROM CPU TO CONTROLLER)
208 ; HF_PORT+1 - SET PRECOMPENSATION CYLINDER
209 ; HF_PORT+2 - SET SECTOR COUNT
210 ; HF_PORT+3 - SET SECTOR NUMBER
211 ; HF_PORT+4 - SET CYLINDER LOW
212 ; HF_PORT+5 - SET CYLINDER HIGH (2 BITS)
213 ; HF_PORT+6 - SET SIZE/DRIVE/HEAD
214 ; HF_PORT+7 - SET COMMAND REGISTER
215 ;
216
217 = 01F0 HF_PORT EQU 01F0H ; DISK PORT
218 = 03F6 HF_REG_PORT EQU 03F6H
219
220 ;----- STATUS REGISTER
221
222 = 0001 ST_ERROR EQU 00000001B ;
223 = 0002 ST_INDEX EQU 00000010B ;
224 = 0004 ST_CORRCD EQU 00000100B ; ECC CORRECTION SUCCESSFUL
225 = 0008 ST_DRQ EQU 00001000B ;
226 = 0010 ST_SEEK_COMPL EQU 00010000B ; SEEK COMPLETE
227 = 0020 ST_WRT_FLT EQU 00100000B ; WRITE FAULT
228 = 0040 ST_READY EQU 01000000B ;
229 = 0080 ST_BUSY EQU 10000000B ;
230
231 ;----- ERROR REGISTER
232
233 = 0001 ERR_DAM EQU 00000001B ; DATA ADDRESS MARK NOT FOUND
234 = 0002 ERR_TRK_0 EQU 00000010B ; TRACK 0 NOT FOUND ON RECAL
235 = 0004 ERR_ABORT EQU 00000100B ; ABORTED COMMAND
236 = 0010 ERR_ID EQU 00001000B ; NOT USED
237 = 0020 ERR_ID EQU 00010000B ; ID NOT FOUND
238 = 0040 ERR_DATA_ECC EQU 01000000B ; NOT USED
239 = 0080 ERR_BAD_BLOCK EQU 10000000B ;
240
241
242
243 = 0010 RECAL_CMD EQU 00010000B ; DRIVE RECAL (10H)
244 = 0020 READ_CMD EQU 00100000B ; READ (20H)
245 = 0030 WRITE_CMD EQU 00110000B ; WRITE (30H)
246 = 0040 VERIFY_CMD EQU 01000000B ; VERIFY (40H)
247 = 0050 FMTRK_CMD EQU 01010000B ; FORMAT TRACK (50H)
248 = 0060 INIT_CMD EQU 01100000B ; INITIALIZE (60H)
249 = 0070 SEEK_CMD EQU 01110000B ; SEEK (70H)
250 = 0090 DIAG_CMD EQU 10010000B ; DIAGNOSTIC (90H)
251 = 0091 SET_PARM_CMD EQU 10010001B ; DRIVE PARMS (91H)
252 = 0001 NO_RETRIES EQU 00000001B ; CMD MODIFIER (01H)
253 = 0002 ECC_MODE EQU 00000010B ; CMD MODIFIER (02H)
254 = 0008 BUFFER_MODE EQU 00001000B ; CMD MODIFIER (08H)
255
256 = 0002 MAX_FILE EQU 2
257 = 0002 S_MAX_FILE EQU 2
258
259 = 0025 DELAY_1 EQU 25H ; DELAY FOR OPERATION COMPLETE
260 = 0600 DELAY_2 EQU 0600H ; DELAY FOR READY
261 = 0100 DELAY_3 EQU 0100H ; DELAY FOR DATA REQUEST
262
263 = 0008 HF_FAIL EQU 08H ; CMOS FLAG IN BYTE 0EH
264
265 ;----- COMMAND BLOCK REFERENCE
266
267 = *CMD_BLOCK EQU BYTE PTR [BP]-8 ; *CMD_BLOCK REFERENCES BLOCK HEAD IN SS
268 ; (BP) POINTS TO COMMAND BLOCK TAIL
269 ; AS DEFINED BY THE "ENTER" PARMS

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270                                     PAGE
271 -----
272                                     |
273                                     | FIXED DISK I/O SETUP
274                                     |
275                                     | - ESTABLISH TRANSFER VECTORS FOR THE FIXED DISK
276                                     | - PERFORM POWER ON DIAGNOSTICS
277                                     | SHOULD AN ERROR OCCUR A "I701" MESSAGE IS DISPLAYED
278                                     |
279 -----
280                                     ASSUME CS:CODE,DS:ABS0
281                                     | WORK OFF DS REGISTER
282
283 DISK_SETUP PROC NEAR
284     0000 FA ----- R
285     0001 8C 0E 004E R
286     0004 8E D8
287     0006 A1 004C R
288     0009 A3 0100 R
289     000C A1 004E R
290     000F A3 0102 R
291     0012 C7 06 004C R 01A9 R
292     0018 8C 0E 004E R
293     001C C7 06 01D8 R 06DA R
294     0022 8C 0E 01DA R
295     0026 C7 06 0104 R 0000 E
296     002C 8C 0E 0106 R
297     0030 C7 06 0118 R 0000 E
298     0036 8C 0E 011A R
299     003A E4 A1
300     003C 24 BF
301     003E EB 00
302     0040 E6 A1
303     0042 E4 21
304     0044 24 FB
305     0046 EB 00
306     0048 E6 21
307     004A FB
308     004B IE
309     004C 07
310     004E 06 0000 E
311     0050 C6 06 0074 R 00
312     0055 C6 06 0075 R 00
313     005A C6 06 0076 R 00
314     005F 80 8E
315     0061 E8 0000 E
316     0064 8A C0
317     0066 24 C0
318     0068 74 03
319     006A E9 00F8 R
320     006D
321     006D 80 E4 F7
322     0070 80 8E
323     0072 E8 0000 E
324     0075 80 92
325     0077 E8 0000 E
326     007A C6 06 0077 R 00
327     007F 8A D8
328     0081 25 00F0
329     0084 74 F2
330
331     0086 3C F0
332     0088 75 10
333
334     008A 80 99
335     008C EF 0000 E
336     008F 3C 00
337     0091 74 65
338     0093 3C 2F
339     0095 77 61
340     0097 C1 E0 04
341     009A
342     009A 05 FFF0 F
343     009D 261 A3 0104 R
344     00A1 C6 06 0075 R 01
345     00A6 8A C3
346     00AB C0 E0 04
347     00AB 74 2A
348     00AD B4 00
349
350     00AF 3C F0
351     00B1 75 10
352
353     00B3 80 9A
354     00B5 EF 0000 E
355     00B8 3C 00
356     00BA 74 1B
357     00BC 3C 2F
358     00BE 77 17
359     00C0 C1 E0 04
360     00C3
361     00C3 05 FFF0 F
362     00C6 8B D8
363     00C8 2E1 83 3F 00
364     00CC 74 09
365     00CE 261 A3 0118 R
366     00D2 C6 06 0075 R 02
367     00D7
368     00D7 B2 80
369     00D9 B4 14
370     00DB C0 13
371     00DD 72 1A
372     00DF A1 006C R
373     00E2 8B D8
374     00E4 05 0444
375     00E7 8B C8
376     00E9 EF 0104 R
377     00EC 80 3E 0075 R 01
378     00F1 76 01
379     00F3 B2 81
380     00F5 EF 0104 R
381     00F8
382     00F8 C3
383
384     STI DS:DATA,ESI:ABS0
385     PUSH DS
386     POP ES
387     CALL DDS
388     MOV 0DISK_STATUS,0
389     MOV 0HF_NUM,0
390     MOV 0CONTROL_BYTE,0
391     MOV AL,CMOS_DIAG+NM1
392     CALL CMOS_READ
393     MOV AH,AC
394     AND AL,BAD_BAD+BAD_CKSUM
395     JZ L1
396     JMP POD_DONE
397
398     AND AH,NOT HF_FAIL
399     MOV AL,CMOS_DIAG+NM1
400     CALL CMOS_WRITE
401     MOV AL,CMOS_DISK+NM1
402     CALL CMOS_READ
403     MOV 0PORT_OFF,0
404     MOV BL,AL
405     AND AX,00F0F0
406     JZ POD_DONE
407
408     CMP AL,0F0H
409     JNE L2
410
411     MOV AL,CMOS_DISK_1+NM1
412     CALL CMOS_READ
413     CMP AL,0
414     JE POD_DONE
415     CMP AL,47
416     JA POD_DONE
417     SHL AX,4
418
419     ADD AX,OFFSET FD_TBL-16D
420     MOV WORD PTR 0HF_TBL_VEC,AX
421     MOV 0HF_NUM,1
422     MOV AL,BL
423     SHL AL,4
424     JZ SHORT L4
425     MOV AH,0
426
427     CMP AL,0F0H
428     JNE L3
429
430     MOV AL,CMOS_DISK_2+NM1
431     CALL CMOS_READ
432     CMP AL,0
433     JE L4
434     CMP AL,47
435     JA L4
436     SHL AX,4
437
438     ADD AX,OFFSET FD_TBL-16D
439     MOV BX,AX
440     MOV WORD PTR CS:[BX],0
441     JE L4
442     MOV WORD PTR 0HF1_TBL_VEC,AX
443     MOV 0HF_NUM,2
444
445     MOV DL,80H
446     MOV AH,14H
447     INT 13H
448     JC CTL_ERRR
449     MOV AX,TIMER_LOW
450     MOV BX,AX
451     ADD AX,6*182
452     CX,AX
453     MOV 0D_RESET,1
454     CMP 0HF_NUM,1
455     JBE POD_DONE
456     MOV DL,81H
457     CALL 0D_RESET_1
458     RET
459
460     ; GET ABSOLUTE SEGMENT
461     ; SET SEGMENT REGISTER
462     ; GET DISKETTE VECTOR
463     ; INTO INT 40H
464     ; FIXED DISK HANDLER
465     ; FIXED DISK INTERRUPT
466     ; PARM TABLE DRIVE 80
467     ; PARM TABLE DRIVE 81
468     ; TURN ON SECOND INTERRUPT CHIP
469     ; LET INTERRUPTS PASS THRU TO
470     ; SECOND CHIP
471     ; CMOS NOT VALID -- NO FIXED DISKS
472     ; ALLOW FIXED DISK IPL
473     ; WRITE IT BACK
474     ; ZERO CARD OFFSET
475     ; SAVE FIXED DISK BYTE
476     ; GET FIRST DRIVE TYPE AS OFFSET
477     ; NO FIXED DISKS
478     ; CHECK FOR EXTENDED DRIVE TYPE BYTE USE
479     ; USE DRIVE TYPE 1 --> 14 IF NOT IN USE
480     ; GET EXTENDED TYPE FOR DRIVE C:
481     ; FROM CMOS
482     ; IS TYPE SET TO ZERO
483     ; EXIT IF NOT VALID AND NO FIXED DISKS
484     ; IS TYPE WITHIN VALID RANGE
485     ; EXIT WITH NO FIXED DISKS IF NOT VALID
486     ; ADJUST TYPE TO HIGH NIBBLE
487     ; COMPUTE OFFSET OF FIRST DRIVE TABLE
488     ; SAVE IN VECTOR POINTER
489     ; AT LEAST ONE DRIVE
490     ; GET SECOND DRIVE TYPE
491     ; ONLY ONE DRIVE
492     ; CHECK FOR EXTENDED DRIVE TYPE BYTE USE
493     ; USE DRIVE TYPE 1 --> 14 IF NOT IN USE
494     ; GET EXTENDED TYPE FOR DRIVE D:
495     ; FROM CMOS
496     ; IS TYPE SET TO ZERO
497     ; SKIP IF SECOND FIXED DISK NOT VALID
498     ; IS TYPE WITHIN VALID RANGE
499     ; SKIP IF NOT VALID
500     ; ADJUST TYPE TO HIGH NIBBLE
501     ; COMPUTE OFFSET FOR SECOND FIXED DISK
502     ; CHECK FOR ZERO CYLINDERS IN TABLE
503     ; SKIP DRIVE IF NOT A VALID TABLE ENTRY
504     ; TWO DRIVES
505     ; CHECK THE CONTROLLER
506     ; USE CONTROLLER DIAGNOSTIC COMMAND
507     ; CALL BIOS WITH DIAGNOSTIC COMMAND
508     ; DISPLAY ERROR MESSAGE IF BAD RETURN
509     ; GET START TIMER COUNTS
510     ; 60 SECONDS* 18.2
511     ; SET UP DRIVE 0
512     ; WERE THERE TWO DRIVES?
513     ; NO-ALL DONE
514     ; SET UP DRIVE 1

```

```

384          |----- POD ERROR
385
386          CTL_ERRX:
387      MOV     SI,OFFSET F1782
388      CALL    SET_FAIL
389      CALL    E_MSG
390      JMP     POD_DONE
391
392
393      HD_RESET: PROC NEAR
394          PUSH BX
395          PUSH CX
396          MOV AH,09H
397          INT 13H
398          JC RES_2
399          MOV AH,TIH
400          INT 13H
401          JNC RES_OK
402          CALL POD_TCHK
403          JNC RES_1
404          MOV SI,OFFSET F1781
405          JNC RES_1
406          JNZ RES_E1
407          MOV SI,OFFSET F1780
408          CALL SET_FAIL
409          JMP SHORT RES_E1
410          MOV AH,00H
411          INT 13H
412          MOV AH,08H
413          MOV BL,DL
414          INT 13H
415          JC RES_ER
416          MOV WORD PTR *NEC_STATUS,CX
417          MOV DL,BL
418          MOV AX,0401H
419          INT 13H
420          JNC RES_OK
421          CMP AH,BAD_SECTOR
422          JE RES_OK
423          CMP AH,DATA_CORRECTED
424          JE RES_OK
425          CMP AH,BAD_ECC
426          JE RES_OK
427          CALL POD_TCHK
428          JC RES_ER
429          MOV CX,WORD PTR *NEC_STATUS
430          MOV AL,CL
431          AND AL,3FH
432          DEC AL
433          JZ RES_RS
434          AND CL,0COH
435          OR CL,AL
436          MOV WORD PTR *NEC_STATUS,CX
437          JMP RES_3
438          MOV SI,OFFSET F1791
439          TEST JX,SI
440          JNZ RES_E1
441          MOV SI,OFFSET F1790
442          JNC RES_E1
443          CALL E_MSG
444          RET
445          POP CX
446          POP BX
447          RET
448          HD_RESET: ENDP
449
450      SET_FAIL: PROC NEAR
451          MOV AX,X*(CMOS_DIAG+NM1)
452          CALL CMOS_READ
453          OR AL,HP_FAIL
454          XCHG AH,AL
455          CALL CMOS_WRITE
456          RET
457          SET_FAIL: ENDP
458
459      POD_TCHK: PROC NEAR
460          POP AX
461          POP CX
462          POP BX
463          PUSH CX
464          PUSH CX
465          PUSH AX
466          MOV AX,*TIMER_LOW
467
468          CMP BX,CX
469          JB TCHK1
470          CMP BX,AX
471          JB TCHK2
472          JNC TCHK2
473          JNC TCHK2
474          CMP AX,BX
475          JB TCHKNG
476          CMP AX,CX
477          JB TCHKNG
478          TCHKNG: STC
479          RET
480          TCHKNG: CLC
481          RET
482          TCHKNG: RET
483
484      POD_TCHK: ENDP
485      DISK_SETUP: ENDP

```

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486 PAGE
487 -----
488 |----- FIXED DISK BIOS ENTRY POINT -----|
489 |-----|
490
491 01A9 DISK_IO PROC FAR
492 ASSUME DS:DATA,ES:NOTHING
493 01A9 80 FA 80 CMP DL,80H ; TEST FOR FIXED DISK DRIVE
494 01AC 75 05 JAE A1 ; YES, HANDLE HERE
495 01AE CD 40 INT 40H ; DISKETTE HANDLER
496 01B0 RET_2 RET 2 ; BACK TO CALLER
497 01B0 CA 0002
498
499 01B3 A1: STI ; ENABLE INTERRUPTS
500 01B3 FB OR AH,AH
501 01B4 0A E4 JNZ A2
502 01B6 75 09E JNZ A2 ; RESET NEC WHEN AH=0
503 01B8 CD 40 INT 40H
504 01BA 2A E4 SUB AH,AH
505 01BC 80 FA 81 CMP DL,(80H + S_MAX_FILE - 1)
506 01BF 77 EF JAE RET_2
507 01C1 80 FC 08 A2: CMP AH,08H ; GET PARAMETERS IS A SPECIAL CASE
508 01C4 75 03 JNZ A3
509 01C6 E9 0393 R JMP GET_PARM_N
510 01C9 80 FC 15 A3: CMP AH,75H ; READ DASD TYPE IS ALSO
511 01CC 75 03 JNZ A4
512 01CE E9 0353 R JMP READ_DASD_TYPE
513
514 01D1 A4: ; SAVE REGISTERS DURING OPERATION
515 01D1 C8 0008 00 ENTER 8,0 ; SAVE (BP) AND MAKE ROOM FOR *CMD_BLOCK
516 01D5 53 PUSH BX ; IN THE STACK, THE COMMAND BLOCK IS:
517 01D6 51 PUSH CX ; *CMD_BLOCK == BYTE PTR [BP]-8
518 01D7 52 PUSH DX
519 01D8 54 PUSH DS
520 01D9 06 PUSH ES
521 01DA 56 PUSH SI
522 01DB 57 PUSH DI
523 01DC 0A E4 OR AH,AH
524 01DE 75 02 JNZ A5 ; CHECK FOR RESET
525 01E0 B2 80 MOV DL,80H ; FORCE DRIVE 80 FOR RESET
526 01E2 E8 0225 R CALL DISK_IO_CONT ; PERFORM THE OPERATION
527 01E3 80 0000 E DD5 ; ESTABLISH SEGMENT
528 01E5 8A 26 0074 R MOV AH,*DISK_STATUS ; GET STATUS FROM OPERATION
529 01E8 80 FC 01 CMP AH,1 ; SET THE CARRY FLAG TO INDICATE
530 01EF F2 CMC ; SUCCESS OR FAILURE
531 01F0 5F POP DI ; RESTORE REGISTERS
532 01F1 5E POP SI
533 01F2 07 POP ES
534 01F3 1F POP DS
535 01F4 5A POP DX
536 01F5 59 POP CX
537 01F6 58 POP BX
538 01F7 C9 LEAVE
539 01F8 CA 0002 RET 2 ; ADJUST (SP) AND RESTORE (BP)
540 01FB DISK_IO ENDP ; THROW AWAY SAVED FLAGS
541
542 M: LABEL WORD ; FUNCTION TRANSFER TABLE
543 01FB 02C1 R DW DISK_RESET ; 000H
544 01FD 0315 R DW RETURN_STATUS ; 001H
545 01FF 031E R DW DISK_READ ; 002H
546 0201 0325 R DW DISK_WRITE ; 003H
547 0203 032C R DW DISK_VERIFY ; 004H
548 0205 033E R DW FMT_TRK ; 005H
549 0207 02B9 R DW BAD_COMMAND ; 006H FORMAT BAD SECTORS
550 0209 02B9 R DW BAD_COMMAND ; 007H FORMAT DRIVE
551 020B 02B9 R DW BAD_COMMAND ; 008H RETURN PARAMETERS
552 020D 03F1 R DW INIT_DRV ; 009H
553 020F 0423 R DW RD_LONG ; 00AH
554 0211 042A R DW WR_LONG ; 00BH
555 0213 0431 R DW DISK_SEEK ; 00CH
556 0215 02C1 R DW DISK_RESET ; 00DH
557 0217 02B9 R DW BAD_COMMAND ; 00EH READ BUFFER
558 0219 02B9 R DW BAD_COMMAND ; 00FH WRITE BUFFER
559 021B 044F R DW TST_RDY ; 010H
560 021D 0466 R DW HDISK_RECAL ; 011H
561 021F 02B9 R DW BAD_COMMAND ; 012H MEMORY DIAGNOSTIC
562 0221 02B9 R DW BAD_COMMAND ; 013H DRIVE DIAGNOSTIC
563 0223 048E R DW CTRL_DIAGNOSTIC ; 014H CONTROLLER DIAGNOSTIC
564 0225 = 002A EQU $-M
565
566 DISK_IO_CONT PROC NEAR
567 0225 E8 0000 E CALL DD5 ; ESTABLISH SEGMENT
568 0228 80 FC 01 CMP AH,01H ; RETURN STATUS
569 022B 75 03 JNZ SU0
570 022D E9 0315 R JMP RETURN_STATUS
571
572 SU0: MOV *DISK_STATUS,0 ; RESET THE STATUS INDICATOR
573 0230 C6 06 0074 R 00 BX ; SAVE DATA ADDRESS
574 0235 53 MOV BL,*HF_NUM ; GET NUMBER OF DRIVES
575 0236 8A 1E 0075 R AX ; GET DRIVE AS 0 OR 1
576 023A 50 PUSH AX
577 023B 80 E2 7F AND DL,7FH
578 023E 3A DA CMP BL,DL
579 0240 76 75 JBE BAD_COMMAND_POP ; INVALID DRIVE
580 0242 06 PUSH ES
581 0243 E8 06C4 R CALL GET_VEC ; GET DISK PARAMETERS
582 0246 26 88 47 05 MOV AX,WORD PTR ES:[BX][5] ; GET WRITE PRE-COMPENSATION CYLINDER
583 024A C1 E8 02 SHR AX,2
584 024D 88 46 F8 MOV *CMD_BLOCK,AL
585 0250 26 8A 47 08 MOV AL,BYTE PTR ES:[BX][8] ; GET CONTROL BYTE MODIFIER
586 0254 52 PUSH DX
587 0255 BA 03F6 MOV DX,*HF_REG_PORT
588 0258 EE OUT DX,AL ; SET EXTRA HEAD OPTION
589 0259 5A POP DX
590 025A 07 POP ES
591 025B 8A 26 0076 R MOV AH,*CONTROL_BYTE ; SET EXTRA HEAD OPTION IN
592 025F 80 E4 C0 AND AH,0C0H ; CONTROL BYTE
593 0262 0A E0 OR AH,AH
594 0264 88 26 0076 R MOV *CONTROL_BYTE,AH
595 0268 58 POP AX
596 0269 88 46 F9 MOV *CMD_BLOCK+1,AL ; SECTOR COUNT
597 026C 50 PUSH AX
598 026D 8A C1 MOV AL,CL ; GET SECTOR NUMBER
599 026F 2A 3F AND AL,3FH

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600 0271 88 46 FA      MOV     @CMD_BLOCK+2,AL
601 0274 88 6E FB      MOV     @CMD_BLOCK+3,CH
602 0277 8A C1         MOV     AL,CL
603 0279 C0 E8 06      SHR     AL,6
604 027C 88 46 FC      MOV     @CMD_BLOCK+4,AL
605 027F 8A C2         MOV     AL,DL
606 0281 C0 E0 04      SHL     AL,4
607 0284 80 E6 0F      AND     DH,0FH
608 0287 0A C6         OR      AL,DH
609 0289 0C A0         OR      AL,80H OR 20H
610 028B 88 46 FD      MOV     @CMD_BLOCK+5,AL
611 028E 58             POP     AX
612 028F 50             PUSH  AX
613 0290 8A C4         MOV     AL,AH
614 0292 32 E4         XOR     AH,AH
615 0294 D1 E0         SAL     AX,1
616 0296 88 F0         MOV     SI,AX
617 0298 3D 002A       CMP     AX,MIL
618 029B 73 1A         JNB     BAD_COMMAND_POP
619 029D 58             POP     AX
620 029E 58             POP     BX
621 029F 51             PUSH  CX
622 02A0 50             PUSH  AX
623 02A1 88 CB         MOV     CX,BX
624 02A3 C1 E9 04      SHR     CX,4
625 02A6 8C 0C         MOV     AX,ES
626 02A8 03 C1         ADD     AX,CX
627 02AA 88 C0         MOV     ES,AX
628 02AC 81 E3 000F    AND     BX,000FH
629 02B0 58             POP     AX
630 02B1 59             POP     CX
631 02B2 2E 1F FF A4 01FB R JMP     WORD PTR CS:[SI + OFFSET MI]
632 02B7             BAD_COMMAND_POP:
633 02B7 58             POP     AX
634 02B8 58             POP     BX
635 02B9             BAD_COMMAND:
636 02B9 C6 06 0074 R 01 MOV     @DISK_STATUS1,BAD_CMD
637 02BE 80 00         MOV     AL,0
638 02C0 C3             RET
639 02C1             DISK_IO_CONT ENDP
640
641 -----
642             RESET THE DISK SYSTEM (AH=00H)
643 -----
644
645 02C1             DISK_RESET PROC NEAR
646 02C1 FA             CLI
647 02C2 E4 A1          IN      AL,INTB01
648 02C4 E8 00          JMP     $+2
649 02C6 24 BF          AND     AL,0BFH
650 02C8 E6 A1          OUT     INTB01,AL
651 02CA FB             STI
652 02CB 80 04          MOV     AL,04H
653 02CD 9A 03F6        MOV     DX,HF_REG_PORT
654 02D0 EE             OUT     DX,AL
655 02D1 B9 000A        MOV     CX,10
656 02D4 49             DEC     CX
657 02D5 75 FD          JNZ     DRD
658 02D7 A0 0076 R      MOV     AL,@CONTROL_BYTE
659 02DA 24 0F          AND     AL,0FH
660 02DC EE             OUT     DX,AL
661 02DD E8 05F3 R      CALL  NOT_BUSY
662 02E0 75 2D          JNZ     DRERR
663 02E2 BA 01F1        MOV     DX,HF_PORT+1
664 02E5 EC             IN      AL,DX
665 02E6 3C 01          CMP     AL,1
666 02E8 75 25          JNZ     DRERR
667 02EA 80 66 FD EF    SUB     DL,DL
668 02EE 2A D2          MOV     DL,DL
669 02F0 E8 03F1 R      CALL  INIT_DRV
670 02F3 E8 0466 R      CALL  HDISK_RECAL
671 02F6 80 3E 0075 R 01 CMP     @HF_NUM,1
672 02F8 76 0C          JBE     DRE
673 02FD 80 4E FD 10    OR      @CMD_BLOCK+5,010H
674 0301 B2 01          MOV     DL,1
675 0303 E8 03F1 R      CALL  INIT_DRV
676 0306 E8 0466 R      CALL  HDISK_RECAL
677 0309 C6 06 0074 R 00 DRE: MOV     @DISK_STATUS1,0
678 030E C3             RET
679 030F C6 06 0074 R 05 DRERR: MOV     @DISK_STATUS1,BAD_RESET
680 0314 C3             RET
681 0315             DISK_RESET ENDP
682
683 -----
684             DISK STATUS ROUTINE (AH = 01H)
685 -----
686
687 0315             RETURN_STATUS PROC NEAR
688 0315 A0 0074 R      MOV     AL,@DISK_STATUS1
689 0318 C6 06 0074 R 00 MOV     @DISK_STATUS1,0
690 031D C3             RET
691 031E             RETURN_STATUS ENDP

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692 PAGE
693
694
695
696
697 031E
698 031E C6 46 FE 20
699 0322 E9 04C6 R
700 0325
701
702
703
704
705
706 0325
707 0325 C6 46 FE 30
708 0329 E9 0505 R
709 032C
710
711
712
713
714
715 032C
716 032C C6 46 FE 40
717 0330 E8 055C R
718 0333 75 08
719 0335 E8 05C2 R
720 0338 75 03
721 033A E8 0630 R
722 033D
723 033D C3
724 033E
725
726
727
728
729
730 033E
731 033E C6 46 FE 50
732 0342 06
733 0343 53
734 0344 E8 06C4 R
735 0347 26 8A 47 0E
736 034B 8B 46 F9
737 034E 5B
738 034F 07
739 0350 E9 050A R
740 0353
741
742
743
744
745
746
747 0353
748 0353
749 0353 IE
750 0354 06
751 0355 53
752
753 0356 E8 0000 E
754 0359 C6 06 0074 R 00
755 035E 8A IE 0075 R
756 0362 80 E2 7F
757 0365 3A DA
758 0367 76 22
759 0369 E8 06C4 R
760 036C 26 8A 47 02
761 0370 26 8A 4F 0E
762 0374 F6 E9
763 0376 26 8B 0F
764 0379 49
765 037A F7 E9
766 037C 8B CA
767 037E 8B D0
768 0380 2B C0
769 0382 B4 03
770 0384 5B
771 0385 07
772 0386 1F
773 0387 F8
774 0388 CA 0002
775 038B
776 038B 2B C0
777 038D 8B C8
778 038F 8B D0
779 0391 E8 F1
780 0393

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PAGE
-----
DISK READ ROUTINE (AH = 02H) :
-----
DISK_READ PROC NEAR
MOV @CMD_BLOCK+6,READ_CMD
JMP COMMAND1
DISK_READ ENDP
-----
DISK WRITE ROUTINE (AH = 03H) :
-----
DISK_WRITE PROC NEAR
MOV @CMD_BLOCK+6,WRITE_CMD
JMP COMMAND0
DISK_WRITE ENDP
-----
DISK VERIFY (AH = 04H) :
-----
DISK_VERIFY PROC NEAR
MOV @CMD_BLOCK+6,VERIFY_CMD
CALL COMMAND
JNZ VERF_EXIT ; CONTROLLER STILL BUSY
CALL WAIT
JNZ VERF_EXIT ; TIME OUT
CALL CHECK_STATUS
VERF_EXIT:
RET
DISK_VERIFY ENDP
-----
FORMATTING (AH = 05H) :
-----
FMT_TRK PROC NEAR
MOV @CMD_BLOCK+6,FMTTRK_CMD
ES
PUSH BX
CALL GET_VEC ; GET DISK PARAMETERS ADDRESS
MOV AL,ESI[BX][14] ; GET SECTORS/TRACK
MOV @CMD_BLOCK+1,AL ; SET SECTOR COUNT IN COMMAND
POP BX
POP ES
JMP CMD_OF ; GO EXECUTE THE COMMAND
FMT_TRK ENDP
-----
READ DASD TYPE (AH = 15H) :
-----
READ_DASD_TYPE LABEL NEAR
READ_D_T PROC FAR ; GET DRIVE PARAMETERS
; SAVE REGISTERS
PUSH DS
PUSH ES
PUSH BX
ASSUME DS:DATA
CALL DOS ; ESTABLISH ADDRESSING
MOV @DISK_STATUS,0
MOV BL,@HF_NUM ; GET NUMBER OF DRIVES
AND DL,7FH ; GET DRIVE NUMBER
CMP BL,DL
JBE RDT_NOT_PRESENT ; RETURN DRIVE NOT PRESENT
CALL GET_VEC ; GET DISK PARAMETER ADDRESS
MOV AL,ESI[BX][2]
MOV CL,ESI[BX][14]
IMUL CL ; * NUMBER OF SECTORS
MOV CX,ESI[BX] ; MAX NUMBER OF CYLINDERS
DEC CX ; LEAVE ONE FOR DIAGNOSTICS
IMUL CX ; NUMBER OF SECTORS
MOV DX,CX ; HIGH ORDER HALF
MOV AX,DX ; LOW ORDER HALF
SUB AX,AX
MOV AH,03H ; INDICATE FIXED DISK
RDT2: POP BX ; RESTORE REGISTERS
POP ES
POP DS
CLC ; CLEAR CARRY
RET 2
RDT_NOT_PRESENT: SUB AX,AX ; DRIVE NOT PRESENT RETURN
MOV CX,AX ; ZERO BLOCK COUNT
MOV DX,AX
JMP RDT2
READ_D_T ENDP

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SECTION 5

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894                                     PAGE
895                                     :-----:
896                                     : TEST DISK READY      (AH = 10H) :
897                                     :-----:
898
899 044F TST_RDY PROC      NEAR
900 044F E8 05F3 R      CALL NOT_BUSY      ; WAIT FOR CONTROLLER
901 0452 75 11          JNZ  TR_EX         ;
902 0454 BA 46 FD      MOV  AL,RCMD_BLOCK+5 ; SELECT DRIVE
903 0457 BA 01F6      MOV  DX,HF_PORT+6
904 045A EE            OUT  DX,AL
905 045B E8 0642 R      CALL CHECK_ST      ; CHECK STATUS ONLY
906 045E 75 05          JNZ  TR_EX         ;
907 0460 C6 06 0074 R 00 MOV  #0DISK_STATUS1,0 ; WIPE OUT DATA CORRECTED ERROR
908 0465 C3            RET
909 0466 TST_RDY ENDP
910
911                                     :-----:
912                                     : RECALIBRATE        (AH = 11H) :
913                                     :-----:
914
915 0466 HDISK_RECAL      PROC  NEAR
916 0466 C6 46 FE 10    MOV  #64K_BLOCK+6,RECAL_CMD ; START THE OPERATION
917 046A E8 055C R      CALL COMMAND      ; ERROR
918 046D 75 19          JNZ  RECAL_EXIT    ; WAIT FOR COMPLETION
919 046F E8 05C2 R      CALL WAIT         ; TIME OUT ONE OK ?
920 0472 74 05          JZ   RECAL_X       ; WAIT FOR COMPLETION LONGER
921 0474 E8 05C2 R      CALL WAIT         ; TIME OUT TWO TIMES IS ERROR
922 0477 75 0F          JNZ  RECAL_EXIT
923 0479 RECAL_X         CALL CHECK_STATUS ; SEEK NOT COMPLETE
924 0479 E8 0630 R      CALL CMP          #DISK_STATUS1,BAD_SEEK ; IS OK
925 047C 80 3E 0074 R 40 JNE  RECAL_EXIT
926 0481 75 05          JNZ  RECAL_EXIT    ;
927 0483 C6 06 0074 R 00 MOV  #DISK_STATUS1,0
928 0488 RECAL_EXIT:    CMP  #DISK_STATUS1,0
929 0488 80 3E 0074 R 00 JNE  RET
930 048D C3            RET
931 048E HDISK_RECAL    ENDP
932
933                                     :-----:
934                                     : CONTROLLER DIAGNOSTIC (AH = 14H) :
935                                     :-----:
936
937 048E CTLR_DIAGNOSTIC PROC  NEAR
938 048E FA            CLT
939 048F EA A1          IN  AL,INTB01      ; DISABLE INTERRUPTS WHILE CHANGING MASK
940 0491 24 BF          AND  AL,0BFH      ; TURN ON SECOND INTERRUPT CHIP
941 0493 EB 00          JMP  $+2
942 0495 EA A1          OUT INTB01,AL
943 0497 EA 21          IN  AL,INTA01
944 0499 24 FB          AND  AL,0FBH
945 049B EB 00          JMP  $+2
946 049D EA 21          OUT INTA01,AL
947 049F FB            STI
948 04A0 E8 05F3 R      CALL NOT_BUSY      ; WAIT FOR CARD
949 04A3 75 1A          JNZ  CD_ERR        ; BAD CARD
950 04A5 BA 01F7      MOV  AL,D1X_CMD
951 04A8 B0 90          MOV  AL,D1X_CMD
952 04AA EE            OUT  DX,AL
953 04AB E8 05F3 R      CALL NOT_BUSY      ; START DIAGNOSE
954 04AE B4 80          MOV  AH,TIME_OUT   ; WAIT FOR IT TO COMPLETE
955 04B0 75 0F          JNZ  CD_EXIT        ; TIME OUT ON DIAGNOSTIC
956 04B2 BA 01F1      MOV  DX,HF_PORT+1   ; GET ERROR REGISTER
957 04B5 EC            IN  AL,DX
958 04B6 A2 00B0 R      MOV  #HF_ERROR,AL   ; SAVE IT
959 04B9 B4 00          MOV  AH,0
960 04BB 3C 01          CMP  AL,1
961 04BD 74 02          JZ   SHORT_CD_EXIT ; CHECK FOR ALL OK
962 04BF B4 20          MOV  AH,BAD_CRTL
963 04C1 CD_ERR: MOV  #DISK_STATUS1,AH
964 04C1 85 26 0074 R  MOV  RET
965 04C5 C3            RET
966 04C6 CTLR_DIAGNOSTIC ENDP
967
968                                     :-----:
969                                     : COMMAND1
970                                     : REPEATEDLY INPUTS DATA TILL
971                                     : NSECTOR RETURNS ZERO
972                                     :-----:
973 04C6 COMMAND1:      CALL CHECK_DMA      ; CHECK 64K BOUNDARY ERROR
974 04C6 E8 06A1 R      CALL CMD_ABORT    ;
975 04C9 72 39          MOV  DI,BX
976 04CB 8B FB          CALL CMD_COMMAND ; OUTPUT COMMAND
977 04CD E8 055C R      JNZ  CMD_ABORT
978 04D0 75 32          JZ   CMD_111
979 04D2 E8 05C2 R      CALL WAIT         ; WAIT FOR DATA REQUEST INTERRUPT
980 04D5 75 2D          JNZ  TM_OUT        ; TIME OUT
981 04D7 B9 0100      MOV  CX,256D
982 04D7 B9 0100      MOV  DX,HF_PORT
983 04DA BA 01F0      CLT
984 04DD FA            CLD
985 04DE FC            REP  INS#          ; GET THE SECTOR
986 04DF F3/ 6D        TEST #CMD_BLOCK+6,ECC_MODE ; CHECK FOR NORMAL INPUT
987 04E1 FB            JZ   CMD_T3
988 04E2 F6 46 FE 02    JZ   CMD_T3
989 04E6 74 12          CALL WAIT_DRQ     ; WAIT FOR DATA REQUEST
990 04E8 E8 061A R      JC   TM_OUT
991 04EB 72 17          MOV  DX,HF_PORT
992 04ED BA 01F0      MOV  CX,4
993 04F0 B9 0004      MOV  AL,DX
994 04F3 EC            IN  ES1BYTE_PTR [DI],AL ; GO SLOW FOR BOARD
995 04F4 26 18 05      INC  DI
996 04F7 47            LOOP CMD_12
997 04F8 E2 F9          JNZ  CMD_12
998 04FA E8 0630 R      CALL CHECK_STATUS ; ERROR RETURNED
999 04FD 75 05          JNZ  CMD_ABORT    ; CHECK FOR MORE
1000 04FF FE 4E F9      DEC  #CMD_BLOCK+1
1001 0502 74 CE          JNZ  SHORT_CMD_11
1002 0504 CMD_ABORT:      TM_OUT:
1003 0504 RET
1004 0504 C3

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1005 PAGE
1006 |-----|
1007 | COMMAND |
1008 | REPEATEDLY OUTPUTS DATA TILL |
1009 | NSECTOR RETURNS ZERO |
1010 |-----|
1011 0505 COMMAND0:
1012 0505 EB 06A1 R CALL CHECK_DMA ; CHECK 64K BOUNDARY ERROR
1013 0508 T2 FA JC CMD_ABORT
1014 050A BB F3 CMD_OF: MOV S1,BX
1015 050C EB 055C R CALL COMMAND ; OUTPUT COMMAND
1016 050F T5 F3 JNZ CMD_ABORT
1017 0511 EB 061A R CALL WAIT_DRQ ; WAIT FOR DATA REQUEST
1018 0514 T2 EE JC TM_OUT ; TOO LONG
1019 0516 IE CMD_O1: PUSH DS
1020 0517 06 PUSH ES ; MOVE ES TO DS
1021 0518 IF POP DS
1022 0519 B9 0100 MOV CX,2560 ; PUT THE DATA OUT TO THE CARD
1023 051C BA 01F0 MOV DX,HF_PORT
1024 051F FA CLJ
1025 0520 FC CLD
1026 0521 F3 / 6F REP OUTSW
1027 0523 FB STI
1028 0524 IF POP DS ; RESTORE DS
1029 0525 F6 46 FE 02 TEST *CMD_BLOCK+6,ECC_MODE ; CHECK FOR NORMAL OUTPUT
1030 0529 T4 12 JZ CMD_D3
1031 052B EB 061A R CALL WAIT_DRQ ; WAIT FOR DATA REQUEST
1032 052E T2 D4 JC TM_OUT
1033 0530 BA 01F0 MOV DX,HF_PORT
1034 0533 B9 0004 MOV CX,4 ; OUTPUT THE ECC BYTES
1035 0536 261 8A 04 CMD_O2: MOV AL,ES1BYTE PTR [S1]
1036 0539 EE OUT DX,AL
1037 053A 46 INC S1
1038 053B E2 F9 LOOP CMD_O2
1039 053D CMD_O3:
1040 053D EB 05C2 R CALL WAIT ; WAIT FOR SECTOR COMPLETE INTERRUPT
1041 0540 T5 C2 JNZ TM_OUT ; ERROR RETURNED
1042 0542 EB 0630 R CALL CHECK_STATUS
1043 0545 T5 B0 JC CMD_ABORT
1044 0547 F6 06 008C R 08 TEST *HF_STATUS,ST_DRQ ; CHECK FOR MORE
1045 054C T5 C8 JNZ SHORT_CMD_01
1046 054E BA 01F2 MOV DX,HF_PORT+2 ; CHECK RESIDUAL SECTOR COUNT
1047 0551 EC IN AL,DX
1048 0552 A8 FF TEST AL,OFFH
1049 0554 T4 05 JZ CMD_04 ; COUNT = 0 OK
1050 0556 C6 06 0074 R BB MOV *DISK_STATUS!,UNDEF_ERR ; OPERATION ABORTED - PARTIAL TRANSFER
1051 0558 CMD_04:
1052 055B C3 RET
1053
1054 |-----|
1055 | COMMAND |
1056 | THIS ROUTINE OUTPUTS THE COMMAND BLOCK |
1057 | OUTPUT |
1058 | BL = STATUS |
1059 | BH = ERROR REGISTER |
1060 |-----|
1061
1062 055C COMMAND PROC NEAR
1063 055C 53 PUSH BX
1064 055D B9 0600 MOV CX,DELAY_2 ; WAIT FOR SEEK COMPLETE AND READY
1065 0560 51 ; SET INITIAL DELAY BEFORE TEST
1066 0560 51 COMMAND1:
1067 0561 EB 044F R PUSH CX
1068 0564 59 CALL TST_RDY ; CHECK DRIVE READY
1069 0565 T4 08 POP CX
1070 0567 80 3E 0074 R 80 CMP *DISK_STATUS!,TIME_OUT ; DRIVE IS READY
1071 056C T4 48 JZ CMD_TIMEOUT ; TST_RDY TIMED OUT--GIVE UP
1072 056E E2 F9 LOOP CMD1
1073 0570 EB 49 JMP SHORT_COMMAND4 ; KEEP TRYING FOR A WHILE
1074 0572 COMMAND2:
1075 0572 5B POP BX
1076 0573 51 PUSH D1
1077 0574 C6 06 008E R 00 MOV *HF_INT_FLAG,0 ; RESET INTERRUPT FLAG
1078 0579 FA CLI ; INHIBIT INTERRUPTS WHILE CHANGING MASK
1079 057A E4 A1 IN AL,INTB01 ; TURN ON SECOND INTERRUPT CHIP
1080 057C 24 BF AND AL,0BFH
1081 057E EB 00 JMP $+2
1082 0580 E6 A1 OUT INTB01,AL
1083 0582 E4 21 IN AL,INTA01 ; LET INTERRUPTS PASS THRU TO
1084 0584 24 FB AND AL,0FBH ; SECOND CHIP
1085 0586 EB 00 JMP $+2
1086 0588 E6 21 OUT INTA01,AL
1087 058A FB STI
1088 058B 33 FF XOR D1,D1 ; INDEX THE COMMAND TABLE
1089 058D BA 01F1 MOV DX,HF_PORT+1 ; DISK ADDRESS
1090 0590 F6 06 0076 R C0 TEST *CONTROL_BYTE,0C0H ; CHECK FOR RETRY SUPPRESSION
1091 0595 T4 11 JZ COMMAND3
1092 0597 8A 46 FE MOV AL,*CMD_BLOCK+6 ; YES-GET OPERATION CODE
1093 059A 24 F0 AND AL,0F0H ; GET RID OF MODIFIERS
1094 059C 3C 20 CMP AL,20H ; 20H-40H IS READ, WRITE, VERIFY
1095 059E T2 08 JB J1
1096 05A0 3C 40 CMP AL,40H
1097 05A2 77 04 JA COMMAND3
1098 05A4 80 4E FE 01 OR *CMD_BLOCK+6,NO_RETRIES ; VALID OPERATION FOR RETRY SUPPRESS
1099 05A8 COMMAND3:
1100 05AB 8A 43 F8 MOV AL,[*CMD_BLOCK+D1] ; GET THE COMMAND STRING BYTE
1101 05AB EE OUT DX,AL ; GIVE IT TO CONTROLLER
1102 05AC 47 INC D1 ; NEXT BYTE IN COMMAND BLOCK
1103 05AD 42 INC DX ; NEXT DISK ADAPTER REGISTER
1104 05AE 81 FA 01F8 CMP DX,HF_PORT+8 ; ALL DONE?
1105 05B2 T5 F4 JNZ COMMAND3 ; NO--GO DO NEXT ONE
1106 05B4 5F POP D1
1107 05B5 C3 RET ; ZERO FLAG IS SET
1108 05B6
1109 05B6 C6 06 0074 R 20 CMD_TIMEOUT: MOV *DISK_STATUS!,BAD_CNTRLR
1110 05B8 5B CMD4:
1111 05B8 5B POP BX
1112 05BC 80 3E 0074 R 00 CMP *DISK_STATUS!,0 ; SET CONDITION CODE FOR CALLER
1113 05C1 C3 RET
1114 05C2 COMMAND ENDP

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1115 PAGE
1116
1117 |-----|
1118 | WAIT FOR INTERRUPT |
1119 |-----|
1119 05C2 WAIT PROC NEAR
1120 05C2 FB STI | MAKE SURE INTERRUPTS ARE ON
1121 05C3 2B C9 SUB CX,CX | SET INITIAL DELAY BEFORE TEST
1122 05C5 F8 CLC
1123 05C6 B8 9000 MOV AX,9000H | DEVICE WAIT INTERRUPT
1124 05C9 CD 15 INT 15H |
1125 05CB 72 0F JC WT2 | DEVICE TIMED OUT
1126
1127 05CD B3 25 MOV BL,DELAY_1 | SET DELAY COUNT
1128
1129 |-----|
1129 05CF F6 06 00BE R 80 WT1: TEST 06H_INT_FLAG,80H | TEST FOR INTERRUPT
1130 05D1 E1 F9 LOOPZ WT1 |
1131 05D4 75 0B JNZ WT3 | INTERRUPT--LETS GO
1132 05D8 FE CB DEC BL |
1133 05DA 75 F3 JNZ WT1 | KEEP TRYING FOR A WHILE
1134
1135 05DC C6 06 0074 R 80 WT2: MOV 0DISK_STATUS1,TIME_OUT | REPORT TIME OUT ERROR
1136 05E1 EB 0A JMP SHORT_WT4
1137 05E3 C6 06 0074 R 80 WT3: MOV 0DISK_STATUS1,0
1138 05E8 C6 06 00BE R 80 WT4: MOV 06H_INT_FLAG,0
1139 05ED 80 3E 0074 R 80 WT4: CMP 0DISK_STATUS1,0 | SET CONDITION CODE FOR CALLER
1140 05F2 C3 RET
1141 05F3 WAIT ENDP
1142
1143 |-----|
1143 05F3 | WAIT FOR CONTROLLER NOT BUSY |
1144 |-----|
1144 05F3 NOT_BUSY PROC NEAR
1145
1146 05F3 FB STI | MAKE SURE INTERRUPTS ARE ON
1147 05F4 53 PUSH BX
1148 05F5 2B C9 SUB CX,CX | SET INITIAL DELAY BEFORE TEST
1149 05F7 BA 01F7 MOV DX,HF_PORT+7
1150 05FA B3 25 MOV BL,DELAY_1
1151 05FC EC IN AL,DX | CHECK STATUS
1152 05FD A8 80 TEST AL,ST_BUSY
1153 05FF 0E FB LOOPNZ NB1 |
1154 0601 74 0B JZ NB2 | NOT BUSY--LETS GO
1155 0603 FE CB DEC BL
1156 0605 75 F5 JNZ NB1 | KEEP TRYING FOR A WHILE
1157 0607 C6 06 0074 R 80 NB2: MOV 0DISK_STATUS1,TIME_OUT | REPORT TIME OUT ERROR
1158 060C EB 05 JMP SHORT_NB3
1159 060E C6 06 0074 R 80 NB2: MOV 0DISK_STATUS1,0
1160 0613 5B POP BX
1161 0614 80 3E 0074 R 80 NB3: CMP 0DISK_STATUS1,0 | SET CONDITION CODE FOR CALLER
1162 0619 C3 RET
1163 061A NOT_BUSY ENDP
1164
1165 |-----|
1165 061A | WAIT FOR DATA REQUEST |
1166 |-----|
1166 061A WAIT_DRQ PROC NEAR
1167
1168 061A B9 0100 MOV CX,DELAY_3
1169 061D BA 01F7 MOV DX,HF_PORT+7
1170 0620 EC IN AL,DX | GET STATUS
1171 0621 A8 08 TEST AL,ST_DRQ | WAIT FOR DRQ
1172 0623 75 09 JNZ WQ_OK
1173 0625 E2 F9 LOOP WQ_1 | KEEP TRYING FOR A SHORT WHILE
1174 0627 C6 06 0074 R 80 WQ_1: MOV 0DISK_STATUS1,TIME_OUT | ERROR
1175 062C F9 STC
1176 062D C3 RET
1177 062E F8 WQ_OK: CLC
1178 062F C3 RET
1179 0630 WAIT_DRQ ENDP
1180
1181 |-----|
1181 0630 | CHECK FIXED DISK STATUS |
1182 |-----|
1182 0630 CHECK_STATUS PROC NEAR
1183
1184 0630 E8 0642 R CALL CHECK_ST | CHECK THE STATUS BYTE
1185 0633 75 07 JNZ CHECK_S1 | AN ERROR WAS FOUND
1186 0635 A8 01 TEST AL,ST_ERROR | WERE THERE ANY OTHER ERRORS
1187 0637 74 03 JZ CHECK_S1 | NO ERROR REPORTED
1188 0639 E8 0676 R CALL CHECK_ER | ERROR REPORTED
1189 063C CHECK_S1: MOV 0DISK_STATUS1,0 | SET STATUS FOR CALLER
1190 063C CMP RET
1191 0641 C3 RET
1192 0642 CHECK_STATUS ENDP
1193
1194 |-----|
1194 0642 | CHECK FIXED DISK STATUS BYTE |
1195 |-----|
1195 0642 CHECK_ST PROC NEAR
1196
1197 0642 BA 01F7 MOV DX,HF_PORT+7 | GET THE STATUS
1198 0645 EC IN AL,DX
1199 0646 A2 00BC R MOV 06H_STATUS,AL
1200 0649 B4 00 MOV AH,0
1201 064B A8 80 TEST AL,ST_BUSY | IF STILL BUSY
1202 064D 75 1A JNZ CKST_EXIT | REPORT OK
1203 064F B4 CC MOV AH,WRITE_FAULT
1204 0651 A6 20 TEST AL,ST_WRT_FLT | CHECK FOR WRITE FAULT
1205 0653 75 14 JNZ CKST_EXIT
1206 0655 B4 AA MOV AH,NOT_RDY
1207 0657 A8 40 TEST AL,ST_READY | CHECK FOR NOT READY
1208 0659 74 0E JZ CKST_EXIT
1209 065B B4 40 MOV AH,BIO_SEEK
1210 065D A8 10 TEST AL,ST_SEEK_COMPL | CHECK FOR SEEK NOT COMPLETE
1211 065F 74 08 JZ CKST_EXIT
1212 0661 B4 11 MOV AH,BIO_CORRECTED
1213 0663 A8 04 TEST AL,ST_CORRECTD | CHECK FOR CORRECTED ECC
1214 0665 75 02 JNZ CKST_EXIT
1215 0667 B4 00 MOV AH,0
1216 0669 CKST_EXIT:
1217 0669 88 26 0074 R MOV 0DISK_STATUS1,AH | SET ERROR FLAG
1218 066D 80 FC 11 CMP AH,DATA_CORRECTED | KEEP GOING WITH DATA CORRECTED
1219 0670 74 03 JZ CKST_EXIT
1220 0672 80 FC 00 CMP AH,0
1221 0675 CKST_EXIT: RET
1222 0676 CHECK_ST ENDP

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1228                                     PAGE
1229                                     |-----|
1230                                     | CHECK FIXED DISK ERROR REGISTER |
1231                                     |-----|
1232 0676 CHECK_ER PROC NEAR
1233 0676 BA 01F1 MOV DX,HF_PORT+1 ; GET THE ERROR REGISTER
1234 0679 EC IN AL,DX
1235 067A A2 008D R MOV #HF_ERROR,AL
1236 067D 53 PUSH BX
1237 067E B9 0008 MOV CX,8 ; TEST ALL 8 BITS
1238 0681 D0 E3 SHL AL,1 ; MOVE NEXT ERROR BIT TO CARRY
1239 0683 72 D2 JC CK2 ; FOUND THE ERROR
1240 0685 E2 FA LOOP CK1 ; KEEP TRYING
1241 0687 BB 0698 R CK2: MOV BX,OFFSET ERR_TBL ; COMPUTE ADDRESS OF
1242 068A 03 D9 ADD BX,CX ; ERROR CODE
1243 068C 2E1 8A 27 MOV AH,BYTE PTR CS:[BX] ; GET ERROR CODE
1244 068F 85 26 0074 R CKEX: MOV #DISK_STATUS1,AH ; SAVE ERROR CODE
1245 0693 5B POP BX
1246 0694 80 FC 00 CMP AH,0
1247 0697 C3 RET
1248 0698 E0 ERR_TBL DB NO_ERR
1249 0699 02 40 01 BB DB BAD_ADDR MARK,BAD SEEK,BAD CMD,UNDEF_ERR
1250 069D 04 BB 10 0A DB RECORD_NOT_FND,UNDEF_ERR,BAD_ECC,BAD_SECTOR
1251 06A1 CHECK_ER ENDP
1252
1253 |-----|
1254 | CHECK DMA |
1255 | -CHECK ES:BX AND # SECTORS TO MAKE SURE THAT IT WILL |
1256 | FIT WITHOUT SEGMENT OVERFLOW. |
1257 | -ES:BX HAS BEEN REVISED TO THE FORMAT SSSS:000X |
1258 | -OK IF # SECTORS < 80H (7FH IF LONG READ OR WRITE) |
1259 | -OK IF # SECTORS = 80H (7FH) AND BX <= 00H (04H) |
1260 | -ERROR OTHERWISE |
1261 |-----|
1262 06A1 CHECK_DMA PROC NEAR
1263 06A1 50 PUSH AX ; SAVE REGISTERS
1264 06A2 BB 8000 MOV AX,8000H ; AH = MAX # SECTORS AL = MAX OFFSET
1265 06A5 F6 4E 02 TEST #CMD_BLOCK+6,ECC_MODE
1266 06A9 74 03 JZ CKD1
1267 06AB B8 7F04 MOV AX,7F04H ; ECC IS 4 MORE BYTES
1268 06AE 3A 66 F9 CMP AH,CMD_BLOCK+1 ; NUMBER OF SECTORS
1269 06B1 77 06 JA CKDOK ; IT WILL FIT
1270 06B3 72 07 JB CKDERR ; TOO MANY
1271 06B5 3A C3 CMP AL,BL ; CHECK OFFSET ON MAX SECTORS
1272 06B7 72 03 JB CKDERR ; ERROR
1273 06B9 F6 CLC ; CLEAR CARRY
1274 06BA 58 POP AX
1275 06BB C3 RET ; NORMAL RETURN
1276 06BC F9 STC ; INDICATE ERROR
1277 06BD C6 06 0074 R 09 CKDERR: MOV #DISK_STATUS1,DMA_BOUNDARY
1278 06C2 58 POP AX
1279 06C3 C3 RET
1280 06C4 CHECK_DMA ENDP
1281
1282 |-----|
1283 | SET UP ES:BX-> DISK PARMS |
1284 |-----|
1285 06C4 GET_VEC PROC NEAR
1286 06C4 2B C0 SUB AX,AX ; GET DISK PARAMETER ADDRESS
1287 06C6 8E C0 MOV ES,AX
1288 06C8 F6 C2 01 TEST DL,1
1289 06CB 74 07 JZ GV_0
1290 06CD 261 C4 IE 0118 R LES BX,#HF1_TBL_VEC ; ES:BX -> DRIVE PARAMETERS
1291 06D0 EB 05 JMP SHORT GV_EXIT
1292 06D4 GV_0: LES BX,#HF_TBL_VEC ; ES:BX -> DRIVE PARAMETERS
1293 06D4 GV_EXIT: RET
1294 06D9 GET_VEC ENDP
1295 06D9
1296 06D9 C3 RET
1297 06DA
1298
1299 |-----|
1300 | HARDWARE INT 76H -- ( IRQ LEVEL 14 ) |
1301 |-----|
1302 | FIXED DISK INTERRUPT ROUTINE |
1303 |-----|
1304
1305 06DA HD_INT PROC NEAR
1306 06DA 50 PUSH AX
1307 06DB 1E PUSH DS
1308 06DC EB 0000 E CALL DDS ; ALL DONE
1309 06DF C6 06 008E R FF MOV #HF_INT_FLAG,OFFH ; NON-SPECIFIC END OF INTERRUPT
1310 06E4 B0 20 MOV AL,E01 ; FOR CONTROLLER #2
1311 06E6 E6 A0 OUT INTB00,AL ; WAIT
1312 06E8 EB 00 JMP $+2 ; FOR CONTROLLER #1
1313 06EA E6 20 OUT INTA00,AL
1314 06EC 1F POP DS
1315 06ED FB STI ; RE-ENABLE INTERRUPTS
1316 06EE BB 9100 MOV AX,9100H ; DEVICE POST
1317 06F1 CD 15 INT 15H ; INTERRUPT
1318 06F3 58 POP AX
1319 06F4 CF IRET ; RETURN FROM INTERRUPT
1320 06F5 HD_INT ENDP
1321
1322 06F5 31 31 2F 31 35 2F DB '11/15/85' ; RELEASE MARKER
1323 38 35
1324 06FD CODE ENDS
1325 ENDP

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